

Package ‘nlsrk’

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Title Runge-Kutta Solver for Function nls()

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Depends R (>= 3.0.0)

Description Performs univariate or multivariate computation of a single ODE or of a set of ODE (ordinary differential equations).

License GPL (>= 2)

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R topics documented:

nlsrk-package	2
dfd ^t	3
evrunge	4
frunge	7
kmk	8
logis	9
logis.don	10
multirunge	10
nlscontour	11
nlsModel	13
plot.nlsrk	13
prepare	15
summary.nlsgrid	16
sys	17
syslin	18
syslin.don	18

Index	20
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nlsrk-package	<i>Runge-Kutta package for nls</i>
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Description

Performs univariate or multivariate computation of a single ODE or of a set of ODE (ordinary differential equations)

Details

Package:	nlsrk
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Univariate functions (single ODE)

dfdt	Right Side of a first order ODE
frunge	Numeric solution of an ODE (univariate)

Multivariate functions (ODEs system)

multirunge	Runge-Kutta numerical solver (single point, multivariate)
evrunge	Numerical Runge-Kutta Solver (multi point, multivariate)
prepare	Prepares a multivariate data set for use in nls / evrunge
sys	Right side of a first order differential equation system (multivariate)

Utility

nlscontour	Draws a contourplot of the sum of squares function around a couple of parameters
summary.nlsgrid	Details on an nlsgrid

data

logis	Logistic growth of bacteria
syslin	Pharmacokinetics : intramuscular injection
syslin.don	Intra muscular injection (columns)

Note

nlsrk provides to nls(stats) an evaluation of functions defined by first order Ordinary Differential Equations (ODEs). For a single ODE use [frunge](#) and edit [dfdt](#). For a system of ODEs, use the multivariate functions [evrunge](#) and edit [sys](#). The method used in both cases is the Runge-Kutta 4 method. The result is not guaranteed especially for "stiff" systems of equations.

Author(s)

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References

Numerical Recipes <http://www.nr.com>

See Also

[nls](#)

dfdt

Right Side of a first order ODE

Description

Gives the value of the right side of a first order Ordinary Differential Equation Used in frunge (Numeric resolution using Runge-Kutta 4 method)

Usage

`dfdt(t, y, param)`

Arguments

t	time, independent variable
y	values of the unknown function at t
param	numeric vector : the set of parameters defining the function

Details

the unique expression composing the body of dfdt is intended as the right side of the first order differential equation :

$$\frac{dy}{dt} = dfdt(t, y, param)$$

The function body has to be written by the user.

param must take the form `c(param1,param2,param3)`. if the initial value (`y0`) is used as a parameter (for model fitting for instance), it **must be the last** in the list and **not used** in dfdt.

Value

a single float numeric value : the derivative of the unknown function at time t.

Note

When used as argument for frunge, the initial condition **y0** may be used as a parameter subject to fitting by **nls**, for instance. In this condition, **y0** must appear as the **last** parameter in param and **must not** be used nor modified in dfdt

Author(s)

Jean-Sebastien Pierre
<Jean-sebastien.pierre@univ-rennes1.fr>

References

Any textbook in mathematics

See Also

[frunge](#), [nls](#)

Examples

```
## Solves and draws the logistic function using default dfdt as provided in the package
frunge(t=10, param=c(r=0.1,k=100), y0=3, Dfdt = dfdt, dt = 0.01, graph = TRUE)
```

Description

evrunge evaluates the solutions of a system of first order ordinary equations for a given set of values of the independent variable (generally the time).

Usage

```
evrunge(t, param, y0, sys, dt = 0.01, graph = FALSE, observable = rep(1, length(y0)))
```

Arguments

t	numerical vector : the values of t at which the ODE system must be evaluated
param	numerical vector or numerical objects list. Passed as arguments to sys
y0	numerical vector : the initial values of the unknown functions to solve
sys	the function giving the right side of the system. Must be written by user (see ?sys)
dt	integration step for Runge-Kutta algorithm. Default = 0.01
graph	optionally : graphic representation of the set of solutions. Default = FALSE
observable	A numeric vector coding what trajectories are observable. 1 = observable, 2 = not observable. Default : a vector of 1, nfunct times

Details

This function is intended basically to be used in conjunction with **nls** for non linear least square fit of a set of ODEs on experimental data. This is the reason why the solutions are concatenated in a single column. For fitting with **nls**, the data have to be organised in the same way. Use **prepare(nlsrk)** to convert a data frame with observations in separate columns in one where the columns are concatenated. In a further version of this function, the solutions will optionnaly be provided as columns of an data.frame. The system must be provided by user. See **sys** for an editable example.

t must be sorted in ascending order **and** every intervals between two consecutive values of t **must be greater then dt**. Otherwise, the function stops and an error message is displayed.

