

Package ‘tvd’

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Type Package

Title Total Variation Denoising

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Description Total Variation Denoising is a regularized denoising method which effectively removes noise from piecewise constant signals whilst preserving edges. This package contains a C++ implementation of Condat's very fast 1D squared error loss TVD algorithm. Additional methods and loss functions may be added in future versions.

License EPL (>= 1.0)

Depends R (>= 3.1.0)

Imports Rcpp (>= 0.11.2)

LinkingTo Rcpp

URL <https://bitbucket.org/marpin/r-tvd>

BugReports <https://bitbucket.org/marpin/r-tvd/issues>

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NeedsCompilation yes

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tvd-package

Total Variation Denoising

Description

Total Variation Denoising

Details

tvd is a package for Total Variation Denoising, a regularized procedure for removing noise from piecewise constant signals whilst retaining edges. Currently implements Condat's algorithm for fast 1D TVD, in function tvd1d.

Author(s)

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References

Condat, L. (2013) A Direct Algorithm for 1-D Total Variation Denoising. IEEE Signal Processing Letters 20(11): 1054-1057. doi:10.1109/LSP.2013.2278339

See Also

[tvd1d](#)

tvd1d

Perform Total Variation Denoising on a 1-Dimensional Signal

Description

When supplied a noisy sequential signal in vector y, performs TVD with regularization parameter lambda, and returns a denoised version of y.

Usage

```
tvd1d(y, lambda, method = "Condat")
```

Arguments

y	a numeric vector of sequential noisy data values
lambda	the total variation penalty coefficient
method	a string indicating the algorithm to use for denoising. Currently only supports method "Condat"

Details

1D TVD is a filtering technique for a sequential univariate signal that attempts to find a vector x_{tvd} that approximates a noisy vector y , as:

$$x_{tvd} = \operatorname{argmin}_x (E(x, y) + \lambda V(x))$$

where $E(x, y)$ is a loss function measuring the error in approximating y with x , and $V(x)$ is the total variation of x :

$$V(x) = \operatorname{sum}(|x_{i+1} - x_i|)$$

TVD is particularly well-suited to recovering piecewise constant signals. The degree of approximation is controlled by the parameter λ : for $\lambda = 0$, $x_{tvd} = y$, and as λ increases, x_{tvd} contains increasingly fewer value transitions, until, for a high enough value, it is constant.

Currently only implements Condat's fast squared-error loss TVD algorithm (method "Condat"), which is restricted to vectors of length $2^{32} - 1$ and shorter.

Value

a numeric vector of the same length as y , containing denoised data.

Author(s)

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References

Condat, L. (2013) A Direct Algorithm for 1-D Total Variation Denoising IEEE Signal Processing Letters 20(11): 1054-1057. doi:10.1109/LSP.2013.2278339

Examples

```
## Generate a stepped signal
x = rep(c(1, 2, 3, 4, 2, 4, 3, 2, 1), each = 100)

## Create a noisy version of the signal
y = x + rnorm(length(x), sd = 0.5)

## Denoise the signal by Condat's method
lines(x.denoised, col = "red", lwd = 1)
x.denoised = tvd1d(y, lambda = 10, method = "Condat")

## Plot the original signal, the noisy signal, and the denoised signal
plot(y, col = "black", pch = 19, cex = 0.3)
lines(x, col = "blue", lwd = 3)
lines(x.denoised, col = "red", lwd = 3)
legend("topleft", legend = c("Original", "Noisy", "Denoised"),
      col = c("blue", "black", "red"), lty = c("solid", "solid", "solid"),
      lwd = c(2, 0, 1), pch = c(NA, 19, NA), pt.cex = c(NA, 0.3, NA), inset = 0.05)
```

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