# Package 'rust'

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Type Package

Title Ratio-of-Uniforms Simulation with Transformation

Version 1.3.9

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Description Uses the generalized ratio-of-uniforms (RU) method to simulate from univariate and (low-dimensional) multivariate continuous distributions. The user specifies the log-density, up to an additive constant. The RU algorithm is applied after relocation of mode of the density to zero, and the user can choose a tuning parameter r. For details see Wakefield, Gelfand and Smith (1991) <DOI:10.1007/BF01889987>, Efficient generation of random variates via the ratio-of-uniforms method, Statistics and Computing (1991) 1, 129-133. A Box-Cox variable transformation can be used to make the input density suitable for the RU method and to improve efficiency. In the multivariate case rotation of axes can also be used to improve efficiency. From version 1.2.0 the 'Rcpp' package <a href="https://cran.r-project.org/package=Rcpp>">https://cran.r-project.org/package=Rcpp></a> can be used to improve efficiency.

**Imports** graphics, Rcpp (>= 0.12.10), stats

License GPL (>= 2)

LazyData TRUE

Encoding UTF-8

**Depends** R (>= 3.3.0)

RoxygenNote 7.1.0

**Suggests** bang, knitr, microbenchmark, revdbayes, rmarkdown, testthat **VignetteBuilder** knitr

URL https://paulnorthrop.github.io/rust/,

http://github.com/paulnorthrop/rust

BugReports http://github.com/paulnorthrop/rust/issues

LinkingTo Rcpp (>= 0.12.10), RcppArmadillo

NeedsCompilation yes

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create\_log\_j\_xptr Create external pointer to a C++ function for log\_j

# Description

Create external pointer to a C++ function for log\_j

# Usage

create\_log\_j\_xptr(fstr)

# Arguments

fstr A string indicating the C++ function required.

create\_phi\_to\_theta\_xptr

Create external pointer to a C++ function for phi\_to\_theta

#### Description

Create external pointer to a C++ function for phi\_to\_theta

#### Usage

```
create_phi_to_theta_xptr(fstr)
```

# Arguments

fstr A string indicating the C++ function required.

create\_xptr

*Create external pointer to a C++ function for logf* 

#### Description

Create external pointer to a C++ function for logf

# Usage

create\_xptr(fstr)

# Arguments

fstr A string indicating the C++ function required.

find\_lambda

Selecting Box-Cox parameter lambda for general d.

# Description

Finds a value of the Box-Cox transformation parameter lambda for which the (positive) random variable with log-density logf has a density closer to that of a Gaussian random variable. In the following we use theta to denote the argument of logf on the original scale and phi on the Box-Cox transformed scale.

# Usage

```
find_lambda(
  logf,
  ...,
  d = 1,
  n_grid = NULL,
  ep_bc = 1e-04,
  min_phi = rep(ep_bc, d),
  max_phi = rep(10, d),
  which_lam = 1:d,
  lambda_range = c(-3, 3),
  init_lambda = NULL,
  phi_to_theta = NULL,
  log_j = NULL
)
```

# Arguments

logf	A function returning the log of the target density f.
	further arguments to be passed to logf and related functions.
d	A numeric scalar. Dimension of f.
n_grid	A numeric scalar. Number of ordinates for each variable in phi. If this is not supplied a default value of $ceiling(2501 (1/d))$ is used.
ep_bc	A (positive) numeric scalar. Smallest possible value of phi to consider. Used to avoid negative values of phi.
<pre>min_phi, max_ph</pre>	i
	Numeric vectors. Smallest and largest values of phi at which to evaluate logf, i.e. the range of values of phi over which to evaluate logf. Any components in min_phi that are not positive are set to ep_bc.
which_lam	A numeric vector. Contains the indices of the components of phi that ARE to be Box-Cox transformed.
lambda_range	A numeric vector of length 2. Range of lambda over which to optimise.
init_lambda	A numeric vector of length 1 or d. Initial value of lambda used in the search for the best lambda. If init_lambda is a scalar then rep(init_lambda,d) is used.
phi_to_theta	A function returning (inverse) of the transformation from theta to phi used to ensure positivity of phi prior to Box-Cox transformation. The argument is phi and the returned value is theta.
log_j	A function returning the log of the Jacobian of the transformation from theta to phi, i.e. based on derivatives of phi with respect to theta. Takes theta as its argument.

# Details

The general idea is to evaluate the density f on a d-dimensional grid, with n\_grid ordinates for each of the d variables. We treat each combination of the variables in the grid as a data point and

# find\_lambda

perform an estimation of the Box-Cox transformation parameter lambda, in which each data point is weighted by the density at that point. The vectors min\_phi and max\_phi define the limits of the grid and which\_lam can be used to specify that only certain components of phi are to be transformed.

#### Value

A list containing the following components

lambda	A numeric vector. The value of lambda.
gm	A numeric vector. Box-cox scaling parameter, estimated by the geometric mean of the values of phi used in the optimisation to find the value of lambda, weighted by the values of f evaluated at phi.
init_psi	A numeric vector. An initial estimate of the mode of the Box-Cox transformed density
sd_psi	A numeric vector. Estimates of the marginal standard deviations of the Box-Cox transformed variables.
phi_to_theta	as detailed above (only if phi_to_theta is supplied)
log_j	as detailed above (only if log_j is supplied)

# References

Box, G. and Cox, D. R. (1964) An Analysis of Transformations. Journal of the Royal Statistical Society. Series B (Methodological), 26(2), 211-252.

Andrews, D. F. and Gnanadesikan, R. and Warner, J. L. (1971) Transformations of Multivariate Data, Biometrics, 27(4).

#### See Also

ru and ru\_rcpp to perform ratio-of-uniforms sampling.

find\_lambda\_one\_d and find\_lambda\_one\_d\_rcpp to produce (somewhat) automatically a list for the argument lambda of ru/ru\_rcpp for the d = 1 case.

find\_lambda\_rcpp for a version of find\_lambda that uses the Rcpp package to improve efficiency.

#### Examples

```
# In practice the value of lambda chosen is quite insensitive to the choice
# of max_phi, provided that max_phi is not far too large or far too small.]
lambda <- find_lambda(logf = dgamma, shape = alpha, log = TRUE,</pre>
                      max_phi = max_phi)
lambda
x \leq ru(\log f = dgamma, shape = alpha, log = TRUE, d = 1, n = 1000,
        trans = "BC", lambda = lambda)
# Generalized Pareto posterior distribution =================================<</pre>
# Sample data from a GP(sigma, xi) distribution
gpd_data <- rgpd(m = 100, xi = -0.5, sigma = 1)</pre>
# Calculate summary statistics for use in the log-likelihood
ss <- gpd_sum_stats(gpd_data)</pre>
# Calculate an initial estimate
init <- c(mean(gpd_data), 0)</pre>
n <- 1000
# Sample on original scale, with no rotation ------
x1 <- ru(logf = gpd_logpost, ss = ss, d = 2, n = n, init = init,</pre>
 lower = c(0, -Inf), rotate = FALSE)
plot(x1, xlab = "sigma", ylab = "xi")
# Parameter constraint line xi > -sigma/max(data)
# [This may not appear if the sample is far from the constraint.]
abline(a = 0, b = -1 / ss$xm)
summary(x1)
# Sample on original scale, with rotation ------
x2 <- ru(logf = gpd_logpost, ss = ss, d = 2, n = n, init = init,</pre>
 lower = c(0, -Inf))
plot(x2, xlab = "sigma", ylab = "xi")
abline(a = 0, b = -1 / ss$xm)
summary(x2)
# Sample on Box-Cox transformed scale ------
# Find initial estimates for phi = (phi1, phi2),
# where phi1 = sigma
# and phi2 = xi + sigma / max(x),
# and ranges of phi1 and phi2 over over which to evaluate
# the posterior to find a suitable value of lambda.
temp <- do.call(gpd_init, ss)</pre>
min_phi <- pmax(0, temp$init_phi - 2 * temp$se_phi)</pre>
max_phi <- pmax(0, temp$init_phi + 2 * temp$se_phi)</pre>
# Set phi_to_theta() that ensures positivity of phi
# We use phi1 = sigma and phi2 = xi + sigma / max(data)
phi_to_theta <- function(phi) c(phi[1], phi[2] - phi[1] / ss$xm)</pre>
log_j <- function(x) 0</pre>
lambda <- find_lambda(logf = gpd_logpost, ss = ss, d = 2, min_phi = min_phi,</pre>
```

```
max_phi = max_phi, phi_to_theta = phi_to_theta, log_j = log_j)
lambda
# Sample on Box-Cox transformed, without rotation
x3 <- ru(logf = gpd_logpost, ss = ss, d = 2, n = n, trans = "BC",
 lambda = lambda, rotate = FALSE)
plot(x3, xlab = "sigma", ylab = "xi")
abline(a = 0, b = -1 / ss$xm)
summary(x3)
# Sample on Box-Cox transformed, with rotation
x4 <- ru(logf = gpd_logpost, ss = ss, d = 2, n = n, trans = "BC",
 lambda = lambda)
plot(x4, xlab = "sigma", ylab = "xi")
abline(a = 0, b = -1 / ss$xm)
summary(x4)
def_par <- graphics::par(no.readonly = TRUE)</pre>
par(mfrow = c(2,2), mar = c(4, 4, 1.5, 1))
plot(x1, xlab = "sigma", ylab = "xi", ru_scale = TRUE,
 main = "mode relocation")
plot(x2, xlab = "sigma", ylab = "xi", ru_scale = TRUE,
 main = "mode relocation and rotation")
plot(x3, xlab = "sigma", ylab = "xi", ru_scale = TRUE,
 main = "Box-Cox and mode relocation")
plot(x4, xlab = "sigma", ylab = "xi", ru_scale = TRUE,
 main = "Box-Cox, mode relocation and rotation")
graphics::par(def_par)
```

find\_lambda\_one\_d Selecting Box-Cox parameter lambda in the one-dimensional case

#### Description

Finds a value of the Box-Cox transformation parameter lambda for which the (positive univariate) random variable with log-density logf has a density closer to that of a Gaussian random variable. Works by estimating a set of quantiles of the distribution implied by logf and treating those quantiles as data in a standard Box-Cox analysis. In the following we use theta to denote the argument of logf on the original scale and phi on the Box-Cox transformed scale.