Although the algorithm works with dt slightly lower than with $\min(t[i+1] - t[i])$ the accuracy of the results are not guaranteed. It is recommended to chose with dt fairly lower than the minimum interval in with t See the note below concerning the parameter 'observable'

Value

A vector of size $nfunct \times \text{length}(t)$ where nfunct is the number of equations in sys

Note

Calls **multirunge** for each point t

Uses Runge-Kutta 4 algorithm. The error is of order dt^4 . This algorithm is robust and simple but is not guaranteed to work correctly on any ODE system. In particular, RK4 is a fixed step algorithm. "stiff" systems of equations require generally more sophisticated methods with adaptive steps.

Sometimes, especially when the observations are the result of a sampling procedure, it may be useful to treat the initial conditions as parameters injected in the fitting procedure of **nls**. Note that in these conditions, y0 appears three times in the call to **nls**: in param, as parameter of **evrunge** and as starting values for parameters in start

The option observable allows to fit data sets where the data are observable only for a subset of the state variables involved in the equations system. There is **no guarantee that nls converges in this case**. The success of the algorithm requires the model to be **identifiable** with the subset of observations. Identifiability is a difficult mathematical topic that filled a lot of books.

Author(s)

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References

~put references to the literature/web site here ~

See Also

[multirunge](#), [sys](#), [prepare](#), [nls](#)

Examples

```
##  

## example 1 : solving and plotting the system sys provided in the package  

##  

data(syslin.don)  

syslin<-prepare(syslin.don)  

evrunge(t=c(1:30),param=c(1,1),y0=c(1000,0),sys=sys,graph=TRUE)  

##  

## example 2 : fitting by nls on data \code{syslin} fixed and known initial conditions  

##  

data(syslin)  

attach(syslin)  

nls(y~ evrunge(t,param=c(k1,k2),y0=c(1000,0),sys,graph=FALSE),data=syslin,start=list(k1=1,k2=1),  

trace=TRUE)->m1  

summary(m1)  

detach(syslin)  

##  

## example 3 : fitting by nls on data syslin "unknown" initial conditions:  

##           they have to be fitted as parameters  

##  

data(syslin)  

nls(y~ evrunge(t,param=c(k1,k2,y0),y0=c(1000,0),sys,graph=FALSE),data=syslin,start=list(k1=1,k2=1,  

y0=c(1000,0)),trace=TRUE)->m2  

summary(m2)  

plot.nlsrk(m2,syslin)  

##  

## example 4 : fitting by nls on data syslin with known initial conditions:  

##           There are no observations for the trajectory 1 which is not observable.  

##           sys is unchanged  

##  

data(syslin)  

##           We eliminate the data corresponding to trajectory 1 and fit only on trajectory 2.  

##           Fixed initial conditions  

syslin2<-syslin[syslin$traj==2,]  

attach(syslin2)  

nls(y~ evrunge(t,param=c(k1,k2),y0=c(1000,0),sys,graph=FALSE,observable=c(0,1)),data=syslin2,  

start=list(k1=1,k2=1),trace=TRUE)->m3  

summary(m3)
```

```
plot.nlsrk(m3,syslin2)
detach(syslin2)
```

frunge*Numeric solution of an ODE (univariate)*

Description

frunge provides a sampled numeric solution for an ODE for a given set of values of the independent variable (t). Returns a series of values corresponding to each values of t

Usage

```
frunge(t, param, y0, Dfdt, dt = 0.01, graph = FALSE)
```

Arguments

t	The independent variable. Must be sorted in increasing order
param	Numeric vector : under the form of c(param1,param2...) gives the parameters passed to dfdt
y0	The initial condition. May appear as a parameter for nls. See details
Dfdt	A function giving the right side of the ODE. Default is dfdt(nlsrk)
dt	Time increment for Runge-Kutta algorithm. Must be lower than the smaller difference between two consecutive t values
graph	If true, plots the graph of the function over the range of t. (For standalone usage)

Details

The vector **t must be** sorted in increasing order. Any badly placed t will result in an error and program exit. dt must be lower than min(diff(t)). If not, an error will occur. The shorter **dt**, the more accurate the solution but the longer the calculation will be.

