# Package 'mgm'

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# **Description**

Estimation of time-varying Mixed Graphical models and mixed VAR models via elastic-net regularized neighborhood regression.

## **Details**

Package: mgm
Type: Package
Version: 1.2-10
Date: 2020-06-27
License: GPL-2

# Author(s)

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#### References

Haslbeck, J. M. B., & Waldorp, L. J. (2020). mgm: Estimating time-varying Mixed Graphical Models in high-dimensional Data. Journal of Statistical Software, 93(8), pp. 1-46. DOI: 10.18637/jss.v093.i08

Loh, P. L., & Wainwright, M. J. (2013). Structure estimation for discrete graphical models: Generalized covariance matrices and their inverses. The Annals of Statistics, 41(6), 3022-3049.

Yang, E., Baker, Y., Ravikumar, P., Allen, G., & Liu, Z. (2014). Mixed graphical models via exponential families. In Proceedings of the Seventeenth International Conference on Artificial Intelligence and Statistics (pp. 1042-1050).

bwSelect 3

| bwSelect | Select optimal bandwidth for time-varying MGMs and mVAR Models |
|----------|--|
|          | , , ,  |

# **Description**

Selects the bandwidth parameter with lowest out of sample prediction error for MGMs and mVAR Models

# Usage

#### **Arguments**

data A n x p data matrix.

type p vector indicating the type of variable for each column in data. "g" for Gaus-

sian, "p" for Poisson, "c" for categorical.

level p vector indicating the number of categories of each variable. For continuous

variables set to 1.

bwSeq A sequence with candidate bandwidth values (0, s] with s < Inf. Note that the

bandwidth is applied relative to the unit time interval [0,1] and hence a banwidth of > 2 corresponds roughly to equal weights for all time points and hence gives

similar estimates as the stationary model estimated via mvar().

bwFolds The number of folds (see details below).

bwFoldsize The size of each fold (see details below).

modeltype If modeltype = "mvar" model, the optimal bandwidth parameter for a tvmvar()

model is selected. If modeltype = "mgm" model, the optimal bandwidth parameter for a tvmgm() model is selected. Additional arguments to tvmvar() or

tvmgm() can be passed via the ... argument.

pbar If TRUE a progress bar is shown. Defaults to pbar = "TRUE".

... Arguments passed to tvmgm or tvmvar.

#### Details

Performs a cross-validation scheme that is specified by bwFolds and bwFoldsize. In the first fold, the test set is defined by an equally spaced sequence between [1, n - bwFolds] of length bwFoldsize. In the second fold, the test set is defined by an equally spaced sequence between [2, n - bwFolds + 1] of length bwFoldsize, etc. . Note that if bwFoldsize = n / bwFolds, this procedure is equal to bwFolds-fold cross validation. However, full cross validation is computationally very expensive and a single split in test/training set by setting bwFolds = 1 is sufficient in many situations. The procedure selects the bandwidth with the lowest prediction error, averaged over variables and time points in the test set.

bwSelect computes the absolute error (continuous) or 0/1-loss (categorical) for each time point in the test set defined by bwFoldsize as described in the previous paragraph for every fold specified

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in bwFolds, separately for each variable. The computed errors are returned in different levels of aggregation in the output list (see below). Note that continuous variables are scaled (centered and divided by their standard deviation), hence the absolute error and 0/1-loss are roughly on the scale scale.

Note that selecting the bandwidth with the EBIC is no alternative. This is because the EBIC always selects the intercept model with the lowest bandwidth. The reason is that the unregularized intercept closely models the noise in the data and hence the penalty sets all other parameters to zero. This problem is solved by using out of sample prediction error in the cross validation scheme.

## Value

The function returns a list with the following entries:

| call           | Contains all provided input arguments. If saveData = TRUE, it also contains the data.   |
|----------------|---|
| bwModels       | Contains the models estimated at the time points in the tests set. For details see $tvmvar$ or $tvmgm$ .  |
| fullErrorFolds | List with number of entries equal to the length of bwSeq entries. Each entry contains a list with bwFolds entries. Each of those entries contains a bwFoldsize times p matrix of out of sample prediction errors. |
| fullError      | The same as fullErrorFolds but pooled over folds.   |
| meanError      | List with number of entries equal to the length of bwSeq entries. Each entry contains the average prediction error over variables and time points in the test set.  |
| testsets       | List with bwFolds entries, which contain the rows of the test sample for each fold.   |
| zeroweights    | List with bwFolds entries, which contains the observation weights used to fit the model at the bwFoldsize time points.  |

#### Author(s)

Jonas Haslbeck <jonashaslbeck@gmail.com>

#### References

Barber, R. F., & Drton, M. (2015). High-dimensional Ising model selection with Bayesian information criteria. Electronic Journal of Statistics, 9(1), 567-607.

Foygel, R., & Drton, M. (2010). Extended Bayesian information criteria for Gaussian graphical models. In Advances in neural information processing systems (pp. 604-612).

Haslbeck, J. M. B., & Waldorp, L. J. (2020). mgm: Estimating time-varying Mixed Graphical Models in high-dimensional Data. Journal of Statistical Software, 93(8), pp. 1-46. DOI: 10.18637/jss.v093.i08

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## **Examples**

```
## Not run:
## A) bwSelect for tvmgm()
# A.1) Generate noise data set
p <- 5
n <- 100
data_n <- matrix(rnorm(p*n), nrow=100)</pre>
head(data_n)
type <- c("c", "c", rep("g", 3))
level <- c(2, 2, 1, 1, 1)
x1 <- data_n[,1]</pre>
x2 <- data_n[,2]</pre>
data_n[x1>0,1] <- 1
data_n[x1<0,1] <- 0
data_n[x2>0,2] <- 1
data_n[x2<0,2] <- 0
head(data_n)
# A.2) Estimate optimal bandwidth parameter
bwobj_mgm <- bwSelect(data = data_n,</pre>
                       type = type,
                       level = level,
                       bwSeq = seq(0.05, 1, length=3),
                       bwFolds = 1,
                       bwFoldsize = 3,
                       modeltype = "mgm",
                       k = 3,
                       pbar = TRUE,
                       overparameterize = TRUE)
print.mgm(bwobj_mgm)
## B) bwSelect for tvmVar()
# B.1) Generate noise data set
p <- 5
n <- 100
data_n <- matrix(rnorm(p*n), nrow=100)</pre>
head(data_n)
type <- c("c", "c", rep("g", 3))
```

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```
level \leftarrow c(2, 2, 1, 1, 1)
x1 <- data_n[,1]</pre>
x2 <- data_n[,2]
data_n[x1>0,1] <- 1
data_n[x1<0,1] <- 0
data_n[x2>0,2] <- 1
data_n[x2<0,2] <- 0
head(data_n)
# B.2) Estimate optimal bandwidth parameter
bwobj_mvar <- bwSelect(data = data_n,</pre>
                        type = type,
                        level = level,
                        bwSeq = seq(0.05, 1, length=3),
                        bwFolds = 1,
                        bwFoldsize = 3,
                        modeltype = "mvar",
                        lags = 1:3,
                        pbar = TRUE,
                        overparameterize = TRUE)
print.mgm(bwobj_mvar)
# For more examples see https://github.com/jmbh/mgmDocumentation
## End(Not run)
```

condition

Computes mgm object conditional on a set of variables

## **Description**

The function takes an mgm object and a set of variables fixed to given values as input and returns the conditional mgm object.

## Usage

```
condition(object, values)
```

# **Arguments**

object

An mgm object, the output of the mgm() function.

values

A list, where the entry name indicates the column number of the variable that should be fixed, and the entry value indicates the value to which the corresponding variable should be fixed. See below for an example.

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## **Details**

The new conditional object still contains the variables that were fixed, however, they are not related to any of the random variables anymore. We kept the variables in the object to avoid confusion with variable labels and plotting. Also note that mgm() by default scales all Gaussian variables to mean=0, sd=1. Thus, fixed values should be selected based on the scaled version of variables.

## Value

The function returns an mgm object that is conditional on the provided values. The new mgm object can again be used as input in predict(), print(), showInteraction(), etc..

#### Author(s)

Jonas Haslbeck <jonashaslbeck@gmail.com>

## References

Haslbeck, J., & Waldorp, L. J. (2019). mgm: Estimating time-varying mixed graphical models in high-dimensional data. arXiv preprint arXiv:1510.06871.

#### See Also

mgm

# **Examples**

