

Package ‘nat.templatebrains’

June 24, 2018

Type Package

Title NeuroAnatomy Toolbox ('nat') Extension for Handling Template Brains

Version 0.9

Description Extends package 'nat' (NeuroAnatomy Toolbox) by providing objects and functions for handling template brains.

License GPL-3

Depends R (>= 2.10), rgl, nat (>= 1.8.6)

Imports igraph, digest, rappidirs, memoise

Suggests testthat (>= 0.10), git2r, nabor

URL <https://github.com/jefferislab/nat.templatebrains>

RoxygenNote 6.0.1

NeedsCompilation no

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Repository CRAN

Date/Publication 2018-06-24 17:47:53 UTC

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nat.templatebrains-package

NeuroAnatomy Toolbox add-on package for handling template brains

Description

This package provides a class `templatebrain` that stores key information about reference brains along with helper functions to simplify transformation of data between template brains (a.k.a bridging) and mirroring of data within a template brain.

Helper functions

Easy-to-use functions for transforming data from one template brain to another, displaying slices alongside 3D data, etc. are provided.

For transforming between spaces, see especially `xform_brain`, `mirror_brain`. The `regtemplate` functions allow an R object containing neuroanatomical data to be tagged as in a particular template brain space.

`plot3d.templatebrain` provides a simple way to plot a surface object representing a given template brain.

Registrations

Functions such as `xform_brain` provided by `nat.templatebrains` are not very useful unless you tell the package about bridging/mirroring registrations that you have available. There are 4 supported ways to add registrations to the search list that will be considered:

- Install a package (e.g. `nat.flybrains`) that bundles registrations.
- `download_reg_repo` to download pre-packaged registration folders from github. This will automatically add the new folders to the registration search list both in the current session and on package startup.
- `add_reg_folders` to add additional local directories to the registration search list. You will need to do this each time your start an R session unless you add it to your `Rprofile`.
- `add_reclist` to add an in-memory `reclist` containing an arbitrary sequence of registrations. By default this will not persist across R sessions but this behaviour can be changed.

Note that the package implements a cache to avoid rescanning the directories in the registration search list all the time. The functions mentioned above will automatically ensure that the cache is reset whenever a new set of registrations are added to the search list.

Package options

- `options('nat.templatebrains.regdirs')` specifies a character vector of directories containing registrations i.e. a registration search list.

It is strongly recommended that you use the functions mentioned above rather than manipulating the registration search list directly.

Note that registration directories will be searched in the order that they are listed. It is therefore strongly recommended that individual registrations have globally unique names.

See Also

[nat](#)

Examples

```
## Not run:  
# Plot all known registrations  
plot(bridging_graph(), vertex.size=25)  
  
## manually add a new directory containing registrations to the search list  
# Don't do this unless essential!  
options(nat.templatebrains.regdirs=union(  
 getOption('nat.templatebrains.regdirs'), "/my/new/path"))  
# NB after mucking around with paths manually you must also manually update  
# the cache so that new registrations are actually used.  
nat.templatebrains:::reset_cache()  
  
## same, but override any built-in registration by putting the new path  
# at the first position in the search list  
options(nat.templatebrains.regdirs=union("/my/new/path"),  
 getOption('nat.templatebrains.regdirs'))  
  
## End(Not run)
```

add_reclist

Add reglist object describing a bridging/mirroring registration

Description

By specifying either `reference`, `sample` or `mirror` arguments, you can add a bridging or mirroring registration, respectively, to the list of those in use for `xform_brain` and `mirror_brain`.

Usage

```
add_reclist(x, reference = NULL, sample = NULL, mirror = NULL,  
           temp = TRUE, ...)
```

Arguments

x	A single <code>reglist</code> object (which)
reference, sample	The reference and sample brains (in character or templatebrain form) for a bridging registration.
mirror	The reference brain (in character or templatebrain form) for a mirroring registration.
temp	Whether to store the on disk representation in a session-specific temporary folder (that will be removed when R closes). Defaults to TRUE.
...	Additional arguments passed to <code>saveRDS</code> e.g. to control compression when the reglist object is saved to disk.