Value

A numeric vector of length equal to the length of t. y[1] is set to y0

Author(s)

Jean-Sebastien Pierre
<Jean-sebastien.pierre@univ-rennes1.fr>

References

Numerical recipes <http://www.nr.com>

See Also[dfdt,nls](#)**Examples**

```

v<-frunge(t=seq(0,50,0.5), param=c(r=0.1,k=100), y0=3, Dfdt = dfdt, dt = 0.01, graph = TRUE)
plot(seq(0,50,0.5),v)
##
##      Example of model fitting with frunge. a : determined initial condition
##
data(logis)
attach(logis)
nls(y~frunge(time,c(r,k),y0=3,dfdt,graph=FALSE),data=logis,start=list(r=0.05,k=100),trace=TRUE)->m1
plot(time,y)
lines(time,fitted(m1))
summary(m1)
detach(logis)
##
##      Example of model fitting with frunge. b : unknown initial condition ;
##      y0 is fitted as a parameter

## Not run: data(logis)
attach(logis)
nls(y~frunge(time,c(r,k,y0),y0,dfdt,graph=FALSE),data=logis,start=list(r=0.05,k=100,y0=y[1]),
     trace=TRUE)->m2
plot(time,y)
lines(time,fitted(m2))
summary(m1)
detach(logis)
## End(Not run)

```

kmk

*mck-Mc Kendrick SIR system***Description**

a variant of sys to use in evrunge

Usage

```
kmk()
```

Value

see [sys](#) Three values for three equations are returned

Author(s)

J.S. Pierre

See Also

[sys](#), [evrunge](#)

Examples

```
## The function is currently defined as
function () {
  f1 <- function(t, y, param) -param[1] * y[1] * y[2]
  f2 <- function(t, y, param) param[1] * y[1] * y[2] - param[2] * y[2]
  f3 <- function(t, y, param) param[2] * y[2]
  c(f1, f2, f3)
}
```

logis *Logistic growth of bacteria*

Description

Logistic growth in bacteria : time versus Optical Density in arbitrary units (simulated data)

Usage

```
data(logis.don)
```

Format

A data frame with 51 observations on the following 2 variables.

time a numeric vector : time in hours
y a numeric vector : Optical Density

Details

a dataset suitable to run nls and fit a logistic model, eventually under the form of a differential equation

Source

personnal source J.S. Pierre

Examples

```
data(logis)
## maybe str(logis) ; plot(logis) ...
```

`logis.don` *Logistic growth of bacteria*

Description

Logistic growth in bacteria : time versus Optical Density in arbitrary units (simulated data)

Usage

```
data(logis.don)
```

Format

A data frame with 51 observations on the following 2 variables.

`time` a numeric vector : time in hours
`y` a numeric vector : Optical Density

Details

a dataset suitable to run `nls` and fit a logistic model, eventually under the form of a differential equation

Source

personnal source J.S. Pierre

Examples

```
data(logis.don)
## maybe str(logis.don) ; plot(logis.don) ...
```

`multirunge` *Runge-Kutta numerical solver (single point, multivariate)*

Description

Solves numerically an initial conditions problem for a set of Ordinary Differential Equations (ODE) by Runge-Kutta 4 method. Integrates numerically the equations from `tmin` to `tmax` by steps of `dt`.

Usage

```
multirunge(y0, tmin, tmax, dt, param, sys)
```

Arguments

y0	Numerical vector : initial conditions (as many elements as equations in sys)
tmin	Minimum value of the independent variable (generally the time)
tmax	Maximum value of the independent variable
dt	Time increment (default = 0.01)
param	Numerical vector providing the parameters for sys
sys	The set of functions giving the right sides of the ODEs

Details

sys must be provided by the user. Please edit the object sys (see ?sys and examples)

Value

A numerical vector of **nfunct** elements. Nfunct is the number of unknown functions of sys determined by the function as length(sys())

Note

Should seldom be used independently. Most often it will be called by **evrunge**

Author(s)

Jean-Sebastien Pierre
<Jean-sebastien.pierre@univ-rennes1.fr>

See Also

[evrunge](#), [sys](#), [nls](#)

Examples

```
multirunge(y0=c(1000,0),tmin=0,tmax=30,dt=0.01,param=c(1,1),sys=sys)
```

nlscontour

Contour plot for nonlinear least squares

Description

Takes as central values the results of non-linear least square fitting by the nls(base, stats) function, then draws a contour plot of the residual sum of squares function around these values.