#### Usage

```
find_lambda_one_d(
    logf,
    ...,
    ep_bc = 1e-04,
    min_phi = ep_bc,
    max_phi = 10,
```

```
num = 1001,
xdiv = 100,
probs = seq(0.01, 0.99, by = 0.01),
lambda_range = c(-3, 3),
phi_to_theta = NULL,
log_j = NULL
```

# Arguments

logf	A function returning the log of the target density f.
	further arguments to be passed to logf and related functions.
ep_bc	A (positive) numeric scalar. Smallest possible value of phi to consider. Used to avoid negative values of phi.
<pre>min_phi, max_phi</pre>	i
	Numeric scalars. Smallest and largest values of phi at which to evaluate logf, i.e. the range of values of phi over which to evaluate logf. Any components in min_phi that are not positive are set to ep_bc.
num	A numeric scalar. Number of values at which to evaluate logf.
xdiv	A numeric scalar. Only values of phi at which the density f is greater than the (maximum of f) / xdiv are used.
probs	A numeric scalar. Probabilities at which to estimate the quantiles of that will be used as data to find lambda.
lambda_range	A numeric vector of length 2. Range of lambda over which to optimise.
phi_to_theta	A function returning (inverse) of the transformation from theta to phi used to ensure positivity of phi prior to Box-Cox transformation. The argument is phi and the returned value is theta.
log_j	A function returning the log of the Jacobian of the transformation from theta to phi, i.e. based on derivatives of phi with respect to theta. Takes theta as its argument. If this is not supplied then a constant Jacobian is used.

#### Details

The general idea is to estimate quantiles of f corresponding to a set of equally-spaced probabilities in probs and to use these estimated quantiles as data in a standard estimation of the Box-Cox transformation parameter lambda.

The density f is first evaluated at num points equally spaced over the interval (min\_phi, max\_phi). The continuous density f is approximated by attaching trapezium-rule estimates of probabilities to the midpoints of the intervals between the points. After standardizing to account for the fact that f may not be normalized, (min\_phi, max\_phi) is reset so that values with small estimated probability (determined by xdiv) are excluded and the procedure is repeated on this new range. Then the required quantiles are estimated by inferring them from a weighted empirical distribution function based on treating the midpoints as data and the estimated probabilities at the midpoints as weights.

#### Value

A list containing the following components

lambda	A numeric scalar. The value of lambda.
gm	A numeric scalar. Box-cox scaling parameter, estimated by the geometric mean of the quantiles used in the optimisation to find the value of lambda.
init_psi	A numeric scalar. An initial estimate of the mode of the Box-Cox transformed density
sd_psi	A numeric scalar. Estimates of the marginal standard deviations of the Box-Cox transformed variables.
phi_to_theta	as detailed above (only if phi_to_theta is supplied)
log_j	as detailed above (only if log_j is supplied)

# References

Box, G. and Cox, D. R. (1964) An Analysis of Transformations. Journal of the Royal Statistical Society. Series B (Methodological), 26(2), 211-252.

Andrews, D. F. and Gnanadesikan, R. and Warner, J. L. (1971) Transformations of Multivariate Data, Biometrics, 27(4).

#### See Also

ru and ru\_rcpp to perform ratio-of-uniforms sampling.

find\_lambda and find\_lambda\_rcpp to produce (somewhat) automatically a list for the argument lambda of ru/ru\_rcpp for any value of d.

find\_lambda\_one\_d\_rcpp for a version of find\_lambda\_one\_d that uses the Rcpp package to improve efficiency.

# Examples

```
lambda <- find_lambda_one_d(logf = dgamma, shape = alpha, log = TRUE,</pre>
                             max_phi = max_phi)
lambda
x <- ru(logf = dgamma, shape = alpha, log = TRUE, d = 1, n = 1000,
        trans = "BC", lambda = lambda)
alpha <- 0.1
# NB. for alpha < 1 the gamma(alpha, beta) density is not bounded</pre>
# So the ratio-of-uniforms emthod can't be used but it may work after a
# Box-Cox transformation.
# find_lambda_one_d() works much better than find_lambda() here.
max_phi <- qgamma(0.999, shape = alpha)</pre>
lambda <- find_lambda_one_d(logf = dgamma, shape = alpha, log = TRUE,</pre>
                             max_phi = max_phi)
lambda
x <- ru(logf = dgamma, shape = alpha, log = TRUE, d = 1, n = 1000,</pre>
        trans = "BC", lambda = lambda)
plot(x)
plot(x, ru_scale = TRUE)
```

```
find_lambda_one_d_rcpp
```

Selecting Box-Cox parameter lambda in the one-dimensional case using C++ via Rcpp

#### Description

Finds a value of the Box-Cox transformation parameter lambda for which the (positive univariate) random variable with log-density logf has a density closer to that of a Gaussian random variable. Works by estimating a set of quantiles of the distribution implied by logf and treating those quantiles as data in a standard Box-Cox analysis. In the following we use theta to denote the argument of logf on the original scale and phi on the Box-Cox transformed scale.

# Usage

```
find_lambda_one_d_rcpp(
    logf,
    ...,
    ep_bc = 1e-04,
    min_phi = ep_bc,
    max_phi = 10,
    num = 1001L,
    xdiv = 100,
    probs = seq(0.01, 0.99, by = 0.01),
```

```
lambda_range = c(-3, 3),
phi_to_theta = NULL,
log_j = NULL,
user_args = list()
```

# Arguments

)

logf	A pointer to a compiled C++ function returning the log of the target density $f$ .
	further arguments to be passed to logf and related functions.
ep_bc	A (positive) numeric scalar. Smallest possible value of phi to consider. Used to avoid negative values of phi.
min_phi, max_ph	i
	Numeric scalars. Smallest and largest values of phi at which to evaluate logf, i.e. the range of values of phi over which to evaluate logf. Any components in min_phi that are not positive are set to ep_bc.
num	A numeric scalar. Number of values at which to evaluate logf.
xdiv	A numeric scalar. Only values of phi at which the density f is greater than the (maximum of f) / xdiv are used.
probs	A numeric scalar. Probabilities at which to estimate the quantiles of that will be used as data to find lambda.
lambda_range	A numeric vector of length 2. Range of lambda over which to optimise.
phi_to_theta	A pointer to a compiled C++ function returning (the inverse) of the transforma- tion from theta to phi used to ensure positivity of phi prior to Box-Cox transfor- mation. The argument is phi and the returned value is theta. If phi_to_theta is undefined at the input value then the function should return NA.
log_j	A pointer to a compiled C++ function returning the log of the Jacobian of the transformation from theta to phi, i.e. based on derivatives of phi with respect to theta. Takes theta as its argument. If this is not supplied then a constant Jacobian is used.
user_args	A list of numeric components providing arguments to the user-supplied func- tions phi_to_theta and log_j.

# Details

The general idea is to estimate quantiles of f corresponding to a set of equally-spaced probabilities in probs and to use these estimated quantiles as data in a standard estimation of the Box-Cox transformation parameter lambda.

The density f is first evaluated at num points equally spaced over the interval (min\_phi, max\_phi). The continuous density f is approximated by attaching trapezium-rule estimates of probabilities to the midpoints of the intervals between the points. After standardizing to account for the fact that f may not be normalized, (min\_phi, max\_phi) is reset so that values with small estimated probability (determined by xdiv) are excluded and the procedure is repeated on this new range. Then the required quantiles are estimated by inferring them from a weighted empirical distribution function based on treating the midpoints as data and the estimated probabilities at the midpoints as weights.

# Value

A list containing the following components

lambda	A numeric scalar. The value of lambda.
gm	A numeric scalar. Box-cox scaling parameter, estimated by the geometric mean of the quantiles used in the optimisation to find the value of lambda.
init_psi	A numeric scalar. An initial estimate of the mode of the Box-Cox transformed density
sd_psi	A numeric scalar. Estimates of the marginal standard deviations of the Box-Cox transformed variables.
phi_to_theta	as detailed above (only if phi_to_theta is supplied)
log_j	as detailed above (only if log_j is supplied)
user_args	as detailed above (only if user_args is supplied)

# References

Box, G. and Cox, D. R. (1964) An Analysis of Transformations. Journal of the Royal Statistical Society. Series B (Methodological), 26(2), 211-252.

Andrews, D. F. and Gnanadesikan, R. and Warner, J. L. (1971) Transformations of Multivariate Data, Biometrics, 27(4).

Eddelbuettel, D. and Francois, R. (2011). Rcpp: Seamless R and C++ Integration. *Journal of Statistical Software*, **40**(8), 1-18. http://www.jstatsoft.org/v40/i08/.

Eddelbuettel, D. (2013). Seamless R and C++ Integration with Rcpp, Springer, New York. ISBN 978-1-4614-6867-7.

# See Also

ru\_rcpp to perform ratio-of-uniforms sampling.

find\_lambda\_rcpp to produce (somewhat) automatically a list for the argument lambda of ru for any value of d.