See Also

`add_reg_folders`

Examples

```
## Not run:
library(nat.flybrains)
# mirroring registration for a specific template brain object
add_reglist(mirroring, mirror=JFRC2013)
# equivalent but without needing to construct the template
add_reglist(mirroring, mirror="JFRC2013")

# add a bridging registration between two brains
add_reglist(bridging, reference=JFRC2, sample=JFRC2013)

## End(Not run)
```

`add_reg_folders` *Set or list local folders containing registrations for nat.templatebrains*

Description

`add_reg_folders` sets options('nat.templatebrains.regdirs') appropriately so that registrations can be found by e.g. `xform_brain`.

`extra_reg_folders` lists extra registration folders present in standard location

Usage

```
add_reg_folders(dir = extra_reg_folders(), first = TRUE)

extra_reg_folders(full.names = TRUE)
```

Arguments

<code>dir</code>	Path to one or more folders containing registrations. Default value will scan for registration folders in a standard location. (Please see Details and File layout sections)
<code>first</code>	Whether the new folder should be added to the start (default) or end of the search list.
<code>full.names</code>	Whether to list full path to registration folders

Details

When `dir` is unset then it will default to the value of `extra_reg_folders()` i.e. any folders / cloned repositories in the standard location

File layout

You must pass a folder containing one or more registrations, not the registration folder itself. So if you have this situation on disk

- `myregistrations/`
- `myregistrations/reg1.list`
- `myregistrations/reg2.list`

you should write `add_reg_folders("/path/to/myregistrations")`

Examples

```
## Not run:
add_reg_folders("myextraregistrations")

## End(Not run)
# adding a non-existent folder will generate an error
tools:::assertError(add_reg_folders(tempfile()))
```

`allreg_dataframe` *Make data.frame with details of all registrations*

Description

Make data.frame with details of all registrations

Usage

```
allreg_dataframe(regdirs = getOption("nat.templatebrains.regdirs"))
```

Arguments

<code>regdirs</code>	Character vector of directories to search for registrations (see details)
----------------------	---

Details

by default `regdirs` is set to `getOption('nat.templatebrains.regdirs')`

Value

`data.frame` with one row for each observed registration and columns

- `path`
- `name`
- `dup`
- `bridge`
- `reference`
- `sample`

If there are no registrations, there will be a `data.frame` with 0 rows and these columns.

Examples

```
## Not run:
allreg_dataframe()

## End(Not run)
```

`as.templatebrain` *Use image file or other object to initialise template brain*

Description

Use image file or other object to initialise template brain

Usage

```
as.templatebrain(x, ...)

## S3 method for class 'character'
as.templatebrain(x, ...)

## S3 method for class 'im3d'
as.templatebrain(x, regName = NULL, name = regName, ...)
```

Arguments

- | | |
|----------------------------|---|
| <code>x</code> | object used to construct the <code>templatebrain</code> , either a character vector with the path to a file or an <code>im3d</code> object. |
| <code>...</code> | additional named arguments passed to methods and then on to <code>templatebrain</code> that will be added as fields to the <code>templatebrain</code> object. |
| <code>name, regName</code> | name and short name of the template brain. Will use the filename (minus final extension) by default for both fields. |

Details

`as.templatebrain` can extract the key fields defining an template space from an image file. This is generally a much more convenient approach to defining a `templatebrain` object than specifying all fields by hand.

Value

A list with class `templatebrain`

See Also

[templatebrain](#), [im3d](#)

Examples

```
# Make templatebrain object using image info from the template brain NRRD file
nhdr=system.file('images','FCWB.nhdr', package='nat.templatebrains')
as.templatebrain(nhdr, name = "FlyCircuit Whole Brain")
```

bridging_graph

Make or query connected graph of bridging registrations

Description

These functions are designed for expert use. In general it is recommended to use `xform_brain`.
`bridging_graph` creates an `igraph::graph` representing all known template brains (vertices) and the bridging registrations connecting them (edges).
`shortest_bridging_seq` finds the shortest bridging sequence on a graph of all available bridging registrations, subject to constraints defined by graph connectivity and the `reciprocal` parameter.

Usage

```
bridging_graph(regdirs =getOption("nat.templatebrains.regdirs"),
               reciprocal = NA)

shortest_bridging_seq(sample, reference, checkboth = TRUE,
                      imagedata = FALSE, reciprocal = NA, ...)
```

Arguments

<code>regdirs</code>	Character vector of directories to search for registrations (see details)
<code>reciprocal</code>	Sets the weight of reciprocal edges in the graph (and thereby whether inverse registrations will be considered).
<code>sample</code>	Source template brain (e.g. IS2) that data is currently in.
<code>reference</code>	Target template brain (e.g. IS2) that data should be transformed into.
<code>checkboth</code>	When TRUE will look for registrations in both directions. See details.