```
## Not run:
# --- Create Mixture of two Gaussians ---
set.seed(1)
n <- 500
library(MASS)
# Component A
Sigma_a <- diag(2)
Sigma_a[1, 2] \leftarrow Sigma_a[2, 1] \leftarrow .5
Xa \leftarrow mvrnorm(n = n, mu = rep(0, 2), Sigma = Sigma_a)
# Component B
Sigma_b <- diag(2)
Sigma_b[1, 2] <- Sigma_b[2, 1] <- 0
Xb \leftarrow mvrnorm(n = n, mu = rep(0, 2), Sigma = Sigma_b)
data <- as.data.frame(cbind(rbind(Xa, Xb), c(rep(0, n), rep(1, n))))</pre>
colnames(data) <- c("x1", "x2", "x3")</pre>
# --- Fit MGM ---
```

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```
# with mgm
mgm_obj <- mgm(data = data,</pre>
                type = c("g", "g", "c"),
                level = c(1, 1, 2),
               moderator = c(3),
               lambdaSel = "EBIC")
# --- Condition on / fix values of variable 3 ---
# Fix x3=0
mgm_obj_x3.0 <- condition(object = mgm_obj,</pre>
                            values = list("3"=0))
mgm_obj_x3.0$pairwise$wadj
# Fix x3=1
mgm_obj_x3.1 <- condition(object = mgm_obj,</pre>
                            values = list("3"=1))
mgm_obj_x3.1$pairwise$wadj
## End(Not run)
```

datasets

Example Datasets in the mgm Package

# Description

The autism dataset (and its short version) are taken from Deserno et al. (2016).

The restingstate fMRI data are taken from Schmittmann et al. (2015).

The gene expression data across the life span of the fruit fly are taken from Gibberd & Nelson (2017), who took a subset of the data first presented by Arbeitman et al. (2002).

The symptom data of the single individual diagnosed with major depression is described in Kossakowski et al. (2017).

The PTSD data is taken from McNally et al. (2015).

The dataset mgm\_data is generated by example code shown in ?mgmsampler, and mvar\_data is generated by example code shown in ?mvarsampler.

The dataset Fried2015 contains 515 cases of the 11 depression symptoms measured by the CES-D and is taken from Fried et al. 2015.

The dataset B5MS contains the mean scores across subscales (48 items each) for the Big Five personality traits. The dataset is taken from the qgraph package (Epskamp, et al., 2012) and was first used in Dolan et al. (2009).

The dataset dataGD contains 4 continuous variables and 3 categorical variables that are generated from a mixed DAG. This dataset is useful to illustrate estimating group differences in MGMs using moderation.

All datasets are loaded automatically. All real data sets come as a list including the data and additional information (names of variables, types of variables, time stamps for time series data, etc.)

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## References

Deserno, M. K., Borsboom, D., Begeer, S., & Geurts, H. M. (2016). Multicausal systems ask for multicausal approaches: A network perspective on subjective well-being in individuals with autism spectrum disorder. Autism.

Dolan, C. V., Oort, F. J., Stoel, R. D., & Wicherts, J. M. (2009). Testing measurement invariance in the target rotated multigroup exploratory factor model. Structural Equation Modeling, 16(2), 295-314.

Epskamp, S., Cramer, A. O., Waldorp, L. J., Schmittmann, V. D., & Borsboom, D. (2012). qgraph: Network visualizations of relationships in psychometric data. Journal of Statistical Software, 48(4), 1-18

Schmittmann, V. D., Jahfari, S., Borsboom, D., Savi, A. O., & Waldorp, L. J. (2015). Making large-scale networks from fMRI data. PloS one, 10(9), e0129074.

Gibberd, A. J., & Nelson, J. D. (2017). Regularized Estimation of Piecewise Constant Gaussian Graphical Models: The Group-Fused Graphical Lasso. Journal of Computational and Graphical Statistics, (just-accepted).

Arbeitman, M. N., Furlong, E. E., Imam, F., Johnson, E., Null, B. H., Baker, B. S., ... & White, K. P. (2002). Gene expression during the life cycle of Drosophila melanogaster. Science, 297(5590), 2270-2275.

Kossakowski, J., Groot, P., Haslbeck, J., Borsboom, D., & Whichers, M. (2017). Data from "Critical Slowing Down as a Personalized Early Warning Signal for Depression". Journal of Open Psychology Data, 5(1).

McNally, R. J., Robinaugh, D. J., Wu, G. W., Wang, L., Deserno, M. K., & Borsboom, D. (2015). Mental disorders as causal systems a network approach to posttraumatic stress disorder. Clinical Psychological Science, 3(6), 836-849.

Fried, E. I., Bockting, C., Arjadi, R., Borsboom, D., Amshoff, M., Cramer, A. O., ... & Stroebe, M. (2015). From loss to loneliness: The relationship between bereavement and depressive symptoms. Journal of abnormal psychology, 124(2), 256.

FactorGraph

Draws a factor graph of a (time-varying) MGM

# Description

Wrapper function around qgraph() that draws factor graphs for (time-varying) MGMs

# Usage

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#### **Arguments**

object The output object of mgm() or tvmgm().

labels A character vector of (variable) node labels.

PairwiseAsEdge If TRUE, pairwise interactions are not displayed as factors but as simple edges

between nodes. Defaults to PairwiseAsEdge = FALSE.

Nodewise If TRUE, the estimates from the individual nodewise regressions are displayed as

a directed edge towards the node on which the respective nodewise regression was performed. This is useful to identify model misspecification (e.g. moderation effects / interaction parameters with largely different values across nodewise

regressions). Defaults to Nodewise = FALSE.

DoNotPlot If DoNotPlot = TRUE no factorgraph is plotted. This way the computed factor

graph can be obtained without plotting. Defaults to DoNotPlot = FALSE.

FactorLabels If FactorLabels = TRUE the factors are labeled by their order. If FactorLabels

= FALSE no label is shown. Defaults to FactorLabels = TRUE.

colors A character vector of colors for nodes and factors. The first color is for variable-

nodes, the second for 2-way interactions, the third for 3-way interactions, etc.

Defaults to colors = c("white", "tomato", "lightblue", "orange").

shapes A character vector of shapes for for nodes and factors. The first shape is for

variable-nodes, the second for 2-way interactions, the third for 3-way interactions, etc. Defaults to shapes = c("circle", "square", "triangle", "diamond").

shapeSizes A numeric vector of length two indicating the size of shapes for nodes and fac-

tors. Defaults to shapeSizes = c(8,4).

estpoint An integer indicating the estimation point to display if the output object of a

time-varying MGM is provided.

negDashed If negDashed = TRUE, edges with negative sign are dashed.

... Arguments passed to qgraph.

#### **Details**

FactorGraph() is a wrapper around qgraph() from the qgraph package. Therefore all arguments of qgraph() are available and can be provided as additional arguments.

To make time-varying factor graphs comparable across estimation points, the factor graph of each estimation point includes all factors that are estimated nonzero at least at one estimation point.

## Value

Plots the factor graph and returns a list including the arguments used to plot the factor graph using qgraph().

Specifically, a list is returned including: graph contains a weighted adjacency matrix of a (bipartide) factor graph. If p is the number of variables and E the number of interactions (factors) in the model, this matrix has dimensions (p+E) x (p+E). The factor graph is furter specified by the following objects: signs is a matrix of the same dimensions as graph that indicates the sign of each interaction, if defined (see pairwise above). edgecolor is a matrix with the same dimension as graph that provides edge colors depending on the sign as above. order is a (p+E) vector indicating the order of interaction. The first p entries are set to zero. qgraph contains the qgraph object created while plotting.