# Examples

```
# Note: the default value of max_phi = 10 is OK here but this will not
# always be the case.
ptr_lnorm <- create_xptr("logdlnorm")
mu <- 0
sigma <- 1
lambda <- find_lambda_one_d_rcpp(logf = ptr_lnorm, mu = mu, sigma = sigma)
lambda
x <- ru_rcpp(logf = ptr_lnorm, mu = mu, sigma = sigma, log = TRUE, d = 1,</pre>
```

```
n = 1000, trans = "BC", lambda = lambda)
```

```
alpha <- 1
# Choose a sensible value of max_phi
max_phi <- qgamma(0.999, shape = alpha)</pre>
# [I appreciate that typically the quantile function won't be available.
# In practice the value of lambda chosen is quite insensitive to the choice
# of max_phi, provided that max_phi is not far too large or far too small.]
ptr_gam <- create_xptr("logdgamma")</pre>
lambda <- find_lambda_one_d_rcpp(logf = ptr_gam, alpha = alpha,</pre>
                                 max_phi = max_phi)
lambda
x <- ru_rcpp(logf = ptr_gam, alpha = alpha, d = 1, n = 1000, trans = "BC",
             lambda = lambda)
alpha <- 0.1
# NB. for alpha < 1 the gamma(alpha, beta) density is not bounded</pre>
# So the ratio-of-uniforms emthod can't be used but it may work after a
# Box-Cox transformation.
# find_lambda_one_d() works much better than find_lambda() here.
max_phi <- qgamma(0.999, shape = alpha)</pre>
lambda <- find_lambda_one_d_rcpp(logf = ptr_gam, alpha = alpha,</pre>
                                 max_phi = max_phi)
lambda
x <- ru_rcpp(logf = ptr_gam, alpha = alpha, d = 1, n = 1000, trans = "BC",</pre>
             lambda = lambda)
plot(x)
plot(x, ru_scale = TRUE)
```

find\_lambda\_rcpp Selecting Box-Cox parameter lambda for general d using C++ via Rcpp.

# Description

Finds a value of the Box-Cox transformation parameter lambda for which the (positive) random variable with log-density logf has a density closer to that of a Gaussian random variable. In the following we use theta to denote the argument of logf on the original scale and phi on the Box-Cox transformed scale.

#### Usage

```
find_lambda_rcpp(
   logf,
   ...,
   d = 1,
```

```
n_grid = NULL,
ep_bc = 1e-04,
min_phi = rep(ep_bc, d),
max_phi = rep(10, d),
which_lam = 1:d,
lambda_range = c(-3, 3),
init_lambda = NULL,
phi_to_theta = NULL,
log_j = NULL,
user_args = list()
)
```

# Arguments

logf	A pointer to a compiled C++ function returning the log of the target density $f$ .
	further arguments to be passed to logf and related functions.
d	A numeric scalar. Dimension of f.
n_grid	A numeric scalar. Number of ordinates for each variable in phi. If this is not supplied a default value of ceiling( $2501 (1 / d)$ ) is used.
ep_bc	A (positive) numeric scalar. Smallest possible value of phi to consider. Used to avoid negative values of phi.
min_phi, max_ph	
	Numeric vectors. Smallest and largest values of phi at which to evaluate logf, i.e. the range of values of phi over which to evaluate logf. Any components in min_phi that are not positive are set to ep_bc.
which_lam	A numeric vector. Contains the indices of the components of phi that ARE to be Box-Cox transformed.
lambda_range	A numeric vector of length 2. Range of lambda over which to optimise.
init_lambda	A numeric vector of length 1 or d. Initial value of lambda used in the search for the best lambda. If init_lambda is a scalar then rep(init_lambda,d) is used.
phi_to_theta	A pointer to a compiled C++ function returning (the inverse) of the transforma- tion from theta to phi used to ensure positivity of phi prior to Box-Cox transfor- mation. The argument is phi and the returned value is theta. If phi_to_theta is undefined at the input value then the function should return NA.
log_j	A pointer to a compiled C++ function returning the log of the Jacobian of the transformation from theta to phi, i.e. based on derivatives of phi with respect to theta. Takes theta as its argument.
user_args	A list of numeric components providing arguments to the user-supplied func- tions phi_to_theta and log_j.

# Details

The general idea is to evaluate the density f on a d-dimensional grid, with n\_grid ordinates for each of the d variables. We treat each combination of the variables in the grid as a data point and perform an estimation of the Box-Cox transformation parameter lambda, in which each data point is weighted by the density at that point. The vectors min\_phi and max\_phi define the limits of the grid and which\_lam can be used to specify that only certain components of phi are to be transformed.

#### Value

A list containing the following components

lambda	A numeric vector. The value of lambda.
gm	A numeric vector. Box-cox scaling parameter, estimated by the geometric mean of the values of phi used in the optimisation to find the value of lambda, weighted by the values of f evaluated at phi.
init_psi	A numeric vector. An initial estimate of the mode of the Box-Cox transformed density
sd_psi	A numeric vector. Estimates of the marginal standard deviations of the Box-Cox transformed variables.
phi_to_theta	as detailed above (only if phi_to_theta is supplied)
log_j	as detailed above (only if log_j is supplied)
user_args	as detailed above (only if user_args is supplied)

#### References

Box, G. and Cox, D. R. (1964) An Analysis of Transformations. Journal of the Royal Statistical Society. Series B (Methodological), 26(2), 211-252.

Andrews, D. F. and Gnanadesikan, R. and Warner, J. L. (1971) Transformations of Multivariate Data, Biometrics, 27(4).

Eddelbuettel, D. and Francois, R. (2011). Rcpp: Seamless R and C++ Integration. *Journal of Statistical Software*, **40**(8), 1-18. http://www.jstatsoft.org/v40/i08/.

Eddelbuettel, D. (2013). Seamless R and C++ Integration with Rcpp, Springer, New York. ISBN 978-1-4614-6867-7.

# See Also

ru\_rcpp to perform ratio-of-uniforms sampling.

find\_lambda\_one\_d\_rcpp to produce (somewhat) automatically a list for the argument lambda of ru for the d = 1 case.

# Examples

```
alpha <- 1
# Choose a sensible value of max_phi
max_phi <- qgamma(0.999, shape = alpha)</pre>
# [Of course, typically the quantile function won't be available. However,
# In practice the value of lambda chosen is quite insensitive to the choice
# of max_phi, provided that max_phi is not far too large or far too small.]
ptr_gam <- create_xptr("logdgamma")</pre>
lambda <- find_lambda_rcpp(logf = ptr_gam, alpha = alpha, max_phi = max_phi)</pre>
lambda
x <- ru_rcpp(logf = ptr_gam, alpha = alpha, d = 1, n = 1000, trans = "BC",</pre>
             lambda = lambda)
n <- 1000
# Sample data from a GP(sigma, xi) distribution
gpd_data <- rgpd(m = 100, xi = -0.5, sigma = 1)</pre>
# Calculate summary statistics for use in the log-likelihood
ss <- gpd_sum_stats(gpd_data)</pre>
# Calculate an initial estimate
init <- c(mean(gpd_data), 0)</pre>
n <- 1000
# Sample on original scale, with no rotation ------
ptr_gp <- create_xptr("loggp")</pre>
for_ru_rcpp <- c(list(logf = ptr_gp, init = init, d = 2, n = n,</pre>
                    lower = c(0, -Inf)), ss, rotate = FALSE)
x1 <- do.call(ru_rcpp, for_ru_rcpp)</pre>
plot(x1, xlab = "sigma", ylab = "xi")
# Parameter constraint line xi > -sigma/max(data)
# [This may not appear if the sample is far from the constraint.]
abline(a = 0, b = -1 / ss$xm)
summary(x1)
# Sample on original scale, with rotation ------
for_ru_rcpp <- c(list(logf = ptr_gp, init = init, d = 2, n = n,</pre>
                      lower = c(0, -Inf), ss)
x2 <- do.call(ru_rcpp, for_ru_rcpp)</pre>
plot(x2, xlab = "sigma", ylab = "xi")
abline(a = 0, b = -1 / ss$xm)
summary(x2)
# Sample on Box-Cox transformed scale ------
# Find initial estimates for phi = (phi1, phi2),
# where phi1 = sigma
   and phi2 = xi + sigma / max(x),
#
# and ranges of phi1 and phi2 over over which to evaluate
# the posterior to find a suitable value of lambda.
temp <- do.call(gpd_init, ss)</pre>
min_phi <- pmax(0, temp$init_phi - 2 * temp$se_phi)</pre>
```

#### gpd\_init

```
max_phi <- pmax(0, temp$init_phi + 2 * temp$se_phi)</pre>
# Set phi_to_theta() that ensures positivity of phi
# We use phi1 = sigma and phi2 = xi + sigma / max(data)
# Create an external pointer to this C++ function
ptr_phi_to_theta_gp <- create_phi_to_theta_xptr("gp")</pre>
# Note: log_j is set to zero by default inside find_lambda_rcpp()
lambda <- find_lambda_rcpp(logf = ptr_gp, ss = ss, d = 2, min_phi = min_phi,</pre>
                           max_phi = max_phi, user_args = list(xm = ss$xm),
                           phi_to_theta = ptr_phi_to_theta_gp)
lambda
# Sample on Box-Cox transformed, without rotation
x3 <- ru_rcpp(logf = ptr_gp, ss = ss, d = 2, n = n, trans = "BC",
              lambda = lambda, rotate = FALSE)
plot(x3, xlab = "sigma", ylab = "xi")
abline(a = 0, b = -1 / ss$xm)
summary(x3)
# Sample on Box-Cox transformed, with rotation
x4 <- ru_rcpp(logf = ptr_gp, ss = ss, d = 2, n = n, trans = "BC",
              lambda = lambda)
plot(x4, xlab = "sigma", ylab = "xi")
abline(a = 0, b = -1 / ss$xm)
summary(x4)
def_par <- graphics::par(no.readonly = TRUE)</pre>
par(mfrow = c(2,2), mar = c(4, 4, 1.5, 1))
plot(x1, xlab = "sigma", ylab = "xi", ru_scale = TRUE,
 main = "mode relocation")
plot(x2, xlab = "sigma", ylab = "xi", ru_scale = TRUE,
 main = "mode relocation and rotation")
plot(x3, xlab = "sigma", ylab = "xi", ru_scale = TRUE,
 main = "Box-Cox and mode relocation")
plot(x4, xlab = "sigma", ylab = "xi", ru_scale = TRUE,
 main = "Box-Cox, mode relocation and rotation")
graphics::par(def_par)
```

gpd\_init

Initial estimates for Generalized Pareto parameters

#### Description

Calculates initial estimates and estimated standard errors (SEs) for the generalized Pareto parameters sigma and xi based on an assumed random sample from this distribution. Also, calculates initial estimates and estimated standard errors for phi1 = sigma and phi2 = xi + sigma / xm.