`imagedata` Whether `x` should be treated as image data (presently only supported as a file on disk) or 3D object vertices - see details.
`...` extra arguments to pass to [xform](#).

Details

When `reciprocal != NA` we create a graph where each forward transformation is matched by a corresponding inverse transformation with the specified edge weight. The edge weight for forward transforms will always be 1.0.

By default `regdirs` is set to `getOption('nat.templatebrains.regdirs')`

See Also

[allreg_dataframe](#)

Examples

```
## Not run:
plot(bridging_graph(reciprocal=3), vertex.size=25)
# the same including
plot(bridging_graph(), vertex.size=25)

## End(Not run)
## Not run:
shortest_bridging_seq(FCWB, IS2)
# or
shortest_bridging_seq('FCWB', 'IS2')

## End(Not run)
```

`bridging_sequence` *Find sequence of one or more bridging registrations*

Description

This function is primarily intended for developer use (it is used inside `xform_brain`) but may be useful for end users.

Usage

```
bridging_sequence(sample, reference, via = NULL, imagedata = FALSE,
checkboth = !imagedata, mustWork = FALSE)
```

Arguments

sample	Source template brain (e.g. IS2) that data is currently in.
reference	Target template brain (e.g. IS2) that data should be transformed into.
via	optional intermediate brain to use when there is no direct bridging registration.
imagedata	Whether x should be treated as image data (presently only supported as a file on disk) or 3D object vertices - see details.
checkbox	whether to look for registrations in both directions. The default (checkbox=FALSE) will only return registrations in the forward direction (see details).
mustWork	whether to error out if appropriate registrations are not found.

Details

When checkbox=FALSE, only registrations that can be directly used to map image data from sample to reference are returned. When working with 3D points, use checkbox=TRUE. Note that all possible directories will first be scanned for registrations in the preferred direction and then res-scanned for the opposite direction if nothing is found.

Registration direction

When mapping points from JFRC2 -> IS2 -> FCWB (i.e. sample=JFRC2, via=IS2, ref=FCWB) the command line passed to CMTK's streamxform should look like: streamxform -- JFRC2_IS2.list --inverse FCWB_IS2.list However when mapping image data the command line for CMTK's reformatx should look like: reformatx -o out.nrrd --floating JFRC2.nrrd FCWB.nrrd FCWB_IS2.list --inverse JFRC2_IS2.list bridging_sequence produces output like
list(JFRC2 = structure(

```
"/GD/dev/R/nat.flybrains/inst/extdata/bridgingregistrations/JFRC2_IS2.list",
  swap = TRUE),
  IS2 = "/GD/dev/R/nat.flybrains/inst/extdata/bridgingregistrations/FCWB_IS2.list")
```

in these circumstances, which xformpoints.cmtkreg turns into "- JFRC2_IS2.list --inverse FCWB_IS2.list".

Examples

```
## Not run:
bridging_sequence(sample=JFRC2, ref=FCWB, checkbox = T)
bridging_sequence(sample=JFRC2, via=IS2, ref=FCWB, checkbox = T)

## End(Not run)
```

Description

Display an image slice in 3D

Usage

```
display_slice(brain, slice, ...)
```

Arguments

<code>brain</code>	template brain (e.g. IS2) of the slice.
<code>slice</code>	Path to PNG image containing slice to display.
<code>...</code>	extra arguments to pass to persp3d .

<code>download_reg_repo</code>	<i>Download and register git repository containing registrations</i>
--------------------------------	--

Description

Note that these extra registrations will be downloaded to a standard location on your hard drive that will be used for one session to the next. See examples and [local_reg_dir_for_url](#).

Usage

```
download_reg_repo(url, localdir = NULL, ...)
```

Arguments

<code>url</code>	Location of one or more remote git repositories. Can accept partial github specifications of the form "<user>/<repo>".
<code>localdir</code>	Full path to local checkout location of git repository. When <code>localdir=NULL</code> , the default, a sensible location is chosen using the <code>rappdirs</code> function.
<code>...</code>	additional arguments passed to <code>git2r::clone</code> e.g. credentials for private repo.