## Author(s)

Jonas Haslbeck <jonashaslbeck@gmail.com>

#### See Also

```
mgm(), tvmgm(), qgraph()
```

## **Examples**

```
## Not run:
# Fit MGM with pairwise & threeway interactions to Autism Dataset
fit_k3 <- mgm(data = autism_data$data,</pre>
              type = autism_data$type,
              level = autism_data$lev,
              k = 3,
              overparameterize = TRUE,
              lambdaSel = "EBIC",
              lambdaGam = .5)
# List of estimated interactions
fit_k3$interactions$indicator
FactorGraph(object = fit_k3,
            PairwiseAsEdge = FALSE,
            DoNotPlot = FALSE,
            labels = 1:7,
            layout="circle")
# For more examples see https://github.com/jmbh/mgmDocumentation
## End(Not run)
```

mgm

Estimating Mixed Graphical Models

# **Description**

Function to estimate k-degree Mixed Graphical Models via nodewise regression.

# Usage

```
mgm(data, type, level, lambdaSeq, lambdaSel, lambdaFolds,
    lambdaGam, alphaSeq, alphaSel, alphaFolds, alphaGam,
    k, moderators, ruleReg, weights, threshold, method,
    binarySign, scale, verbatim, pbar, warnings, saveModels,
    saveData, overparameterize, thresholdCat, signInfo, ...)
```

#### **Arguments**

data n x p data matrix

type p vector indicating the type of variable for each column in data. "g" for Gaus-

sian, "p" for Poisson, "c" for categorical.

level p vector indicating the number of categories of each variable. For continuous

variables set to 1.

lambdaSeq A sequence of lambdas that should be searched (see also lambdaSel). Defaults

to NULL, which uses the glmnet default to select a lambda candidate sequence

(recommended). See ?glmnet for details.

lambdaSel Specifies the procedure for selecting the tuning parameter controlling the Lq-

penalization. The two options are cross validation "CV" and the Extended Bayesian Information Criterion (EBIC) "EBIC". The EBIC performs well in selecting sparse graphs (see Barber and Drton, 2010 and Foygel and Drton, 2014). Note that when also searching the alpha parameter in the elastic net penalty, cross validation should be preferred, as the parameter vector will not necessarily be sparse anymore. The EBIC tends to be a bit more conservative than CV (see Haslbeck and Waldorp, 2016). CV can sometimes not be performed with categorical variables, because glmnet requires at least 2 events of each category of each categorical variable in each training-fold. Defaults to lambdaSel = "CV".

lambdaFolds Number of folds in cross validation if lambdaSel = "CV".

lambdaGam Hyperparameter gamma in the EBIC if lambdaSel = "EBIC". Defaults to lambdaGam

= .25.

alphaSeq A sequence of alpha parameters for the elastic net penality in [0,1] that should

be searched (see also alphaSel). Defaults to alphaSeq = 1, which means that the lasso is being used. alphaSeq =  $\emptyset$  corresponds to an L2-penalty (Ridge re-

gression). For details see Friedman, Hastie and Tibshirani (2010).

alphaSel Specifies the procedure for selecting the alpha parameter in the elastic net penalty.

The two options are cross validation "CV" and the Extended Bayesian Information Criterion (EBIC) "EBIC". The EBIC performs well in selecting sparse graphs (see Barber and Drton, 2010 and Foygel and Drton, 2014). Note that when also searching the alpha parameter in the elastic net penalty, cross validation should be preferred, as the parameter vector will not necessarily be sparse anymore. The EBIC tends to be a bit more conservative than CV (see Haslbeck and Waldorp, 2016). CV can sometimes not be performed with categorical variables, because glmnet requires at least 2 events of each category of each cate

gorical variable in each training-fold. Defaults to alphaSel = "CV".

alphaFolds Number of folds in cross validation if alphaSel = "CV".

alphaGam Hyperparameter gamma in the EBIC if alphaSel = "EBIC". Defaults to alphaGam

= .25.

k Order up until including which interactions are included in the model. k = 2 means that all pairwise interactions are included, k = 3 means that all pairwise

and all three-way interactions are included, etc. In previous versions of mgm the order of interactions was specified by the parameter d, the largest size or a

neighborhood. Note that k = d + 1.

moderators

Integer vector with elements in 1:p, specifying moderation effects to be included in the model. For instance, moderators = c(4) includes all linear moderation effects of variable 4. This is equivalent to including all 3-way interactions that include variable 4. Note that moderators = 1:p gives the same model as setting k = 3 (see previous argument). Alternatively, a specific set of moderators can be specified via a M x 3 matrix, where M is the number of moderation effects. For example, moderators = matrix(1:3, nrow=1) adds (only) the 3-way interaction 1-2-3 to the model.

ruleReg

Rule used to combine estimates from neighborhood regression. E.g. for pairwise interactions, two estimates (one from regressing A on B and one from B on A) have to combined in one edge parameter. ruleReg = "AND" requires all estimates to be nonzero in order to set the edge to be present. ruleReg = "OR" requires at least one estimate to be nonzero in order to set the edge to be present. For higher order interactions, k estimate have to be combined with this rule.

weights

A n vector with weights for observations.

threshold

A threshold below which edge-weights are put to zero. This is done in order to guarantee a lower bound on the false-positive rate. threshold = "LW" refers to the threshold in Loh and Wainwright (2013), which was used in all previous versions of mgm. threshold = "HW" refers to the threshold in Haslbeck and Waldorp (2016). If threshold = "none" no thresholding is applied. Defaults to threshold = "LW".

method

Estimation method, currently only method = "glm".

binarySign

If binarySign = TRUE, a sign for the interaction within binary nodes and between binary and continuous nodes is provided in the output. Note that in this case the two categories of the binary variables have to be coded in 0,1. This is to ensure that the interpretation of the sign is unambigous: a positive sign of a parameter means that increasing the associated predictor results in a higher probability for category 1.

scale

If scale = TRUE, all Gaussian nodes (specified by "g" in type) are centered and divided by their standard deviation. Scaling is recommended, because otherwise the penalization of a parameter depends on the variance of the associated predictor. Defaults to scale = TRUE.

verbatim

If verbatim = TRUE, no warnings and no progress bar is shown. Defaults to verbatim = FALSE.

pbar

If pbar = TRUE, a progress bar is shown. Defaults to pbar = TRUE.

warnings

If warnings = TRUE, no warnigns are returned. Defaults to warnings = FALSE.

saveModels

If saveModels = FALSE, only information about the weighted adjacency matrix, and if k > 2 about the factor graph is provided in the output list. If saveModels = TRUE, all fitted parameters are additionally returned.

saveData

If saveData = TRUE, the data is saved in the output list. Defaults to saveData = FALSE.

overparameterize

If overparameterize = TRUE, mgm() uses over-parameterized design-matrices for each neighborhood regression; this means that an interaction between two categorical variables with m and s categories is parameterized by m\*s parameters. If overparameterize = FALSE the standard parameterization (in glmnet)

with m\*(s-1) parameters is used, where the first category of the predicting variable serves as reference category. If all variables are continuous both parameterizations are the same. Note that the default is set to overparameterize = FALSE, to be consistent with the previous mgm versions. However when the goal is to seperate pairwise interactions from 3-way (or higher) interactions, then the overparameterized version is advantageous. See the examples below for an illustration. Note that we can estimate the model despite the colinear columns in the design matrix because we use penalized regression.

thresholdCat

If thresholdCat = FALSE, the thresholds of categorical variables are set to zero. Defaults to thresholdCat = TRUE for which the thresholds are esimated.

signInfo

If signInfo = TRUE, a message is shown in the console, indicating that the sign

of estimates is stored separately. Defaults to signInfo = TRUE.

... Additional arguments.