Usage

```
nlscontour(x, param1 = 1, param2 = 2, range1 = NULL, range2 = NULL,
npoints = 100, filled = FALSE,colored=FALSE)
```

Arguments

<code>x</code>	a <code>nls</code> model
<code>param1</code>	The number of the first parameter to plot in the parameters list of model formula
<code>param2</code>	The number of the second parameter to plot
<code>range1</code>	The range (min and max) for plotting parameter <code>param1</code> . Default = +/-4*Standard Error of the parameter
<code>range2</code>	The range (min and max) for plotting parameter <code>param2</code> . Default = +/-4*Standard Error of the parameter
<code>npoints</code>	Number of points of the grid for contour. Default = 100
<code>filled</code>	Defines the style of the contour plot FALSE: lines (default), TRUE: filled contours (shades of gray)
<code>colored</code>	Defines the style of the contour plot FALSE: lines (default), TRUE: Colored contours (red= lower)

Details

`npoints` defines the total number of points of the square grid used for drawing the contour plot. Thus, the grid will be of size `round(sqrt(npoints))*round(sqrt(npoints))`

Value

an object of class `nlsgrid` with three components:

<code>\$x</code>	the values used for the first parameter
<code>\$y</code>	the values used for the second parameter
<code>\$grid</code>	a square matrix: The values of the residual sum of squares for each combination of the parameters
...	

Author(s)

Jean-Sebastien Pierre
 <Jean-sebastien.pierre@univ-rennes1.fr>

References

~put references to the literature/web site here ~

See Also

[nls](#) [logis](#) [summary.nlsgrid](#)

Examples

```
data(logis)
attach(logis)
m1<-nls(y~k/(1+c*exp(-r*time)),data=logis,start=c(k=100,r=0.1,c=40))
nlscontour(m1)
detach(logis)
```

nlsModel

calculate a model as defined in nls for the set of parameters start on the values data

Description

Recovered from older versions of R (<= 1.8), obsolete in 2.10

Usage

```
nlsModel(form, data, start)
```

Arguments

form	A nls model object
data	a data frame of independent variables
start	a list of parameter values

Value

a vector of estimates

Author(s)

R development core team

plot.nlsrk

Plot of multivariate data fitted by the nlsrk package

Description

Plot the experimental points of each trajectory with the lines fitted by nls / nlsrk

Usage

```
## S3 method for class 'nlsrk'
plot(x, data, maintitle = "Ordinary Differential Equations system", ...)
```

Arguments

<code>x</code>	A "nls" object obtained with <code>evrunge</code>
<code>data</code>	a <code>data.frame</code> with only three columns named (imperatively) <code>t</code> , <code>y</code> , <code>traj</code> in that order
<code>maintitle</code>	Title for the graph
<code>...</code>	optional parameters for plot

Details

`syslin` Minimal and preliminary implementation of a plot method for "nls" objects obtained by Runge-Kutta 4 resolution of a set of ODE. The symbols of the experimental points are chosen automatically according to the formula `pch=19+data$traj`. Then, the first trajectory is drawn with `pch=20` (black dot), the next with `pch=21` (empty circles), etc... see [plot\(options\)](#) and [par](#) for details. Similarly, the lines of the fitted solutions are drawn in a color defined automatically according to the formula `col=data$traj`. The first trajectory is drawn in black (`col=1`), the next in red (`col=2`), etc... Any object of type "nls" is accepted by the program, but if it does not result of the use of `evrunge`, unpredictable errors will occur.

Value

`none`

Author(s)

jean-sebastien pierre
`<jean-sebastien.pierre@univ-rennes1.fr>`

See Also

[evrunge](#)

Examples

```
##  

## example 1 : solving and plotting the system sys provided in the package  

##  

data(syslin.don)  

syslin<-prepare(syslin.don)  

attach(syslin)  

nls(y~ evrunge(t,param=c(k1,k2),y0=c(1000,0),sys,graph=FALSE),data=syslin,  

start=list(k1=1,k2=1),trace=TRUE)->m1  

plot.nlsrk(m1,syslin)  

##
```

prepare*Prepares a multivariate data set for use in nls / evrunge*

Description

Utility :

Modifies a multivariate data.frame for fitting a nonlinear model defined by a system of first order Ordinary Differential Equations. In the original data.frame, the data must be arranged in **nfunct + 1** columns, **nfunct** being the dimension of the ODE system. One of the columns must be the observation times (or in general the observations of the independent variable). The other columns are the observations of the functions. **prepare** returns the same data set with a single column for time (repeated **nfunct** times), and a single column for the concatenated observations. A third column is created as a factor indexing the original column (1 for the first, 2 for the second, etc)

Usage

```
prepare(x = data.frame, ntime = 1, cols = c(2:(length(x[1, ]))))
```

Arguments

- | | |
|-------|--|
| x | a data.frame : one column for time and one for each function |
| ntime | numeric : the number of the column coding for time (independent variable) |
| cols | numeric vector : the numbers of the columns corresponding to each dependent variable |

Details

Prepares the data set as an entry for **nls** which is basically univariate. The formula in **nls** must involve **evrunge**. As **nls** considers the observations as univariate, the criterion used in the least-square process is that of the **trace** of the variance-covariance matrix of the residuals.