#### Usage

gpd\_init(gpd\_data, m, xm, sum\_gp = NULL, xi\_eq\_zero = FALSE, init\_ests = NULL)

# Arguments

gpd_data	A numeric vector containing positive sample values.
m	A numeric scalar. The sample size, i.e. the length of gpd_data.
xm	A numeric scalar. The sample maximum.
sum_gp	A numeric scalar. The sum of the sample values.
xi_eq_zero	A logical scalar. If TRUE assume that the shape parameter $xi = 0$ .
init_ests	A numeric vector. Initial estimate of theta = (sigma, xi). If supplied gpd_init() just returns the corresponding initial estimate of phi = (phi1, phi2).

#### Details

The main aim is to calculate an admissible estimate of theta, i.e. one at which the log-likelihood is finite (necessary for the posterior log-density to be finite) at the estimate, and associated estimated SEs. These are converted into estimates and SEs for phi. The latter can be used to set values of min\_phi and max\_phi for input to find\_lambda.

In the default setting (xi\_eq\_zero = FALSE and init\_ests = NULL) the methods tried are Maximum Likelihood Estimation (MLE) (Grimshaw, 1993), Probability-Weighted Moments (PWM) (Hosking and Wallis, 1987) and Linear Combinations of Ratios of Spacings (LRS) (Reiss and Thomas, 2007, page 134) in that order.

For xi < -1 the likelihood is unbounded, MLE may fail when xi is not greater than -0.5 and the observed Fisher information for (sigma, xi) has finite variance only if xi > -0.25. We use the ML estimate provided that the estimate of xi returned from  $gpd_mle$  is greater than -1. We only use the SE if the MLE of xi is greater than -0.25.

If either the MLE or the SE are not OK then we try PWM. We use the PWM estimate only if is admissible, and the MLE was not OK. We use the PWM SE, but this will be c(NA, NA) is the PWM estimate of xi is > 1/2. If the estimate is still not OK then we try LRS. As a last resort, which will tend to occur only when xi is strongly negative, we set xi = -1 and estimate sigma conditional on this.

#### Value

If init\_ests is not supplied by the user, a list is returned with components

init	A numeric vector. Initial estimates of sigma and xi.
se	A numeric vector. Estimated standard errors of sigma and xi.
init_phi	A numeric vector. Initial estimates of $phi1 = sigma$ and $phi2 = xi + sigma / xm$ , where xm is the maximum of gpd_data.
se_phi	A numeric vector. Estimated standard errors of phi1 and phi2.

If init\_ests is supplied then only the numeric vector init\_phi is returned.

#### gpd\_logpost

#### References

Grimshaw, S. D. (1993) Computing Maximum Likelihood Estimates for the Generalized Pareto Distribution. Technometrics, 35(2), 185-191. and Computing (1991) 1, 129-133. http://dx.doi.org/10.1007/BF01889987.

Hosking, J. R. M. and Wallis, J. R. (1987) Parameter and Quantile Estimation for the Generalized Pareto Distribution. Technometrics, 29(3), 339-349. http://dx.doi.org/10.2307/1269343.

Reiss, R.-D., Thomas, M. (2007) Statistical Analysis of Extreme Values with Applications to Insurance, Finance, Hydrology and Other Fields.Birkhauser. http://dx.doi.org/10.1007/978-3-7643-7399-3.

#### See Also

gpd\_sum\_stats to calculate summary statistics for use in gpd\_loglik.

rgpd for simulation from a generalized Pareto

find\_lambda to produce (somewhat) automatically a list for the argument lambda of ru.

#### Examples

```
# Sample data from a GP(sigma, xi) distribution
gpd_data <- rgpd(m = 100, xi = 0, sigma = 1)
# Calculate summary statistics for use in the log-likelihood
ss <- gpd_sum_stats(gpd_data)
# Calculate initial estimates
do.call(gpd_init, ss)</pre>
```

gpd\_logpost

Generalized Pareto posterior log-density

#### Description

Calculates the generalized Pareto posterior log-density based on a particular prior for the generalized Pareto parameters, a Maximal Data Information (MDI) prior truncated to  $xi \ge -1$  in order to produce a posterior density that is proper.

#### Usage

gpd\_logpost(pars, ss)

#### Arguments

pars	A numeric vector containing the values of the generalized Pareto parameters sigma and xi.
SS	A numeric list. Summary statistics to be passed to the generalized Pareto log- likelihood. Calculated using gpd_sum_stats

- -

A numeric scalar. The value of the log-likelihood.

#### References

Northrop, P. J. and Attalides, N. (2016) Posterior propriety in Bayesian extreme value analyses using reference priors. Statistica Sinica, 26(2), 721-743, http://dx.doi.org/10.5705/ss.2014.034.

#### See Also

gpd\_sum\_stats to calculate summary statistics for use in gpd\_loglik.

rgpd for simulation from a generalized Pareto

# Examples

```
# Sample data from a GP(sigma, xi) distribution
gpd_data <- rgpd(m = 100, xi = 0, sigma = 1)
# Calculate summary statistics for use in the log-likelihood
ss <- gpd_sum_stats(gpd_data)
# Calculate the generalized Pareto log-posterior
gpd_logpost(pars = c(1, 0), ss = ss)</pre>
```

gpd\_sum\_stats Generalized Pareto summary statistics

# Description

Calculates summary statistics involved in the Generalized Pareto log-likelihood.

#### Usage

```
gpd_sum_stats(gpd_data)
```

#### Arguments

```
gpd_data A numeric vector containing positive values.
```

# Value

A list with components

gpd_data	A numeric vector. The input vector with any missings removed.
m	A numeric scalar. The sample size, i.e. the number of non-missing values.
xm	A numeric scalar. The sample maximum
sum_gp	A numeric scalar. The sum of the non-missing sample values.

# plot.ru

# See Also

rgpd for simulation from a generalized Pareto distribution.

# Examples

```
# Sample data from a GP(sigma, xi) distribution
gpd_data <- rgpd(m = 100, xi = 0, sigma = 1)
# Calculate summary statistics for use in the log-likelihood
ss <- gpd_sum_stats(gpd_data)</pre>
```

plot.ru

Plot diagnostics for an ru object

# Description

plot method for class "ru". For d = 1 a histogram of the simulated values is plotted with a the density function superimposed. The density is normalized crudely using the trapezium rule. For d = 2 a scatter plot of the simulated values is produced with density contours superimposed. For d > 2 pairwise plots of the simulated values are produced.

#### Usage

```
## S3 method for class 'ru'
plot(
    x,
    y,
    ...,
    n = ifelse(x$d == 1, 1001, 101),
    prob = c(0.1, 0.25, 0.5, 0.75, 0.95, 0.99),
    ru_scale = FALSE,
    rows = NULL,
    xlabs = NULL,
    ylabs = NULL,
    points_par = list(col = 8)
)
```

#### Arguments

х	an object of class "ru", a result of a call to ru.
У	Not used.
	Additional arguments passed on to hist, lines, contour or points.
n	A numeric scalar. Only relevant if $x$ = 1 or $x$ = 2. The meaning depends on the value of $x$ = 0.

	• For d = 1 : n + 1 is the number of abscissae in the trapezium method used to normalize the density.
	• For d = 2 : an n by n regular grid is used to contour the density.
prob	Numeric vector. Only relevant for $d = 2$ . The contour lines are drawn such that the respective probabilities that the variable lies within the contour are approximately prob.
ru_scale	A logical scalar. Should we plot data and density on the scale used in the ratio- of-uniforms algorithm (TRUE) or on the original scale (FALSE)?
rows	A numeric scalar. When $d > 2$ this sets the number of rows of plots. If the user doesn't provide this then it is set internally.
xlabs, ylabs	Numeric vectors. When $d > 2$ these set the labels on the x and y axes respectively. If the user doesn't provide these then the column names of the simulated data matrix to be plotted are used.
points_par	A list of arguments to pass to points to control the appearance of points depict- ing the simulated values. Only relevant when d = 2.

# See Also

summary.ru for summaries of the simulated values and properties of the ratio-of-uniforms algorithm.

#### Examples

# Log-normal density -----x <- ru(logf = dlnorm, log = TRUE, d = 1, n = 1000, lower = 0, init = 1)</pre>

#### plot(x)

```
# Improve appearance using arguments to plot() and hist()
```

```
# Two-dimensional normal with positive association ------
rho <- 0.9
covmat <- matrix(c(1, rho, rho, 1), 2, 2)
log_dmvnorm <- function(x, mean = rep(0, d), sigma = diag(d)) {
    x <- matrix(x, ncol = length(x))
    d <- ncol(x)
    - 0.5 * (x - mean) %*% solve(sigma) %*% t(x - mean)
}
x <- ru(logf = log_dmvnorm, sigma = covmat, d = 2, n = 1000, init = c(0, 0))</pre>
```

```
plot(x)
```

print.ru

# Description

print method for class "ru".