#### **Details**

mgm() estimates an exponential mixed graphical model as introduced in Yang and colleagies (2014). Note that MGMs are not normalizable for all parameter values. See Chen, Witten & Shojaie (2015) for an overview of when pairwise MGMs are normalizable. To our best knowledge, for MGMs with interactions of order > 2 that include non-categorical variables, the conditions for normalizablity are unknown.

#### Value

The function returns a list with the following entries:

call

Contains all provided input arguments. If saveData = TRUE, it also contains the data

pairwise

Contains a list with all information about estimated pairwise interactions. wadj contains the p x p weighted adjacency matrix, if p is the number of variables in the network. signs has the same dimensions as wadj and contains the signs for the entries of wadj: 1 indicates a positive sign, -1 a negative sign and 0 an undefined sign. A sign is undefined if an edge is a function of more than one parameter. This is the case for interactions involving a categorical variable with more than 2 categories. edgecolor also has the same dimensions as wadj contains a color for each edge, depending on signs. It is provided for more convenient plotting. If only pairwise interactions are modeled (d = 1), wadj contains all conditional independence relations. The matrices edgecolor\_cb contain a color blind friendly color scheme. edge\_lty contains a matrix with 1s for positive/undefined signs and 2s for negative signes, which can be used as input to the 1ty argument in qgraph() in order to plot edges with negative sign as dashed lines.

interactions

A list with three entries that relate each interaction in the model to all its parameters. This is different to the output provided in factorgraph, where one value is assigned to each interaction. indicator contains a list with k-1 entries, one for each order of modeled interaction, which contain the estimated (nonzero) interactions. weightsAgg contains a list with k-1 entries, which in turn contain R lists, where R is the number of interactions (and rows in the corresponding

list entry inindicator) that were estimated (nonzero) in the given entry. Each of these entries contains the mean of the absolute values of all parameters involved in this interaction. weights has the same structure as weightsAgg, but does contain all parameters involved in the interaction instead of the mean of their absolute values. signs has the same structure as weightsAgg/weights and provides the sign of the interaction, if defined.

intercepts

A list with p entries, which contain the intercept/thresholds for each node in the network. In case a given node is categorical with m categories, there are m thresholds for this variable.

nodemodels

A list with p glmnet() models, from which all above output is computed. Also contains the coefficients models for the selected lambda and the applied tau threshold tau.

## Author(s)

Jonas Haslbeck <jonashaslbeck@gmail.com>

#### References

Barber, R. F., & Drton, M. (2015). High-dimensional Ising model selection with Bayesian information criteria. Electronic Journal of Statistics, 9(1), 567-607.

Chen S, Witten DM & Shojaie (2015). Selection and estimation for mixed graphical models. Biometrika, 102(1), 47.

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Yang, E., Baker, Y., Ravikumar, P., Allen, G. I., & Liu, Z. (2014, April). Mixed Graphical Models via Exponential Families. In AISTATS (Vol. 2012, pp. 1042-1050).

# **Examples**

```
level = autism_data$lev,
              k = 2) # ad most pairwise interacitons
# Weighted adjacency matrix
fit_k2$pairwise$wadj
# Visualize using qgraph()
library(qgraph)
qgraph(fit_k2$pairwise$wadj,
       edge.color = fit_k2$pairwise$edgecolor,
       layout = "spring",
       labels = autism_data$colnames)
# 2) Fit MGM with pairwise & three-way interactions
fit_k3 <- mgm(data = autism_data$data,</pre>
              type = autism_data$type,
              level = autism_data$lev,
              k = 3) # include all interactions up to including order 3
# List of estimated interactions
fit_k3$interactions$indicator
# 3) Plot Factor Graph
FactorGraph(object = fit_k3,
            PairwiseAsEdge = FALSE,
            labels = autism_data$colnames)
# 4) Predict values
pred_obj <- predict(fit_k3, autism_data$data)</pre>
head(pred_obj$predicted) # first six rows of predicted values
pred_obj$errors # Nodewise errors
## Here we illustrate why we need to overparameterize the design matrix to
## recover higher order interactions including categorical variables
# 1) Define Graph (one 3-way interaction between 3 binary variables)
# a) General Graph Info
type = c("c", "c", "c")
level = c(2, 2, 2)
# b) Define Interaction
factors <- list()</pre>
factors[[1]] <- NULL # no pairwise interactions</pre>
factors[[2]] \leftarrow matrix(c(1,2,3), ncol=3, byrow = T) # one 3-way interaction
interactions <- list()</pre>
interactions[[1]] <- NULL</pre>
interactions[[2]] <- vector("list", length = 1)</pre>
# threeway interaction no1
interactions[[2]][[1]] <- array(0, dim = c(level[1], level[2], level[3]))</pre>
theta <- .7
```

```
interactions[[2]][[1]][1, 1, 1] <- theta #weight theta for conf (1,1,1), weight 0 for all others
# c) Define Thresholds
thresholds <- list()</pre>
thresholds[[1]] <- c(0, 0)
thresholds[[2]] <- c(0, 0)
thresholds[[3]] <- c(0, 0)
# 2) Sample from Graph
iter <- 1
set.seed(iter)
N <- 2000
d_iter <- mgmsampler(factors = factors,</pre>
                      interactions = interactions,
                      thresholds = thresholds,
                      type = type,
                      level = level,
                      N = N,
                      nIter = 50,
                      pbar = TRUE)
\# 3.1) Estimate order 3 MGM usind standard parameterization
d_est_stand <- mgm(data = d_iter$data,</pre>
                    type = type,
                    level = level,
                    k = 3,
                    lambdaSel = "CV",
                    ruleReg = "AND",
                    pbar = TRUE,
                    overparameterize = FALSE,
                    signInfo = FALSE)
# We look at the nodewise regression for node 1 (same for all)
coefs_stand <- d_est_stand$nodemodels[[1]]$model</pre>
coefs_stand
# We see that nonzero-zero pattern of parameter vector does not allow us to infer whether
# interactions are present or not
# 3.2) Estimate order 3 MGM usind overparameterization
d_est_over <- mgm(data = d_iter$data,</pre>
                   type = type,
                   level = level,
                   k = 3,
                   lambdaSel = "CV",
                   ruleReg = "AND",
                   pbar = TRUE,
                   overparameterize = TRUE,
                   signInfo = FALSE)
# We look at the nodewise regression for node 1 (same for all)
coefs_over <- d_est_over$nodemodels[[1]]$model</pre>
```

```
coefs_over # recovers exactly the 3-way interaction

# For more examples see https://github.com/jmbh/mgmDocumentation

## End(Not run)
```

mgmsampler

Sample from k-order Mixed Graphical Model

# Description

Generates samples from a k-order Mixed Graphical Model

## Usage

#### **Arguments**

factors

This object indicates which interactions are present in the model. It is a list in which the first entry corresponds to 2-way interactions, the second entry corresponds to 3-way interactions, etc. and the kth entry to the k+1-way interaction. Each entry contains a matrix with dimensions order x number of interaction of given order. Each row in the matrix indicates an interaction, e.g. (1, 3, 7, 9) in the matrix in list entry three indicates a 4-way interaction between the variables 1, 3, 7 and 9.

interactions

This object specifies the parameters associated to the interactions specified in factors. Corresponding to the structure in factors, this object is a list, where the kth entry corresponds to k+1-way interactions. Each list entry contains another list, with entries equal to the number of rows in the corresponding matrix in factors. Each of these list entries (for a fixed k) contains a k-dimensional array that specifies the parameters of the given k-order interaction. For instance, if we have a 3-way interaction (1, 2, 3) and all variables are binary, we have a 2 x 2 x 2 array specifying the parameters for each of the  $2^{\Lambda}3 = 8$  possible configurations. If all variables are continuous, we have a 1 x 1 x 1 array, so the interaction is specified by a single parameter. See the examples below for an illustration.

thresholds A list with p entries corresponding to p variables in the model. Each entry

contains a vector indicating the threshold for each category (for categorical variables) or a numeric value indicating the threshold/intercept (for continuous variables)

ables).

sds A numeric vector with p entries, specifying the variances of Gaussian variables.