Value

A data.frame with columns :

- | | |
|------|--|
| t | time repeated as many times as necessary |
| y | concatenated observed trajectories |
| traj | factor : number of the trajectory |

Author(s)

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See Also

[frunge](#), [dfdt](#), [multirunge](#), [evrunge](#), [sys](#), [nls](#)

Examples

```
data(syslin.don)
syslin<-prepare(syslin.don)
summary(syslin)
```

summary.nlsgrid

Summary method for objects of class nlsgrid(nlsrk)

Description

Prints the characteristics of an nlsgrid

Usage

```
## S3 method for class 'nlsgrid'
summary(object, ...)
```

Arguments

object	An object of class nlsgrid
...	Any parameters for summary

Value

NULL

Author(s)

Jean-Sebastien Pierre
 <Jean-sebastien.pierre@univ-rennes1.fr>

References

none

See Also

[nlsrk](#), [nlsrk-package](#), [nls](#), [nlscontour](#)

Examples

```
data(logis)
m1<-nls(y~k/(1+c*exp(-r*time)),data=logis,start=list(k=100,r=0.1,c=45))
gr12<-nlscontour(m1)
summary(gr12)
```

sys

Right side of a first order differential equation system (multivariate)

Description

sys gives the set of derivatives of a first order differential equation system. The functions must be provided by user. Edit and change sys.

Usage

sys()

Details

sys has no arguments but the componing functions must have three : **t, y param**. sys returns the rights sides of the set of **nfonct** functions.

Value

A numeric vector of the **nfonct** functions at time **t**

Author(s)

Jean-Sebastien Pierre
<Jean-sebastien.pierre@univ-rennes1.fr>

References

any mathematical textbook

See Also

[evrunge](#), [multirunge](#), [nls](#)

Examples

```
evrunge(seq(0,10,0.1),c(1,1),y0=c(1000,0),sys=sys,graph=TRUE)
```

syslin

*Pharmacokinetics : intramuscular injection***Description**

A survey in time of muscle and blood concentrations of a drug following an intramuscular injection.

Usage

```
data(syslin)
```

Format

A data frame with 100 observations on the following 3 variables.

t a numeric vector : time in hours
y a numeric vector : blood or muscle concentration
traj a factor : number of the compartments. 1=muscle, 2= blood

Source

simulated data (J.S. Pierre)

Examples

```
data(syslin)
## maybe str(syslin) ; plot(syslin) ...
```

syslin.don

*Intra muscular injection (columns)***Description**

Concentration of a drug in the muscle and in the blood at various times after injection

Usage

```
data(syslin.don)
```

Format

A data frame with 50 observations on the following 3 variables.

t a numeric vector: time
y1 a numeric vector : muscle concentration
y2 a numeric vector : blood concentration

Details

must be modified by [prepare](#) to be fitted by nls / evrunge

Source

Simulated data (J.S. Pierre)

Examples

```
## concatenation of muscle and blood concentration by prepare
```

```
data(syslin.don)
summary(syslin.don)
syslin<-prepare(syslin.don)
summary(syslin)
```

Index

*Topic **datasets**
 `logis`, 9
 `logis.don`, 10
 `syslin`, 18
 `syslin.don`, 18

*Topic **multivariate**
 `plot.nlsrk`, 13

*Topic **nonlinear**
 `dfdt`, 3
 `evrunge`, 4
 `frunge`, 7
 `kmk`, 8
 `multirunge`, 10
 `nlscontour`, 11
 `nlsModel`, 13
 `prepare`, 15
 `summary.nlsgrid`, 16
 `sys`, 17

*Topic **package**
 `nlsrk-package`, 2

`dfdt`, 3, 3, 8, 15

`evrunge`, 3, 4, 9, 11, 14, 15, 17

`frunge`, 3, 4, 7, 15

`kmk`, 8

`logis`, 9, 12
 `logis.don`, 10

`multirunge`, 6, 10, 15, 17

`nls`, 3, 4, 6, 8, 11, 12, 15–17
 `nlscontour`, 11, 16
 `nlsModel`, 13
 `nlsrk`, 16
 `nlsrk (nlsrk-package)`, 2
 `nlsrk-package`, 2

`options`, 14
 `par`, 14
 `plot`, 14
 `plot.nlsrk`, 13
 `prepare`, 6, 15, 19
 `summary.nlsgrid`, 12, 16
 `sys`, 3, 5, 6, 8, 9, 11, 15, 17
 `syslin`, 18
 `syslin.don`, 18