# Usage

## S3 method for class 'ru'
print(x, ...)

# Arguments

х	an object of class "ru", a result of a call to ru or ru_rcpp.
	Additional arguments. None are used in this function.

# Details

Simply prints the call to ru or ru\_rcpp.

# Value

The argument x, invisibly, as for all print methods.

#### See Also

summary.ru for summaries of the simulated values and properties of the ratio-of-uniforms algorithm.

plot.ru for a diagnostic plot.

print.summary.ru Print method for objects of class "summary.ru"

# Description

print method for an object object of class "summary.ru".

# Usage

```
## S3 method for class 'summary.ru'
print(x, ...)
```

#### Arguments

х	an object of class "summary.ru", a result of a call to summary.ru.
	Additional optional arguments to be passed to print.

# Value

Prints

- a summary of the simulated values, via summary(object\$sim\_vals)
- an estimate of the probability of acceptance, i.e. object\$pa
- information about the ratio-of-uniforms bounding box, i.e. object\$box

#### See Also

summary.ru for summaries of the simulated values and properties of the ratio-of-uniforms algorithm.

plot.ru for a diagnostic plot.

ru for descriptions of object\$sim\_vals and object\$box.

#### Examples

```
# one-dimensional standard normal ------
x <- ru(logf = function(x) -x ^ 2 / 2, d = 1, n = 1000, init = 0)
summary(x)
# two-dimensional normal with positive association ------
rho <- 0.9
covmat <- matrix(c(1, rho, rho, 1), 2, 2)
log_dmvnorm <- function(x, mean = rep(0, d), sigma = diag(d)) {
    x <- matrix(x, ncol = length(x))
    d <- ncol(x)
    - 0.5 * (x - mean) %*% solve(sigma) %*% t(x - mean)
}
x <- ru(logf = log_dmvnorm, sigma = covmat, d = 2, n = 1000, init = c(0, 0))
summary(x)
```

rgpd
------

Generalized Pareto simulation

#### Description

Simulates a sample of size m from a generalized Pareto distribution.

#### Usage

rgpd(m = 1, sigma = 1, xi = 0)

#### Arguments

m	A numeric scalar. The size of sample required.
sigma	A numeric scalar. The generalized Pareto scale parameter.
xi	A numeric scalar. The generalized Pareto shape parameter.

# Value

A numeric vector. A generalized Pareto sample of size m.

# Examples

# Sample data from a GP(sigma, xi) distribution
gpd\_data <- rgpd(m = 100, xi = 0, sigma = 1)</pre>

ru

# Generalized ratio-of-uniforms sampling

#### Description

Uses the generalized ratio-of-uniforms method to simulate from a distribution with log-density log f (up to an additive constant). The density f must be bounded, perhaps after a transformation of variable.

#### Usage

```
ru(
  logf,
  ...,
 n = 1,
 d = 1,
  init = NULL,
  trans = c("none", "BC", "user"),
  phi_to_theta = NULL,
  log_j = NULL,
  user_args = list(),
  lambda = rep(1L, d),
  lambda_tol = 1e-06,
  gm = NULL,
  rotate = ifelse(d == 1, FALSE, TRUE),
  lower = rep(-Inf, d),
  upper = rep(Inf, d),
  r = 1/2,
 ep = 0L,
 a_algor = if (d == 1) "nlminb" else "optim",
```

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```
b_algor = c("nlminb", "optim"),
a_method = c("Nelder-Mead", "BFGS", "CG", "L-BFGS-B", "SANN", "Brent"),
b_method = c("Nelder-Mead", "BFGS", "CG", "L-BFGS-B", "SANN", "Brent"),
a_control = list(),
b_control = list(),
var_names = NULL,
shoof = 0.2
```

# Arguments

logf	A function returning the log of the target density $f$ . This function should return -Inf when the density is zero.
	Further arguments to be passed to logf and related functions.
n	A numeric scalar. Number of simulated values required.
d	A numeric scalar. Dimension of f.
init	A numeric vector. Initial estimates of the mode of logf. If trans="BC" or trans = "user" this is <i>after</i> Box-Cox transformation or user-defined transformation, but <i>before</i> any rotation of axes.
trans	A character scalar. "none" for no transformation, "BC" for Box-Cox transforma- tion, "user" for a user-defined transformation. If trans = "user" then the trans- formation should be specified using phi_to_theta and log_j and user_args may be used to pass arguments to phi_to_theta and log_j.
phi_to_theta	A function returning (the inverse) of the transformation from theta to phi used to ensure positivity of phi prior to Box-Cox transformation. The argument is phi and the returned value is theta. If phi_to_theta is undefined at the input value then the function should return NA.
log_j	A function returning the log of the Jacobian of the transformation from theta to phi, i.e. based on derivatives of phi with respect to theta. Takes theta as its argument.
user_args	A list of numeric components. If trans = ``user'' then user_args is a list providing arguments to the user-supplied functions phi_to_theta and log_j.
lambda	Either
	<ul><li>A numeric vector. Box-Cox transformation parameters, or</li><li>A list with components</li></ul>
	lambda A numeric vector. Box-Cox parameters (required).
	<b>gm</b> A numeric vector. Box-cox scaling parameters (optional). If supplied this overrides any gm supplied by the individual gm argument described below.
	<b>init_psi</b> A numeric vector. Initial estimate of mode <i>after</i> Box-Cox transformation (optional).
	sd_psi A numeric vector. Estimates of the marginal standard deviations of the Box-Cox transformed variables (optional).
	phi_to_theta as above (optional).
	<b>log_j</b> as above (optional).

	This list may be created using find_lambda_one_d (for $d = 1$ ) or find_lambda (for any d).	
lambda_tol	A numeric scalar. Any values in lambda that are less than lambda_tol in mag- nitude are set to zero.	
gm	A numeric vector. Box-cox scaling parameters (optional). If lambda\$gm is supplied in input list lambda then lambda\$gm is used, not gm.	
rotate	A logical scalar. If TRUE (d > 1 only) use Choleski rotation. If d = 1 and rotate = TRUE then rotate will be set to FALSE with a warning.	
lower, upper	Numeric vectors. Lower/upper bounds on the arguments of the function <i>after</i> any transformation from theta to phi implied by the inverse of phi_to_theta. If rotate = FALSE these are used in all of the optimizations used to construct the bounding box. If rotate = TRUE then they are use only in the first optimisation to maximise the target density.' If trans = "BC" components of lower that are negative are set to zero without warning and the bounds implied after the Box-Cox transformation are calculated inside ru.	
r	A numeric scalar. Parameter of generalized ratio-of-uniforms.	
ер	A numeric scalar. Controls initial estimates for optimizations to find the b- bounding box parameters. The default (ep=0) corresponds to starting at the mode of logf small positive values of ep move the constrained variable slightly away from the mode in the correct direction. If ep is negative its absolute value is used, with no warning given.	
a_algor,b_algo		
	Character scalars. Either "nlminb" or "optim". Respective optimization algorithms used to find $a(r)$ and $(bi-(r), bi+(r))$ .	
a_method, b_met		
	Character scalars. Respective methods used by optim to find $a(r)$ and $(bi-(r), bi+(r))$ . Only used if optim is the chosen algorithm. If $d = 1$ then a_method and b_method are set to "Brent" without warning.	
a_control, b_control		
	Lists of control arguments to optim or nlminb to find $a(r)$ and $(bi-(r), bi+(r))$ respectively.	
var_names	A character vector. Names to give to the column(s) of the simulated values.	
shoof	A numeric scalar in [0, 1]. Sometimes a spurious non-zero convergence indi- cator is returned from optim or nlminb). In this event we try to check that a minimum has indeed been found using different algorithm. shoof controls the starting value provided to this algorithm. If $shoof = 0$ then we start from the current solution. If $shoof = 1$ then we start from the initial estimate provided to the previous minimisation. Otherwise, shoof interpolates between these two extremes, with a value close to zero giving a starting value that is close to the current solution. The exception to this is when the initial and current solutions are equal. Then we start from the current solution multiplied by 1 -shoof.	

# Details

If trans = "none" and rotate = FALSE then ru implements the (multivariate) generalized ratio of uniforms method described in Wakefield, Gelfand and Smith (1991) using a target density whose mode is relocated to the origin ('mode relocation') in the hope of increasing efficiency.

If trans = "BC" then marginal Box-Cox transformations of each of the d variables is performed, with parameters supplied in lambda. The function phi\_to\_theta may be used, if necessary, to ensure positivity of the variables prior to Box-Cox transformation.

If trans = "user" then the function phi\_to\_theta enables the user to specify their own transformation.

In all cases the mode of the target function is relocated to the origin *after* any user-supplied transformation and/or Box-Cox transformation.

If d is greater than one and rotate = TRUE then a rotation of the variable axes is performed *after* mode relocation. The rotation is based on the Choleski decomposition (see chol) of the estimated Hessian (computed using optimHess of the negated log-density after any user-supplied transformation or Box-Cox transformation. If any of the eigenvalues of the estimated Hessian are non-positive (which may indicate that the estimated mode of logf is close to a variable boundary) then rotate is set to FALSE with a warning. A warning is also given if this happens when d = 1.

The default value of the tuning parameter r is 1/2, which is likely to be close to optimal in many cases, particularly if trans = "BC".

See vignette("rust-a-vignette",package = "rust") for full details.

# Value

An object of class "ru" is a list containing the following components:

sim_vals	An n by d matrix of simulated values.
box	A $(2 * d + 1)$ by d + 2 matrix of ratio-of-uniforms bounding box information, with row names indicating the box parameter. The columns contain
	column 1 values of box parameters.
	<b>columns 2 to (2+d-1)</b> values of variables at which these box parameters are obtained.
	<b>column 2+</b> d convergence indicators.
	Scaling of f within ru and relocation of the mode to the origin means that the first row of box will always be $c(1, rep(0, d))$ .
ра	A numeric scalar. An estimate of the probability of acceptance.
d	A numeric scalar. The dimension of logf.
logf	A function. logf supplied by the user, but with f scaled by the maximum of the target density used in the ratio-of-uniforms method (i.e. $logf_rho$ ), to avoid numerical problems in contouring fin plot.ru when d = 2.
logf_rho	A function. The target function actually used in the ratio-of-uniforms algorithm.
sim_vals_rho	An n by d matrix of values simulated from the function used in the ratio-of- uniforms algorithm.
logf_args	A list of further arguments to logf.
f_mode	The estimated mode of the target density f, after any Box-Cox transformation and/or user supplied transformation, but before mode relocation.

#### References

Wakefield, J. C., Gelfand, A. E. and Smith, A. F. M. (1991) Efficient generation of random variates via the ratio-of-uniforms method. *Statistics and Computing* (1991), **1**, 129-133. http://dx.doi.org/10.1007/BF01889987.

#### See Also

ru\_rcpp for a version of ru that uses the Rcpp package to improve efficiency.

summary.ru for summaries of the simulated values and properties of the ratio-of-uniforms algorithm.

plot.ru for a diagnostic plot.

find\_lambda\_one\_d to produce (somewhat) automatically a list for the argument lambda of ru for the d = 1 case.

find\_lambda to produce (somewhat) automatically a list for the argument lambda of ru for any value of d.

optim for choices of the arguments a\_method, b\_method, a\_control and b\_control.

nlminb for choices of the arguments a\_control and b\_control.

optimHess for Hessian estimation.

chol for the Choleski decomposition.

# Examples