If variables 6 and 13 are Gaussians, then the corresponding entries of sds have

to contain the corresponding variances. Other entries are ignored.

type p character vector indicating the type of variable for each column in data. "g"

for Gaussian, "p" for Poisson, "c" of each variable.

level p integer vector indicating the number of categories of each variable. For con-

tinuous variables set to 1.

N Number of samples that should be drawn from the distribution.

nIter Number of iterations in the Gibbs sampler until a sample is drawn.

pbar If pbar = TRUE a progress bar is shown. Defaults to pbar = TRUE.

divWarning mgmsampler() returns a warning message if the absolute value of a continuous

variable the chain of the gibbs sampler is larger than divWarning. To our best knowledge there is no theory yet defining a parameter space that ensures a proper probability density and hence a converging chain. Defaults to divWarning =

10^3.

returnChains If returnChains = TRUE, the sampler provides the entire chain of the Gibbs

sampler, for each sampled case. Can be used to check convergence of the Gibbs

sampler. Defaults to returnChains = FALSE.

## **Details**

We use a Gibbs sampler to sample from the join distribution introduced by Yang and colleageus (2014). Note that the contraints on the parameter space necessary to ensure that the joint distribution is normalizable are to our best knowledge unknown. Yang and colleagues (2014) give these constraints for a number of simple pairwise models. In practice, an "improper joint density" will lead to a sampling process that approaches infinity, and hence mgmsampler() will return Inf / -Inf values.

## Value

A list containing:

call Contains all provided input arguments.

data The N x p data matrix of sampled values

#### Author(s)

Jonas Haslbeck <jonashaslbeck@gmail.com>

## References

Haslbeck, J., & Waldorp, L. J. (2018). mgm: Estimating time-varying Mixed Graphical Models in high-dimensional Data. arXiv preprint arXiv:1510.06871.

Yang, E., Baker, Y., Ravikumar, P., Allen, G. I., & Liu, Z. (2014, April). Mixed Graphical Models via Exponential Families. In AISTATS (Vol. 2012, pp. 1042-1050).

# **Examples**

```
## Not run:
# ----- Example 1: p = 10 dimensional Gaussian ------
# ---- 1) Specify Model ----
# a) General Graph Info
p <- 10 # number of variables
type = rep("g", p) # type of variables
level = rep(1, 10) # number of categories for each variable (1 = convention for continuous)
# b) Define interactions
factors <- list()</pre>
factors[[1]] \leftarrow matrix(c(1,2,
                          1,3,
                          4,5,
                          7,8), ncol=2, byrow = T) # 4 pairwise interactions
interactions <- list()</pre>
interactions[[1]] <- vector("list", length = 4)</pre>
# all pairwise interactions have value .5
for(i in 1:4) interactions[[1]][[i]] <- array(.5, dim=c(1, 1))</pre>
# c) Define Thresholds
thresholds <- vector("list", length = p)</pre>
thresholds <- lapply(thresholds, function(x) 0 ) # all means are zero
# d) Define Variances
sds <- rep(1, p) # All variances equal to 1
# ---- 2) Sample cases -----
data <- mgmsampler(factors = factors,</pre>
                   interactions = interactions,
                   thresholds = thresholds,
                   sds = sds,
                   type = type,
                   level = level,
                   N = 500,
                   nIter = 100,
                   pbar = TRUE)
```

```
# ---- 3) Recover model from sampled cases ----
set.seed(1)
mgm_obj <- mgm(data = data$data,</pre>
                type = type,
                level = level,
                k = 2,
                lambdaSel = "EBIC".
                lambdaGam = 0.25)
mgm_obj$interactions$indicator # worked!
# ----- Example 2: p = 3 Binary model with one 3-way interaction ------
# ----- 1) Specify Model -----
# a) General Graph Info
type = c("c", "c", "c")
level = c(2, 2, 2)
# b) Define Interaction
factors <- list()</pre>
factors[[1]] <- NULL # no pairwise interactions</pre>
factors[[2]] <- matrix(c(1,2,3), ncol=3, byrow = T) \# one 3-way interaction
interactions <- list()</pre>
interactions[[1]] <- NULL</pre>
interactions[[2]] <- vector("list", length = 1)</pre>
# threeway interaction no1
interactions[[2]][[1]] <- array(0, dim = c(level[1], level[2], level[3]))</pre>
interactions[[2]][[1]][1, 1, 1] \leftarrow theta \# fill in nonzero entries
# thus: high probability for the case that x1 = x2 = x3 = 1
# c) Define Thresholds
thresholds <- list()</pre>
thresholds[[1]] <- rep(0, level[1])</pre>
thresholds[[2]] <- rep(0, level[2])</pre>
thresholds[[3]] <- rep(0, level[3])</pre>
# ---- 2) Sample cases ----
set.seed(1)
dlist <- mgmsampler(factors = factors,</pre>
                     interactions = interactions,
                     thresholds = thresholds,
                     type = type,
                     level = level,
```

```
N = 500,
                     nIter = 100,
                     pbar = TRUE)
# ---- 3) Check: Contingency Table ----
dat <- dlist$data
table(dat[,1], dat[,2], dat[,3]) # this is what we expected
# ---- 4) Recover model from sampled cases ----
mgm_obj <- mgm(data = dlist$data,</pre>
                type = type,
               level = level,
               k = 3,
               lambdaSel = "EBIC",
                lambdaGam = 0.25,
                overparameterize = TRUE)
mgm_obj$interactions$indicator # recovered, plus small spurious pairwise 1-2
# ------ Example 3: p = 5 Mixed Graphical Model with two 3-way interaction ------
# ---- 1) Specify Model ----
# a) General Graph Info
type = c("g", "c", "c", "g")
level = c(1, 3, 5, 1)
# b) Define Interaction
factors <- list()</pre>
factors[[1]] <- NULL # no pairwise interactions</pre>
factors[[2]] <- matrix(c(1,2,3,</pre>
                           2,3,4), ncol=3, byrow = T) # no pairwise interactions
interactions <- list()</pre>
interactions[[1]] <- NULL</pre>
interactions[[2]] <- vector("list", length = 2)</pre>
# 3-way interaction no1
interactions[[2]][[1]] <- array(0, dim = c(level[1], level[2], level[3]))</pre>
interactions[[2]][[1]][,,1:3] \leftarrow rep(.8, 3) # fill in nonzero entries
# 3-way interaction no2
interactions[[2]][[2]] <- array(0, dim = c(level[2], level[3], level[4]))</pre>
interactions[[2]][[2]][1,1,] <- .3</pre>
interactions[[2]][[2]][2,2,] <- .3
interactions[[2]][[2]][3,3,] <- .3</pre>
# c) Define Thresholds
thresholds <- list()</pre>
thresholds[[1]] \leftarrow 0
thresholds[[2]] <- rep(0, level[2])</pre>
thresholds[[3]] <- rep(0, level[3])</pre>
thresholds[[4]] <- 0
```

```
# d) Define Variances
sds <- rep(.1, length(type))</pre>
# ---- 2) Sample cases -----
set.seed(1)
data <- mgmsampler(factors = factors,</pre>
                   interactions = interactions,
                   thresholds = thresholds,
                   sds = sds,
                   type = type,
                   level = level,
                   N = 500,
                   nIter = 100,
                   pbar = TRUE)
# ---- 3) Check: Conditional Means ----
# We condition on the categorical variables and check whether
# the conditional means match what we expect from the model:
dat <- data$data
# Check interaction 1
mean(dat[dat[,2] == 1 \& dat[,3] == 1, 1]) # (compare with interactions[[2]][[1]])
mean(dat[dat[,2] == 1 \& dat[,3] == 5, 1])
# first mean higher, ok!
# Check interaction 2
mean(dat[dat[,2] == 1 \& dat[,3] == 1, 4]) # (compare with interactions[[2]][[2]])
mean(dat[dat[,2] == 1 \& dat[,3] == 2, 4])
# first mean higher, ok!
## End(Not run)
```

mvar

Estimating mixed Vector Autoregressive Model (mVAR)