See Also

[add_reg_folders](#), [local_reg_dir_for_url](#), [git2r::clone](#)
[update_reg_repos](#)

Examples

```
## find the root location of all registration directories
local_reg_dir_for_url()
## Not run:
## Add the two main jefferislab bridging and mirroring registration
# collections for Drosophila brains from github.com.
download_reg_repo("jefferislab/BridgingRegistrations")
download_reg_repo("jefferislab/MirrorRegistrations")

## update all current registration repositories
update_reg_repos()

## End(Not run)
```

FCWB.demo

Sample template brain: FlyCircuit Whole Brain

Description

This is a sample template brain for testing purposes which is equivalent to the FCWB template brain defined by the `nat.flybrains`, which should be considered the canonical version.

`local_reg_dir_for_url` *Standard local checkout location for extra registration directories*

Description

Standard local checkout location for extra registration directories

Usage

```
local_reg_dir_for_url(url = NULL)
```

Arguments

<code>url</code>	Character vector containing a url. When <code>url=NULL</code> defaults to giving the base path.
------------------	---

Details

When called without any argument returns the root directory that will be inspected for extra registrations. You can put a sub-folder yourself there manually and then call `add_reg_folders`, but you are much better off in general using `download_reg_repo` to install from a github repository such as this one of ours: [jefferislab/BridgingRegistrations](#)

Note that this folder will always be the same place on a machine i.e. this defines a consistent, persistent location on disk to store data across sessions.

When called with a url, a SHA1 hash will be calculated for the URL and appended to the basepath. This should ensure that locations derived from different URLs do not clash.

See Also

[download_reg_repo](#)

mirror_brain	<i>Mirror 3D object around a given axis, optionally using a warping registration</i>
---------------------	--

Description

Mirror 3D object around a given axis, optionally using a warping registration

Usage

```
mirror_brain(x, brain = regtemplate(x), mirrorAxis = c("X", "Y", "Z"),
             transform = c("warp", "affine", "flip"), ...)
```

Arguments

x	the 3D object to be mirrored.
brain	source template brain (e.g. IS2) that data is in.
mirrorAxis	the axis to mirror (default "X").
transform	whether to use warp (default) or affine component of registration, or simply flip about midplane of axis.
...	extra arguments to pass to mirror .

See Also

[xform_brain](#), [regtemplate](#)

Examples

```
data(FCWB.demo)
# Simple mirror along the x i.e. medio-lateral axis
kcs20.flip=mirror_brain(kcs20, FCWB.demo, transform='flip')

## Full non-rigid mirroring to account for differences in shape/centering of
## template brain.
## Depends on nat.flybrains package and system CMTK installation
## Not run:
library(nat.flybrains)
kcs20.right=mirror_brain(kcs20, FCWB, .progress='text')
plot3d(kcs20, col='red')
plot3d(kcs20.right, col='green')
# include surface plot of brain
plot3d(FCWB)

# Compare simple flip with full mirror
# This template brain is highly symmetric so these are almost identical
clear3d()
plot3d(kcs20.flip, col='blue')
plot3d(kcs20.right, col='green')
```

```

# Convert to JFRC2 and do the same
kcs20.jfrc2=xform_brain(kcs20, sample = FCWB, reference=JFRC2, .progress='text')
kcs20.jfrc2.right=mirror_brain(kcs20.jfrc2, JFRC2, .progress='text')
kcs20.jfrc2.flip=mirror_brain(kcs20.jfrc2, JFRC2, transform='flip')
clear3d()
# This time there is a bigger difference between the two transformations
plot3d(kcs20.jfrc2.flip, col='blue')
plot3d(kcs20.jfrc2.right, col='green')
# plot mushroom body neuropils as well
plot3d(JFRC2NP.surf, "MB.*_R", alpha=0.3, col='grey')

# Compare Euclidean distance between corresponding points in all neurons
diffs=xyzmatrix(kcs20.jfrc2.flip)-xyzmatrix(kcs20.jfrc2.right)
hist(sqrt(rowSums(diffs^2)), xlab='Distance /microns')

## End(Not run)

```

plot3d.templatebrain *Plot 3D surface of a template brain*

Description

Plot 3D surface of a template brain

Usage

```

## S3 method for class 'templatebrain'
plot3d(x, col = "grey", alpha = 0.3, ...)

```

Arguments

- x the template brain to plot.
- col the color of the surface.
- alpha the alpha value of the surface.
- ... extra arguments to pass to [plot3d](#).