```
# One-dimensional standard normal ------
x \leftarrow ru(logf = function(x) - x^{2} / 2, d = 1, n = 1000, init = 0.1)
# Two-dimensional standard normal -----
x \le ru(logf = function(x) - (x[1]^2 + x[2]^2) / 2, d = 2, n = 1000,
       init = c(0, 0)
# Two-dimensional normal with positive association ------
rho <- 0.9
covmat <- matrix(c(1, rho, rho, 1), 2, 2)</pre>
log_dmvnorm <- function(x, mean = rep(0, d), sigma = diag(d)) {</pre>
 x \leftarrow matrix(x, ncol = length(x))
 d \leq -ncol(x)
  - 0.5 * (x - mean) %*% solve(sigma) %*% t(x - mean)
}
# No rotation.
x <- ru(logf = log_dmvnorm, sigma = covmat, d = 2, n = 1000, init = c(0, 0),
       rotate = FALSE)
# With rotation.
x <- ru(logf = log_dmvnorm, sigma = covmat, d = 2, n = 1000, init = c(0, 0))</pre>
# three-dimensional normal with positive association ------
```

```
covmat <- matrix(rho, 3, 3) + diag(1 - rho, 3)
# No rotation. Slow !
x <- ru(logf = log_dmvnorm, sigma = covmat, d = 3, n = 1000,</pre>
       init = c(0, 0, 0), rotate = FALSE)
# With rotation.
x <- ru(logf = log_dmvnorm, sigma = covmat, d = 3, n = 1000,</pre>
       init = c(0, 0, 0))
# Sampling on original scale ------
x <- ru(logf = dlnorm, log = TRUE, d = 1, n = 1000, lower = 0, init = 1)
# Box-Cox transform with lambda = 0 ------
lambda <- 0
x <- ru(logf = dlnorm, log = TRUE, d = 1, n = 1000, lower = 0, init = 0.1,
       trans = "BC", lambda = lambda)
# Equivalently, we could use trans = "user" and supply the (inverse) Box-Cox
# transformation and the log-Jacobian by hand
x <- ru(logf = dlnorm, log = TRUE, d = 1, n = 1000, init = 0.1,
       trans = "user", phi_to_theta = function(x) exp(x),
       \log_j = function(x) - \log(x)
# Note: the gamma density in unbounded when its shape parameter is < 1.</pre>
# Therefore, we can only use trans="none" if the shape parameter is >= 1.
# Sampling on original scale ------
alpha <- 10
x \leq ru(logf = dgamma, shape = alpha, log = TRUE, d = 1, n = 1000,
       lower = 0, init = alpha)
alpha <- 1
x \leq ru(logf = dgamma, shape = alpha, log = TRUE, d = 1, n = 1000,
       lower = 0, init = alpha)
# Box-Cox transform with lambda = 1/3 works well for shape >= 1. --------
alpha <- 1
x \leq ru(logf = dgamma, shape = alpha, log = TRUE, d = 1, n = 1000,
       trans = "BC", lambda = 1/3, init = alpha)
summary(x)
# Equivalently, we could use trans = "user" and supply the (inverse) Box-Cox
# transformation and the log-Jacobian by hand
# Note: when phi_to_theta is undefined at x this function returns NA
phi_to_theta <- function(x, lambda) {</pre>
```

ru

```
ifelse(x * lambda + 1 > 0, (x * lambda + 1) ^ (1 / lambda), NA)
}
log_j <- function(x, lambda) (lambda - 1) * log(x)</pre>
lambda <- 1/3
x <- ru(logf = dgamma, shape = alpha, log = TRUE, d = 1, n = 1000,</pre>
       trans = "user", phi_to_theta = phi_to_theta, log_j = log_j,
       user_args = list(lambda = lambda), init = alpha)
summary(x)
# Sample data from a GP(sigma, xi) distribution
gpd_data <- rgpd(m = 100, xi = -0.5, sigma = 1)</pre>
# Calculate summary statistics for use in the log-likelihood
ss <- gpd_sum_stats(gpd_data)</pre>
# Calculate an initial estimate
init <- c(mean(gpd_data), 0)</pre>
# Mode relocation only -----
n <- 1000
x1 <- ru(logf = gpd_logpost, ss = ss, d = 2, n = n, init = init,</pre>
        lower = c(0, -Inf), rotate = FALSE)
plot(x1, xlab = "sigma", ylab = "xi")
# Parameter constraint line xi > -sigma/max(data)
# [This may not appear if the sample is far from the constraint.]
abline(a = 0, b = -1 / ss$xm)
summary(x1)
# Rotation of axes plus mode relocation -----
x2 <- ru(logf = gpd_logpost, ss = ss, d = 2, n = n, init = init,</pre>
        lower = c(0, -Inf))
plot(x2, xlab = "sigma", ylab = "xi")
abline(a = 0, b = -1 / ss$xm)
summary(x2)
# The bounding box cannot be constructed if r < 1. For r = 1 the
# bounding box parameters b1-(r) and b1+(r) are attained in the limits
# as x decreases/increases to infinity respectively. This is fine in
# theory but using r > 1 avoids this problem and the largest probability
# of acceptance is obtained for r approximately equal to 1.26.
res <- ru(logf = dcauchy, log = TRUE, init = 0, r = 1.26, n = 1000)
log_halfcauchy <- function(x) {</pre>
 return(ifelse(x < 0, -Inf, dcauchy(x, log = TRUE)))</pre>
}
# Like the Cauchy case the bounding box cannot be constructed if r < 1.
```

```
# We could use r > 1 but the mode is on the edge of the support of the
# density so as an alternative we use a log transformation.
x <- ru(logf = log_halfcauchy, init = 0, trans = "BC", lambda = 0, n = 1000)
x$pa
plot(x, ru_scale = TRUE)
# Bivariate normal x bivariate student-t
\log_n r_t <- function(x, mean = rep(0, d), sigma1 = diag(d), sigma2 = diag(d)) {
 x <- matrix(x, ncol = length(x))</pre>
 d \leq ncol(x)
 log_h1 <- -0.5 * (x - mean) %*% solve(sigma1) %*% t(x - mean)</pre>
 log_h2 <- -2 * log(1 + 0.5 * x %*% solve(sigma2) %*% t(x))
 return(log_h1 + log_h2)
}
rho <- 0.9
covmat <- matrix(c(1, rho, rho, 1), 2, 2)</pre>
y <- c(0, 0)
# Case in the top right corner of Table 3
x <- ru(logf = log_norm_t, mean = y, sigma1 = covmat, sigma2 = covmat,</pre>
 d = 2, n = 10000, init = y, rotate = FALSE)
x$pa
# Rotation increases the probability of acceptance
x <- ru(logf = log_norm_t, mean = y, sigma1 = covmat, sigma2 = covmat,</pre>
 d = 2, n = 10000, init = y, rotate = TRUE)
x$pa
```

rust

rust: Ratio-of-Uniforms Simulation with Transformation

#### Description

Uses the multivariate generalized ratio-of-uniforms method to simulate from a distribution with logdensity logf (up to an additive constant). logf must be bounded, perhaps after a transformation of variable.

#### **Details**

The main functions in the rust package are ru and ru\_rcpp, which implement the generalized ratioof-uniforms algorithm. The latter uses the Rcpp package to improve efficiency. Also provided are two functions, find\_lambda and find\_lambda\_one\_d, that may be used to set a suitable value for the parameter lambda if Box-Cox transformation is used prior to simulation. If ru\_rcpp is used the equivalent functions are find\_lambda\_rcpp and find\_lambda\_one\_d\_rcpp Basic plot and summary methods are also provided.

See vignette("rust-a-vignette", package = "rust") for an overview of the package.

#### ru\_rcpp

#### References

Wakefield, J. C., Gelfand, A. E. and Smith, A. F. M. Efficient generation of random variates via the ratio-of-uniforms method. Statistics and Computing (1991) 1, 129-133. http://dx.doi.org/10. 1007/BF01889987.

Box, G. and Cox, D. R. (1964) An Analysis of Transformations. Journal of the Royal Statistical Society. Series B (Methodological), 26(2), 211-252.

Eddelbuettel, D. and Francois, R. (2011). Rcpp: Seamless R and C++ Integration. Journal of Statistical Software, 40(8), 1-18. http://www.jstatsoft.org/v40/i08/.

Eddelbuettel, D. (2013) Seamless R and C++ Integration with Rcpp. Springer, New York. ISBN 978-1-4614-6867-7.

# See Also

ru and ru\_rcpp to perform ratio-of-uniforms sampling.

summary.ru for summaries of the simulated values and properties of the ratio-of-uniforms algorithm.

plot.ru for a diagnostic plot.

find\_lambda\_one\_d and find\_lambda\_one\_d\_rcpp to produce (somewhat) automatically a list for the argument lambda of ru for the d = 1 case.

find\_lambda and find\_lambda\_rcpp to produce (somewhat) automatically a list for the argument lambda of ru for any value of d.

ru\_rcpp

Generalized ratio-of-uniforms sampling using C++ via Rcpp

# Description

Uses the generalized ratio-of-uniforms method to simulate from a distribution with log-density logf (up to an additive constant). f must be bounded, perhaps after a transformation of variable. The file file 'user\_fns.cpp' that is sourced before running the examples below is available at the rust Github page at https://github.com/paulnorthrop/rust/blob/master/src/user\_fns.cpp.

#### Usage