# **Description**

Estimates mixed Vector Autoregressive Model (mVAR) via elastic-net regularized Generalized Linear Models

#### Usage

```
mvar(data, type, level, lambdaSeq, lambdaSel, lambdaFolds,
    lambdaGam, alphaSeq, alphaSel, alphaFolds, alphaGam, lags,
    consec, beepvar, dayvar, weights, threshold, method, binarySign,
    scale, verbatim, pbar, warnings, saveModels, saveData,
    overparameterize, thresholdCat, signInfo, ...)
```

#### **Arguments**

data n x p data matrix.

type p vector indicating the type of variable for each column in data. "g" for Gaus-

sian, "p" for Poisson, "c" for categorical.

level p vector indicating the number of categories of each variable. For continuous

variables set to 1.

lambdaSeq A sequence of lambdas that should be searched (see also lambdaSel). Defaults

to NULL, which uses the glmnet default to select a lambda candidate sequence

(recommended). See ?glmnet for details.

lambdaSel Specifies the procedure for selecting the tuning parameter controlling the Lq-

penalization. The two options are cross validation "CV" and the Extended Bayesian Information Criterion (EBIC) "EBIC". The EBIC performs well in selecting sparse graphs (see Barber and Drton, 2010 and Foygel and Drton, 2014). Note that when also searching the alpha parameter in the elastic net penalty, cross validation should be preferred, as the parameter vector will not necessarily be sparse anymore. The EBIC tends to be a bit more conservative than CV (see Haslbeck and Waldorp, 2016). CV can sometimes not be performed with categorical variables, because glmnet requires at least 2 events of each category of each categorical variable in each training-fold. Defaults to lambdaSel = "CV".

lambdaFolds Number of folds in cross validation if lambdaSel = "CV".

lambdaGam Hyperparameter gamma in the EBIC if lambdaSel = "EBIC". Defaults to lambdaGam

= .25.

alphaSeq A sequence of alpha parameters for the elastic net penality in [0,1] that should

be searched (see also alphaSel). Defaults to alphaSeq = 1, which means that the lasso is being used. alphaSeq = 0 corresponds to an L2-penalty (Ridge re-

gression). For details see Friedman, Hastie and Tibshirani (2010).

alphaSel Specifies the procedure for selecting the alpha parameter in the elastic net penalty.

The two options are cross validation "CV" and the Extended Bayesian Information Criterion (EBIC) "EBIC". The EBIC performs well in selecting sparse graphs (see Barber and Drton, 2010 and Foygel and Drton, 2014). Note that when also searching the alpha parameter in the elastic net penalty, cross validation should be preferred, as the parameter vector will not necessarily be sparse anymore. The EBIC tends to be a bit more conservative than CV (see Haslbeck and Waldorp, 2016). CV can sometimes not be performed with categorical variables, because glmnet requires at least 2 events of each category of each cate

gorical variable in each training-fold. Defaults to alphaSel = "CV".

alphaFolds Number of folds in cross validation if alphaSel = "CV"

alphaGam Hyperparameter gamma in the EBIC if alphaSel = "EBIC". Defaults to alphaGam

= .25.

Vector of positive integers indicating the lags included in the mVAR model (e.g. 1:3 or c(1,3,5))

consec An integer vector of length n, indicating the consecutiveness of measurement

points of the rows in data. This means that rows for which the necessary (defined by the specified VAR model) measurements at previous time points are not available are excluded from the analysis. For instance, for a VAR model with lag 1 a consec vector of consec = c(1,2,3,5) would mean that the fourth row is excluded from the analysis, since no measurement 5-1=4 is available (next to the first row, for which also no previous measurement can be available). This is useful in many applications in which measurements are missing randomly or due to the design of the data collection (for example, respondents only respond during the hours they are awake). The "trimmed" dataset is returned in call\$data\_lagged if saveData = TRUE. Defaults to consec = NULL, which assumes that all measurements are consecutive, i.e. consec = 1:n. In this case only the first max(lags) lags are excluded to obtain the VAR design matrix.

Together with the argument dayvar, this argument is an alternative to the consec argument (see above) to specify the consecutiveness of measurements. This is tailored to experience sampling method (ESM) studies, where the consecutiveness is defined by the number of notification on a given day (beepvar) and the

given day (dayvar).

dayvar See beepvar.

beepvar

weights A vector with n - max(lags) entries, indicating the weight for each observation. The mVAR design matrix has with n - max(lags) rows, because the first row

must be predictable by the highest lag. The weights have to be on the scale [0, n

- max(lags)].

threshold A threshold below which edge-weights are put to zero. This is done in order

to guarantee a lower bound on the false-positive rate. threshold = "LW" refers to the threshold in Loh and Wainwright (2013), which was used in all previous versions of mgm. threshold = "HW" refers to the threshold in Haslbeck and Waldorp (2016). If threshold = "none" no thresholding is applied. Defaults to

threshold = "LW".

method Estimation method, currently only method = "glm".

binarySign If binarySign = TRUE, a sign for the interaction within binary nodes and be-

tween binary and continuous nodes is provided in the output. Note that in this case the two categories of the binary variables have to be coded in 0,1. This is to ensure that the interpretation of the sign is unambigous: a positive sign of a parameter means that increasing the associated predictor results in a higher

probability for category 1.

scale If scale = TRUE, all Gaussian nodes (specified by "g" in the type argument)

are centered and divided by their standard deviation. Scaling is recommended, because otherwise the penalization of a parameter depends on the variance of

the associated predictor.

verbatim = TRUE, no warnings and no progress bar is shown. Defaults to

verbatim = FALSE.

pbar If pbar = TRUE, a progress bar is shown. Defaults to pbar = TRUE.

warnings If warnings = TRUE, no warnigns are returned. Defaults to warnings = FALSE. saveModels If saveModels = FALSE, only information about the weighted adjacency matrix,

and if d > 1 about the factor graph is provided in the output list. If saveModels

= TRUE, all fitted parameters are additionally returned.

saveData If saveData = TRUE, the data is saved in the output list. Defaults to saveData =

FALSE.

overparameterize

If overparameterize = TRUE, mgm() uses over-parameterized design-matrices for each neighborhood regression; this means that a cross-lagged effect between two categorical variables with m and s categories is parameterized by m\*s parameters. If overparameterize = FALSE the standard parameterization (in glmnet) with m\*(s-1) parameters is used, where the first category of the predicting variable serves as reference category. If all variables are continuous both parameterizations are the same. The default is set to overparameterize =

FALSE.

thresholdCat If thresholdCat = FALSE, the thresholds of categorical variables are set to zero.

Defaults to thresholdCat = TRUE for which the thresholds are esimated.

signInfo If signInfo = TRUE, a message is shown in the console, indicating that the sign

of estimates is stored separately. Defaults to signInfo = TRUE.

... Additional arguments.

#### **Details**

See Haslbeck and Waldorp (2018) for details about how the mixed VAR model is estimated.

## Value

signs

The function returns a list with the following entries:

call Contains all provided input arguments. If saveData = TRUE, it also contains the

data.

wadj A p x p x n\_lags array, in which rows are predicted by columns, i.e. entry

wadj[1,2,4] corresponds to the parameter(s) of variable 2 at time point t predicting variable 1 at time point t - z, where z is the fourth specified lag in lags and n\_lags is the number of specified lags in lags. For interactions that involve more than two parameters (e.g. always for categorical variables with more than 2 categories), we take the arithmetic mean of the absolute value of all parame-

A p x p x n\_lags array, specifying the signs corresponding to the entries of

ters. The full set of estimated parameters is saved in rawlags (see below).

wadj (if defined), where n\_lags is the number of specified lags in lags. 1/-1 indicate positive and negative relationships, respectively. 0 indicates that no sign is defined, which is the case for interactions that involve a categorical variable where an interaction can have more than one parameter. If binarySign = TRUE,

a sign is calculated for interactions between binary variables and binary and continuous variables, where the interaction is still defined by one parameter and hence a sign can be specified. NA indicates that the corresponding parameter in

wadj is zero.