Details

This function will work immediately for the standard [templatebrain](#) defined in the package documentation. If passed an object called e.g. FCWB it expects to find another object named FCWB.surf containing the surface information. If you follow this naming convention for user-defined refbrains it will work for them as well.

regtemplate*Get or set the registration template space in which an object lives***Description**

Get or set the registration template space in which an object lives

Usage

```
regtemplate(x)

regtemplate(x) <- value
```

Arguments

- | | |
|--------------------|--|
| <code>x</code> | The 3D object whose registration space will be set/returned |
| <code>value</code> | The registration template brain (either a character vector naming the space or a templatebrain object) |

Details

In order to facilitate transformations between objects in defined anatomical spaces these functions allow the registration template for an object to be specified. Most of the time you will not need to use these functions manually since the appropriate space will be set by the function `xform_brain` and friends.

Value

Either a `templatebrain` object or the newly tagged object

Examples

```
## Not run:
library(nat.flybrains)
kcs3=kcs20[1:3]
regtemplate(kcs3)=FCWB
regtemplate(kcs3)

kcs3m=mirror_brain(kcs3, brain=regtemplate(kcs20))
plot3d(kcs3, col='red')
plot3d(kcs3m, col='green')

## End(Not run)
```

templatebrain*Construct templatebrain object for an image registration template*

Description

templatebrain objects encapsulate key information for the reference brain in an image registration. Usually this will be a standard template brain used for many registrations. **It will normally be much more convenient to use `as.templatebrain` methods to convert an image file or an im3d object into a templatebrain.**

Usage

```
templatebrain(name, regName = name, type = NULL, sex = NULL,  
             dims = NULL, BoundingBox = NULL, voxdims = NULL, units = NULL,  
             description = NULL, doi = NULL, ...)
```

Arguments

<code>name</code>	the full name of the template.
<code>regName</code>	the short name. This will be the stem used to prefix registrations (e.g. JFRC2_someimage.list) for this template brain and likely also the stem of the template brain image (e.g. JFRC2.nrrd).
<code>type</code>	one of <code>c('single brain', 'average')</code> , indicating whether the template brain has been created from just one image, or is the average of multiple images.
<code>sex</code>	the sex of the template brain. For templates with <code>type=='average'</code> , the possibility of <code>sex='intersex'</code> exists.
<code>dims</code>	dimensions of the image (number of voxels).
<code>BoundingBox</code>	physical dimensions of the image (see boundingbox).
<code>voxdims</code>	physical spacing between voxels.
<code>units</code>	units of physical measurements (e.g. microns).
<code>description</code>	details of the template.
<code>doi</code>	a DOI for the original template brain image.
<code>...</code>	additional named arguments that will be added as fields to the templatebrain object.

Details

A variety of methods are available to work on templatebrain objects. See [templatebrain-meths](#) for basic methods. The two main functions that are availavle for using template brains are [xform_brain](#) and [mirror_brain](#).

templatebrain objects are only useful for transformation processes when the BoundingBox is specified to define the physical extent of the volume. We use the definition of the Amira 3D visualisation and analysis software. This corresponds to the `node centers` option in the [NRRD format](#). The bounding box can be obtained from NRRD or AmiraMesh format files. See [boundingbox](#) for details.

Value

A list with class `templatebrain`.

See Also

[as.templatebrain](#), [templatebrain-meths](#), [xform_brain](#), [mirror_brain](#).

`templatebrain-meths` *Template brain methods*

Description

`is.templatebrain` tests if object is of class `templatebrain`
`as.character.templatebrain` converts template brain to character vector representation (normally used to extract the short name i.e. `regName`).
`print.templatebrain` prints `templatebrain` information in human-readable form
`as.im3d` converts a template brain to a `nat::im3d` object; this is probably useful for developers.
`origin` extracts the space origin of a `templatebrain` object.
`dim` extracts the dimensions (in number of pixels) of the image associated with a `templatebrain` object.
`voxdims` extracts the dimensions (in calibrated spatial units, e.g. microns) of voxels in the image associated with a `templatebrain` object.
`boundingbox` extracts the boundingbox (in calibrated spatial units, e.g. microns) of the image associated with a `templatebrain` object. See [boundingbox](#) for details.