```
ru_rcpp(
    logf,
    ...,
    n = 1,
    d = 1,
    init = NULL,
    trans = c("none", "BC", "user"),
    phi_to_theta = NULL,
    log_j = NULL,
    user_args = list(),
```

```
lambda = rep(1L, d),
  lambda_tol = 1e-06,
 gm = NULL,
 rotate = ifelse(d == 1, FALSE, TRUE),
 lower = rep(-Inf, d),
 upper = rep(Inf, d),
 r = 1/2,
 ep = 0L,
 a_algor = if (d == 1) "nlminb" else "optim",
 b_algor = c("nlminb", "optim"),
 a_method = c("Nelder-Mead", "BFGS", "CG", "L-BFGS-B", "SANN", "Brent"),
 b_method = c("Nelder-Mead", "BFGS", "CG", "L-BFGS-B", "SANN", "Brent"),
 a_control = list(),
 b_control = list(),
 var_names = NULL,
 shoof = 0.2
)
```

#### Arguments

logf	An external pointer to a compiled C++ function returning the log of the tar- get density <i>f</i> . This function should return -Inf when the density is zero. See the vignette("rust-c-using-rcpp-vignette", package = "rust"), partic- ularly the Section <b>Providing a C++ function to</b> ru_rcpp, for details.
	Further arguments to be passed to logf and related functions.
n	A numeric scalar. Number of simulated values required.
d	A numeric scalar. Dimension of f.
init	A numeric vector. Initial estimates of the mode of logf. If trans = "BC" or trans = "user" this is <i>after</i> Box-Cox transformation or user-defined transformation, but <i>before</i> any rotation of axes.
trans	A character scalar. "none" for no transformation, "BC" for Box-Cox transforma- tion, "user" for a user-defined transformation. If trans = "user" then the trans- formation should be specified using phi_to_theta and log_j and user_args may be used to pass arguments to phi_to_theta and log_j.
phi_to_theta	An external pointer to a compiled C++ function returning (the inverse) of the transformation from theta to phi used to ensure positivity of phi prior to Box-Cox transformation. The argument is phi and the returned value is theta. If phi_to_theta is undefined at the input value then the function should return NA.
log_j	An external pointer to a compiled C++ function returning the log of the Jacobian of the transformation from theta to phi, i.e. based on derivatives of phi with respect to theta. Takes theta as its argument.
user_args	A list of numeric components. If trans = ``user'' then user_args is a list providing arguments to the user-supplied functions phi_to_theta and log_j.
lambda	Either
	• A numeric vector. Box-Cox transformation parameters, or

	• A list with components
	<b>lambda</b> A numeric vector. Box-Cox parameters (required).
	gm A numeric vector. Box-cox scaling parameters (optional). If supplied this overrides any gm supplied by the individual gm argument described below.
	<b>init_psi</b> A numeric vector. Initial estimate of mode <i>after</i> Box-Cox transformation (optional).
	<b>sd_psi</b> A numeric vector. Estimates of the marginal standard deviations of the Box-Cox transformed variables (optional).
	phi_to_theta as above (optional).
	<b>log_j</b> as above (optional).
	user_args as above (optional).
	This list may be created using find_lambda_one_d_rcpp (for d = 1) or find_lambda_rcpp (for any d).
lambda_tol	A numeric scalar. Any values in lambda that are less than lambda_tol in mag- nitude are set to zero.
gm	A numeric vector. Box-cox scaling parameters (optional). If lambda\$gm is supplied in input list lambda then lambda\$gm is used, not gm.
rotate	A logical scalar. If TRUE $(d > 1 \text{ only})$ use Choleski rotation. If $d = 1$ and rotate = TRUE then rotate will be set to FALSE with a warning.
lower, upper	Numeric vectors. Lower/upper bounds on the arguments of the function <i>after</i> any transformation from theta to phi implied by the inverse of phi_to_theta. If rotate = FALSE these are used in all of the optimizations used to construct the bounding box. If rotate = TRUE then they are use only in the first optimisation to maximise the target density.' If trans = "BC" components of lower that are negative are set to zero without warning and the bounds implied after the Box-Cox transformation are calculated inside ru.
r	A numeric scalar. Parameter of generalized ratio-of-uniforms.
ep	A numeric scalar. Controls initial estimates for optimizations to find the b- bounding box parameters. The default (ep=0) corresponds to starting at the mode of logf small positive values of ep move the constrained variable slightly away from the mode in the correct direction. If ep is negative its absolute value is used, with no warning given.
a_algor,b_algo	or
	Character scalars. Either "nlminb" or "optim". Respective optimization algorithms used to find $a(r)$ and $(bi-(r), bi+(r))$ .
a_method, b_me	
	Character scalars. Respective methods used by optim to find $a(r)$ and $(bi-(r), bi+(r))$ . Only used if optim is the chosen algorithm. If $d = 1$ then a_method and b_method are set to "Brent" without warning.
a_control,b_co	ontrol
	Lists of control arguments to optim or nlminb to find $a(r)$ and $(bi-(r), bi+(r))$ respectively.
var_names	A character vector. Names to give to the column(s) of the simulated values.

shoof A numeric scalar in [0, 1]. Sometimes a spurious non-zero convergence indicator is returned from optim or nlminb). In this event we try to check that a minimum has indeed been found using different algorithm. shoof controls the starting value provided to this algorithm. If shoof = 0 then we start from the current solution. If shoof = 1 then we start from the initial estimate provided to the previous minimisation. Otherwise, shoof interpolates between these two extremes, with a value close to zero giving a starting value that is close to the current solution. The exception to this is when the initial and current solutions are equal. Then we start from the current solution multiplied by 1 -shoof.

#### Details

If trans = "none" and rotate = FALSE then ru implements the (multivariate) generalized ratio of uniforms method described in Wakefield, Gelfand and Smith (1991) using a target density whose mode is relocated to the origin ('mode relocation') in the hope of increasing efficiency.

If trans = "BC" then marginal Box-Cox transformations of each of the d variables is performed, with parameters supplied in lambda. The function phi\_to\_theta may be used, if necessary, to ensure positivity of the variables prior to Box-Cox transformation.

If trans = "user" then the function phi\_to\_theta enables the user to specify their own transformation.

In all cases the mode of the target function is relocated to the origin *after* any user-supplied transformation and/or Box-Cox transformation.

If d is greater than one and rotate = TRUE then a rotation of the variable axes is performed *after* mode relocation. The rotation is based on the Choleski decomposition (see chol) of the estimated Hessian (computed using optimHess of the negated log-density after any user-supplied transformation or Box-Cox transformation. If any of the eigenvalues of the estimated Hessian are non-positive (which may indicate that the estimated mode of logf is close to a variable boundary) then rotate is set to FALSE with a warning. A warning is also given if this happens when d = 1.

The default value of the tuning parameter r is 1/2, which is likely to be close to optimal in many cases, particularly if trans = "BC".

See vignette("rust-b-using-rcpp-vignette",package = "rust") and vignette("rust-a-vignette",package = "rust") for full details.

#### Value

An object of class "ru" is a list containing the following components:

sim_vals	An n by d matrix of simulated values.
box	A $(2 * d + 1)$ by $d + 2$ matrix of ratio-of-uniforms bounding box information, with row names indicating the box parameter. The columns contain
	column 1 values of box parameters.
	<b>columns 2 to (2+d-1)</b> values of variables at which these box parameters are obtained.
	column 2+d convergence indicators.
	Scaling of f within ru and relocation of the mode to the origin means that the first row of box will always be $c(1, rep(0, d))$ .

ра	A numeric scalar. An estimate of the probability of acceptance.	
d	A numeric scalar. The dimension of logf.	
logf	A function. logf supplied by the user, but with f scaled by the maximum of the target density used in the ratio-of-uniforms method (i.e. logf_rho), to avoid numerical problems in contouring f in plot.ru when d = 2.	
logf_rho	A function. The target function actually used in the ratio-of-uniforms algorithm.	
sim_vals_rho	An n by d matrix of values simulated from the function used in the ratio-of- uniforms algorithm.	
logf_args	A list of further arguments to logf.	
logf_rho_args	A list of further arguments to logf_rho. Note: this component is returned by ru_rcpp but not by ru.	
f_mode	The estimated mode of the target density f, after any Box-Cox transformation and/or user supplied transformation, but before mode relocation.	

#### References

Wakefield, J. C., Gelfand, A. E. and Smith, A. F. M. (1991) Efficient generation of random variates via the ratio-of-uniforms method. *Statistics and Computing* (1991), **1**, 129-133. http://dx.doi.org/10.1007/BF01889987.

Eddelbuettel, D. and Francois, R. (2011). Rcpp: Seamless R and C++ Integration. *Journal of Statistical Software*, **40**(8), 1-18. http://www.jstatsoft.org/v40/i08/.

Eddelbuettel, D. (2013). Seamless R and C++ Integration with Rcpp, Springer, New York. ISBN 978-1-4614-6867-7.

#### See Also

ru for a version of ru\_rcpp that accepts R functions as arguments.

summary.ru for summaries of the simulated values and properties of the ratio-of-uniforms algorithm.

plot.ru for a diagnostic plot.

find\_lambda\_one\_d\_rcpp to produce (somewhat) automatically a list for the argument lambda of ru for the d = 1 case.

find\_lambda\_rcpp to produce (somewhat) automatically a list for the argument lambda of ru for any value of d.

optim for choices of the arguments a\_method, b\_method, a\_control and b\_control.

nlminb for choices of the arguments a\_control and b\_control.

optimHess for Hessian estimation.

chol for the Choleski decomposition.

#### Examples