Usage

```
is.templatebrain(x)

## S3 method for class 'templatebrain'
as.character(x, field = c("regName", "name"), ...)

## S3 method for class 'templatebrain'
print(x, ...)

## S3 method for class 'templatebrain'
as.im3d(x, ...)

## S3 method for class 'templatebrain'
origin(x, ...)

## S3 method for class 'templatebrain'
dim(x, ...)
```

```
## S3 method for class 'templatebrain'
voxdims(x, ...)

## S3 method for class 'templatebrain'
boundingbox(x, ...)
```

Arguments

- x an object (usually a `templatebrain`).
- field which field to use (defaults to '`regName`').
- ... additional arguments for methods.

Value

A logical indicating whether or not the object is a `templatebrain`.

Character vector.

See Also

[im3d](#)
[origin](#)
[voxdims](#)
[boundingbox](#)

Examples

```
data(FCWB.demo)
is.templatebrain(FCWB.demo)
origin(FCWB.demo)
dim(FCWB.demo)
voxdims(FCWB.demo)
boundingbox(FCWB.demo)
# print method
FCWB.demo
```

`update_reg_repos` *Update local copy of git repository containing registrations*

Description

When `x=NULL` all repositories listed in `options(nat.templatebrains.regdirs)` are checked to see if they are git repositories and, if yes, they are pulled to update.

Usage

```
update_reg_repos(x = NULL)
```

Arguments

- x Path to local checkout of a registration git repository. See details for meaning of default.

See Also

[download_reg_repo](#)

xform_brain

Transform 3D object between template brains

Description

Transform 3D object between template brains

Usage

```
xform_brain(x, sample = regtemplate(x), reference, via = NULL,
            imagedata = is.character(x), checkboth = NULL, ...)
```

Arguments

- | | |
|-----------|---|
| x | the 3D object to be transformed |
| sample | Source template brain (e.g. IS2) that data is currently in. |
| reference | Target template brain (e.g. IS2) that data should be transformed into. |
| via | optional intermediate brain to use when there is no direct bridging registration. |
| imagedata | Whether x should be treated as image data (presently only supported as a file on disk) or 3D object vertices - see details. |
| checkboth | When TRUE will look for registrations in both directions. See details. |
| ... | extra arguments to pass to xform . |

Details

NB the sample, reference and via brains can either be `templatebrain` objects or a character string containing the short name of the template e.g. "IS2".

The significance of the imagedata and checkboth arguments is that CMTK registrations are not directly invertible although they can be numerically inverted in most cases (unless there are regions where folding occurred). For image data, numerical inversion is *much* slower.

You can control whether you want to allow inverse registrations manually by setting checkboth explicitly. Otherwise when `checkboth=NULL` the following default behaviour occurs:

- when `via=NULL` `checkboth=T` but a warning will be given if an inversion must be used.
- when `via` is specified then `checkboth=T` but a warning will be given if an inversion must be used.

See Also

[mirror_brain](#), [regtemplate](#)

Examples

```
## depends on nat.flybrains package and system CMTK installation
## Not run:
## reformat neurons
##
library(nat.flybrains)
# Plot Kenyon cells in their original FCWB template brain
nopen3d()
plot3d(kcs20)
plot3d(FCWB)
# Convert to JFRC2 template brain
kcs20.jfrc2=xform_brain(kcs20, sample = FCWB, reference=JFRC2, .progress='text')
# now plot in the new JFRC2 space
nopen3d()
plot3d(kcs20.jfrc2)
plot3d(JFRC2)
# compare with the untransformed neurons
plot3d(kcs20)
# plot with neuropil sub regions for the left mushroom body
clear3d()
plot3d(kcs20.jfrc2)
# nb "MB.*_L" is a regular expression
plot3d(JFRC2NP.surf, "MB.*_L", alpha=0.3)
# compare with originals - bring registration is no perfect in peduncle
nopen3d()
plot3d(kcs20)
plot3d(FCWBNP.surf, "MB.*_L", alpha=0.3)

## reformat image examples
# see ?cmtk.reformatx for details of all additional arguments
xform_brain('in.nrrd', sample=FCWB, ref=JFRC2, output='out.nrrd', Verbose=F)

# use nearest neighbour interpolation for label field
xform_brain('labels.nrrd', sample=FCWB, ref=JFRC2, output='out.nrrd', interpolation='nn')

# use binary mask to restrict (and speed up) reformatting
xform_brain('in.nrrd', sample=FCWB, ref=JFRC2, output='out.nrrd', mask='neuropil.nrrd')

## End(Not run)
```

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