```
n <- 1000
# One-dimensional standard normal ------
ptr_N01 <- create_xptr("logdN01")</pre>
x <- ru_rcpp(logf = ptr_N01, d = 1, n = n, init = 0.1)
# Two-dimensional standard normal ------
ptr_bvn <- create_xptr("logdnorm2")</pre>
rho <- 0
x <- ru_rcpp(logf = ptr_bvn, rho = rho, d = 2, n = n,</pre>
 init = c(0, 0)
rho <- 0.9
# No rotation.
x \leq ru_rcpp(logf = ptr_bvn, rho = rho, d = 2, n = n, init = c(0, 0),
            rotate = FALSE)
# With rotation.
x \leftarrow ru_rcpp(logf = ptr_bvn, rho = rho, d = 2, n = n, init = c(0, 0))
# Using general multivariate normal function.
ptr_mvn <- create_xptr("logdmvnorm")</pre>
covmat <- matrix(rho, 2, 2) + diag(1 - rho, 2)
x \leq ru_rcpp(logf = ptr_mvn, sigma = covmat, d = 2, n = n, init = c(0, 0))
# Three-dimensional normal with positive association ------
covmat <- matrix(rho, 3, 3) + diag(1 - rho, 3)</pre>
# No rotation.
x <- ru_rcpp(logf = ptr_mvn, sigma = covmat, d = 3, n = n,</pre>
            init = c(0, 0, 0), rotate = FALSE)
# With rotation.
x <- ru_rcpp(logf = ptr_mvn, sigma = covmat, d = 3, n = n,</pre>
            init = c(0, 0, 0)
ptr_lnorm <- create_xptr("logdlnorm")</pre>
mu <- 0
sigma <- 1
# Sampling on original scale ------
x <- ru_rcpp(logf = ptr_lnorm, mu = mu, sigma = sigma, d = 1, n = n,</pre>
            lower = 0, init = exp(mu))
# Box-Cox transform with lambda = 0 ------
lambda <- 0
x <- ru_rcpp(logf = ptr_lnorm, mu = mu, sigma = sigma, d = 1, n = n,</pre>
```

```
lower = 0, init = exp(mu), trans = "BC", lambda = lambda)
# Equivalently, we could use trans = "user" and supply the (inverse) Box-Cox
# transformation and the log-Jacobian by hand
ptr_phi_to_theta_lnorm <- create_phi_to_theta_xptr("exponential")</pre>
ptr_log_j_lnorm <- create_log_j_xptr("neglog")</pre>
x <- ru_rcpp(logf = ptr_lnorm, mu = mu, sigma = sigma, d = 1, n = n,</pre>
 init = 0.1, trans = "user", phi_to_theta = ptr_phi_to_theta_lnorm,
 log_j = ptr_log_j_lnorm)
# Note: the gamma density in unbounded when its shape parameter is < 1.
# Therefore, we can only use trans="none" if the shape parameter is >= 1.
# Sampling on original scale ------
ptr_gam <- create_xptr("logdgamma")</pre>
alpha <- 10
x <- ru_rcpp(logf = ptr_gam, alpha = alpha, d = 1, n = n,</pre>
 lower = 0, init = alpha)
alpha <- 1
x <- ru_rcpp(logf = ptr_gam, alpha = alpha, d = 1, n = n,</pre>
 lower = 0, init = alpha)
# Box-Cox transform with lambda = 1/3 works well for shape >= 1. --------
alpha <- 1
x <- ru_rcpp(logf = ptr_gam, alpha = alpha, d = 1, n = n,</pre>
 trans = "BC", lambda = 1/3, init = alpha)
summary(x)
# Equivalently, we could use trans = "user" and supply the (inverse) Box-Cox
# transformation and the log-Jacobian by hand
lambda <- 1/3
ptr_phi_to_theta_bc <- create_phi_to_theta_xptr("bc")</pre>
ptr_log_j_bc <- create_log_j_xptr("bc")</pre>
x <- ru_rcpp(logf = ptr_gam, alpha = alpha, d = 1, n = n,</pre>
 trans = "user", phi_to_theta = ptr_phi_to_theta_bc, log_j = ptr_log_j_bc,
 user_args = list(lambda = lambda), init = alpha)
summary(x)
# Sample data from a GP(sigma, xi) distribution
gpd_data <- rgpd(m = 100, xi = -0.5, sigma = 1)</pre>
# Calculate summary statistics for use in the log-likelihood
ss <- gpd_sum_stats(gpd_data)</pre>
# Calculate an initial estimate
init <- c(mean(gpd_data), 0)</pre>
```

```
n <- 1000
# Mode relocation only ------
ptr_gp <- create_xptr("loggp")</pre>
for_ru_rcpp <- c(list(logf = ptr_gp, init = init, d = 2, n = n,</pre>
                lower = c(0, -Inf), ss, rotate = FALSE)
x1 <- do.call(ru_rcpp, for_ru_rcpp)</pre>
plot(x1, xlab = "sigma", ylab = "xi")
# Parameter constraint line xi > -sigma/max(data)
# [This may not appear if the sample is far from the constraint.]
abline(a = 0, b = -1 / ss$xm)
summary(x1)
# Rotation of axes plus mode relocation ------
for_ru_rcpp <- c(list(logf = ptr_gp, init = init, d = 2, n = n,</pre>
                lower = c(0, -Inf), ss)
x2 <- do.call(ru_rcpp, for_ru_rcpp)</pre>
plot(x2, xlab = "sigma", ylab = "xi")
abline(a = 0, b = -1 / ss$xm)
summary(x2)
ptr_c <- create_xptr("logcauchy")</pre>
# The bounding box cannot be constructed if r < 1. For r = 1 the
# bounding box parameters b1-(r) and b1+(r) are attained in the limits
# as x decreases/increases to infinity respectively. This is fine in
# theory but using r > 1 avoids this problem and the largest probability
# of acceptance is obtained for r approximately equal to 1.26.
res <- ru_rcpp(logf = ptr_c, log = TRUE, init = 0, r = 1.26, n = 1000)
ptr_hc <- create_xptr("loghalfcauchy")</pre>
# Like the Cauchy case the bounding box cannot be constructed if r < 1.
# We could use r > 1 but the mode is on the edge of the support of the
# density so as an alternative we use a log transformation.
x <- ru_rcpp(logf = ptr_hc, init = 0, trans = "BC", lambda = 0, n = 1000)</pre>
x$pa
plot(x, ru_scale = TRUE)
# Bivariate normal x bivariate student-t
ptr_normt <- create_xptr("lognormt")</pre>
rho <- 0.9
covmat <- matrix(c(1, rho, rho, 1), 2, 2)</pre>
y <- c(0, 0)
```

#### summary.ru

```
# Case in the top right corner of Table 3
x <- ru_rcpp(logf = ptr_normt, mean = y, sigma1 = covmat, sigma2 = covmat,
    d = 2, n = 10000, init = y, rotate = FALSE)
x$pa
# Rotation increases the probability of acceptance
x <- ru_rcpp(logf = ptr_normt, mean = y, sigma1 = covmat, sigma2 = covmat,
    d = 2, n = 10000, init = y, rotate = TRUE)
x$pa</pre>
```

summary.ru

# Summarizing ratio-of-uniforms samples

# Description

summary method for class "ru"

# Usage

## S3 method for class 'ru'
summary(object, ...)

# Arguments

object	an object of class "ru", a result of a call to ru.
	Additional arguments passed on to summary.

# Value

# Prints

- information about the ratio-of-uniforms bounding box, i.e. object\$box
- an estimate of the probability of acceptance, i.e. object\$pa
- a summary of the simulated values, via summary(object\$sim\_vals)

# See Also

ru for descriptions of object\$sim\_vals and object\$box.

plot.ru for a diagnostic plot.

# Examples

```
# one-dimensional standard normal ------
x <- ru(logf = function(x) -x ^ 2 / 2, d = 1, n = 1000, init = 0)
summary(x)
# two-dimensional normal with positive association ------
rho <- 0.9
covmat <- matrix(c(1, rho, rho, 1), 2, 2)
log_dmvnorm <- function(x, mean = rep(0, d), sigma = diag(d)) {
    x <- matrix(x, ncol = length(x))
    d <- ncol(x)
    - 0.5 * (x - mean) %*% solve(sigma) %*% t(x - mean)
}
x <- ru(logf = log_dmvnorm, sigma = covmat, d = 2, n = 1000, init = c(0, 0))
summary(x)
```

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