A p x p x n\_lags array of colors indicating the sign of each parameter. This array

contains the same information is signs and is included for convenient plotting.

List with entries equal to the number of specified lags in lags. Each entry is a nested list, with each p entries: the first level indicates the predicted variable, the second level the predictor variable. In case of categorical variables, interactions have more than one parameter.

A list with p entries, which contain the intercept/thresholds for each node. In case a given node is categorical with m categories, there are m thresholds for this variable.

A list with p glmnet() models, from which all above output is computed. Also contains the coefficients models for the selected lambda and the applied tau threshold tau.

# Author(s)

edgecolor

Jonas Haslbeck <jonashaslbeck@gmail.com>

#### References

Barber, R. F., & Drton, M. (2015). High-dimensional Ising model selection with Bayesian information criteria. Electronic Journal of Statistics, 9(1), 567-607.

Foygel, R., & Drton, M. (2010). Extended Bayesian information criteria for Gaussian graphical models. In Advances in neural information processing systems (pp. 604-612).

Friedman, J., Hastie, T., & Tibshirani, R. (2010). Regularization paths for generalized linear models via coordinate descent. Journal of statistical software, 33(1), 1.

Haslbeck, J. M. B., & Waldorp, L. J. (2020). mgm: Estimating time-varying Mixed Graphical Models in high-dimensional Data. Journal of Statistical Software, 93(8), pp. 1-46. DOI: 10.18637/jss.v093.i08

Loh, P. L., & Wainwright, M. J. (2012, December). Structure estimation for discrete graphical models: Generalized covariance matrices and their inverses. In NIPS (pp. 2096-2104).

Yang, E., Baker, Y., Ravikumar, P., Allen, G. I., & Liu, Z. (2014, April). Mixed Graphical Models via Exponential Families. In AISTATS (Vol. 2012, pp. 1042-1050).

# Examples

```
## Not run:

## We generate data from a mixed VAR model and then recover the model using mvar()

# 1) Define mVAR model
p <- 6 # Six variables
type <- c("c", "c", "c", "c", "g", "g") # 4 categorical, 2 gaussians
level <- c(2, 2, 4, 4, 1, 1) # 2 categoricals with m=2, 2 categoricals with m=4, two continuous
max_level <- max(level)

lags <- c(1, 3, 9) # include lagged effects of order 1, 3, 9</pre>
```

```
n_lags <- length(lags)</pre>
# Specify thresholds
thresholds <- list()</pre>
thresholds[[1]] <- rep(0, level[1])</pre>
thresholds[[2]] <- rep(0, level[2])</pre>
thresholds[[3]] <- rep(0, level[3])</pre>
thresholds[[4]] <- rep(0, level[4])</pre>
thresholds[[5]] <- rep(0, level[5])</pre>
thresholds[[6]] <- rep(0, level[6])</pre>
# Specify standard deviations for the Gaussians
sds <- rep(NULL, p)</pre>
sds[5:6] <- 1
# Create coefficient array
coefarray <- array(0, dim=c(p, p, max_level, max_level, n_lags))</pre>
# a.1) interaction between continuous 5<-6, lag=3</pre>
coefarray[5, 6, 1, 1, 2] <- .4
# a.2) interaction between 1<-3, lag=1
m1 <- matrix(0, nrow=level[2], ncol=level[4])</pre>
m1[1,1:2] <- 1
m1[2,3:4] <- 1
coefarray[1, 3, 1:level[2], 1:level[4], 1] <- m1</pre>
# a.3) interaction between 1<-5, lag=9
coefarray[1, 5, 1:level[1], 1:level[5], 3] \leftarrow c(0, 1)
# 2) Sample
set.seed(1)
dlist <- mvarsampler(coefarray = coefarray,</pre>
                       lags = lags,
                       thresholds = thresholds,
                       sds = sds,
                       type = type,
                       level = level,
                       N = 200,
                       pbar = TRUE)
# 3) Recover
set.seed(1)
mvar_obj <- mvar(data = dlist$data,</pre>
                  type = type,
                  level = level,
                  lambdaSel = "CV",
                  lags = c(1, 3, 9),
                  signInfo = FALSE,
                  overparameterize = F)
# Did we recover the true parameters?
mvar_obj$wadj[5, 6, 2] # cross-lagged effect of 6 on 2 over lag lags[2]
mvar_obj$wadj[1, 3, 1] # cross-lagged effect of 3 on 1 over lag lags[1]
```

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```
mvar_obj$wadj[1, 5, 3] # cross-lagged effect of 1 on 5 over lag lags[3]

# How to get the exact parameter estimates?
# Example: the full parameters for the crossed-lagged interaction of 2 on 1 over lag lags[1]
mvar_obj$rawlags[[1]][[1]][[2]]

# 4) Predict / Compute nodewise Error
pred_mvar <- predict.mgm(mvar_obj, dlist$data)

head(pred_mvar$predicted) # first 6 rows of predicted values
pred_mvar$errors # Nodewise errors

# For more examples see https://github.com/jmbh/mgmDocumentation

## End(Not run)</pre>
```

mvarsampler

Sampling from a mixed VAR model

# Description

Function to sample from a mixed VAR (mVAR) model

# Usage

## Arguments

coefarray

A p x p x max(level) x max(level) x n\_lags array, where p are the number of variables, level is the input argument level and n\_lags is the number of specified lags in lags, so n\_lags = length(n\_lags). The first four dimensions specify the parameters involved in the cross-lagged effects of the lag specified in the 5th dimension. I.e. coefarray[5, 6, 1, 1, 3] indicates the cross-lagged effect of variable 6 on variable 5 (if both are continuous), for the third lag specified in lags. If variable 1 and 3 are categorical with m = 2 and = 4 categories, respectively, then coefarray[1, 3, 1:2, 1:4, 1] indicates the m\*s=8 parameters specifying this interaction for the first lag specified in lags. See the examples below for an illustration.

lags

A vector indicating the lags in the mVAR model. E.g. lags = c(1,4,9) specifies lags of order 1, 3, 9. The number of specified lags has to match the 5th dimension in coefarray.

thresholds

A list with p entries, each consisting of a vector indicating a threshold for each category of the given variable. For continuous variable, the vector has length 1.

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sds A vector of length p indicating the standard deviations of the included Gaussian

nodes. If non-Gaussian variables are included in the mVAR model, the corre-

sponding entries are ignored.

type p vector indicating the type of variable for each column in data. "g" for Gaus-

sian, "p" for Poisson, "c" for categorical.

level p vector indicating the number of categories of each variable. For continuous

variables set to 1.

N The number of samples to be drawn from the specified mVAR model.

pbar If pbar = TRUE, a progress bar is shown.

## **Details**

We sample from the mVAR model by separately sampling from its corresponding p conditional distributions.

#### Value

A list with two entries:

call The function call

data The sampled n x p data matrix

## Author(s)

Jonas Haslbeck <jonashaslbeck@gmail.com>

#### References

Haslbeck, J. M. B., & Waldorp, L. J. (2020). mgm: Estimating time-varying Mixed Graphical Models in high-dimensional Data. Journal of Statistical Software, 93(8), pp. 1-46. DOI: 10.18637/jss.v093.i08

# **Examples**

```
## Not run:

## Generate data from mixed VAR model using mvarsampler() and recover model using mvar()

# 1) Define mVAR model

p <- 6 # Six variables
type <- c("c", "c", "c", "c", "g", "g") # 4 categorical, 2 gaussians
level <- c(2, 2, 4, 4, 1, 1) # 2 categoricals with m=2, 2 categoricals with m=4, two continuous
max_level <- max(level)

lags <- c(1, 3, 9) # include lagged effects of order 1, 3, 9
n_lags <- length(lags)</pre>
```

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```
# Specify thresholds
thresholds <- list()</pre>
thresholds[[1]] <- rep(0, level[1])</pre>
thresholds[[2]] <- rep(0, level[2])</pre>
thresholds[[3]] <- rep(0, level[3])</pre>
thresholds[[4]] <- rep(0, level[4])</pre>
thresholds[[5]] <- rep(0, level[5])</pre>
thresholds[[6]] <- rep(0, level[6])</pre>
# Specify standard deviations for the Gaussians
sds <- rep(NULL, p)
sds[5:6] <- 1
# Create coefficient array
coefarray <- array(0, dim=c(p, p, max_level, max_level, n_lags))</pre>
# a.1) interaction between continuous 5<-6, lag=3</pre>
coefarray[5, 6, 1, 1, 2] <- .4
# a.2) interaction between 1<-3, lag=1
m1 <- matrix(0, nrow=level[2], ncol=level[4])</pre>
m1[1,1:2] <- 1
m1[2,3:4] <- 1
coefarray[1, 3, 1:level[2], 1:level[4], 1] <- m1</pre>
# a.3) interaction between 1<-5, lag=9
coefarray[1, 5, 1:level[1], 1:level[5], 3] \leftarrow c(0, 1)
# 2) Sample
set.seed(1)
dlist <- mvarsampler(coefarray = coefarray,</pre>
                      lags = lags,
                       thresholds = thresholds,
                       sds = sds,
                       type = type,
                      level = level,
                      N = 200,
                      pbar = TRUE)
# 3) Recover
set.seed(1)
mvar_obj <- mvar(data = dlist$data,</pre>
                  type = type,
                  level = level,
                  lambdaSel = "CV",
                  lags = c(1, 3, 9),
                  signInfo = FALSE,
                  overparameterize = F)
# Did we recover the true parameters?
mvar_obj$wadj[5, 6, 2] # cross-lagged effect of 6 on 5 over lag lags[2]
mvar_obj$wadj[1, 3, 1] # cross-lagged effect of 3 on 1 over lag lags[1]
mvar_obj$wadj[1, 5, 3] # cross-lagged effect of 1 on 5 over lag lags[3]
```

32 plotRes

```
# For more examples see https://github.com/jmbh/mgmDocumentation
## End(Not run)
```

plotRes

Plot summary of resampled sampling distributions

# Description

Plots a summary of sampling distributions resampled with the resample() function

# Usage

```
plotRes(object, quantiles = c(.05, .95), labels = NULL, decreasing = TRUE, cut = NULL, cex.label = 0.75, lwd.qtl = 2, cex.mean = 0.55, cex.bg = 2.7, axis.ticks = c(-0.5, -0.25, 0, 0.25, 0.5, 0.75, 1), axis.ticks.mod = NULL, layout.width.labels = .2, layout.gap.pw.mod = .15)
```

# **Arguments**

| object     | An output object from the resample() function.  |
|------------|---|
| quantiles  | A numerical vector of length two, specifying the desired lower/upper quantiles. Defaults to quantiles = $c(.05,.95)$ .  |
| labels     | A character vector of length p, containing the label of each variable, where p is the number of variables.  |
| decreasing | If TRUE (default), the edges are ordered by the arithmetic mean of the sampling distribution in decreasing order. If FALSE they are ordered in increasing order.  |
| cut        | A sequence of integers, specifying which edges are represented. For instance, if decreasing = TRUE and cut = 1:10, summaries for the 10 edges with the largest parameter estimate are displayed. The cut argument can also be used to present the boostrapped CIs in several figures. |
| cex.label  | Text size of the labels.  |
| lwd.qtl    | Line width of line indicating the upper/lower quantiles.  |
| cex.mean   | Text size of the number indicating the proportion of the estimates whose absolute value is larger than zero.  |
| cex.bg     | Size of the white background of the number indicating the proportion of the estimates whose absolute value is larger than zero.   |
| axis.ticks | A numeric vector indicating the axis ticks and labels for the x-axis.   |

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axis.ticks.mod A numeric vector indicating the axis ticks and labels for the x-axis for moderation effects. If axis.ticks.mod=NULL, the values from axis.ticks for pairwise interactions are used.

layout.width.labels

A positive numeric value which specifies the width of the left-hand-side legend relative to the width of the data panel (or data panels, in case of a moderator model), which have width = 1. Defaults to layout.width.labels = 0.2.

layout.gap.pw.mod

A positive numeric value which specifies the width of the gap between the stability of pairwise effects and moderation effects. Defaults to layout.gap.pw.mod = 0.15.

#### **Details**

Currently only supports summaries for resampled mgm() objects, and moderated MGMs with a single moderator.

#### Value

Plots a figure that shows summaries of the resampled sampling distribution for (a set of) all edge parameters. These include the mean, a specified upper and lower quantile and the proportion of parameter estimates whose absolute value is larger than zero.

## Author(s)

Jonas Haslbeck <jonashaslbeck@gmail.com>

#### See Also

```
resample(), mgm(), mvar(), tvmgm(), tvmar()
```

# **Examples**

34 predict.mgm

```
labels = NULL,
        axis.ticks = c(-.25, 0, .25, .5, .75)
## End(Not run)
```

predict.mgm

Compute predictions from mgm model objects

# **Description**

Computes predictions and prediction errors from a mgm model-object (mgm, mvar, tvmgm or tvmvar).

## Usage

```
## S3 method for class 'mgm'
predict(object, data, errorCon, errorCat,
        tvMethod, consec, beepvar, dayvar, ...)
```

## **Arguments**

object

An mgm model object (the output of one of the functions mgm(), mvar(), tvmgm()

or tvmvar())

data

A n x p data matrix with the same structure (number of variables p and types of

variables) as the data used to fit the model.

errorCon

Either a character vector specifying the types of nodewise errors that should be computed, where the two provided error functions for continuous varaibles are errorCon = "RMSE", the Root Mean Squared Error, and errorCon = "R2", the proportion of explained variance. The default is errorCon = c("RMSE" "R2").

Alternatively, errorCon can be a list, where each list entry is a custom error function of the form foo(true, pred), where true and pred are the arguments for the vectors of true and predicted values, respectively. If predictions are made for a time-varying model and tvMethod = "weighted", the weighted R2 or RMSE are computed. If a custom function is used, an additional argument for the weights has to be provided: foo(true, pred, weights). Note that custom error functios can also be combined with the buildt-in functions, i.e. errorCon

= list("RMSE", "CustomError"=foo).

errorCat

Either a character vector specifying the types of nodewise errors that should be computed, where the two provided error functions for categorical variables are errorCat = "CC", the proportion of correct classification (accuracy) and errorCat = "nCC", the proportion of correct classification normalized by the marginal distribution of the variable at hand. Specifically, nCC = (CC - norm\_constant) / (1 - norm constant), where norm constant is the highest relative frequency across categories. Another provided error is "CCmarg" which returns the accuracy of the intercept/marginal model. The default is to return all types of errors errorCon = c("CC" "nCC", "CCmarg").

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Alternatively, errorCat can be a list, where each list entry is a custom error function of the form foo(true,pred), where true and pred are the arguments for the vectors of true and predicted values, respectively. If predictions are made for a time-varying model and tvMethod = "weighted", the weighted R2 or RMSE are computed. If a custom function is used, an additional argument for the weights has to be provided: foo(true,pred,weights). Note that custom error functios can also be combined with the buildt-in functions, i.e. errorCon = list("nCC", "CustomError"=foo).

tvMethod

Specifies how predictions and errors are computed for time-varying models: tvMethod = "weighted" computes errors by computing a weighted error over all cases in the time series at each estimation point specified in estpoints in tvmgm() or tvmvar(). The weighting corresponds to the weighting used for estimation (see ?tvmgm or ?tvmvar). tvMethod = "closestModel" determines for each time point the closest model and uses that model for prediction. See Details below for a more detailed explanation.

consec

Only relevant for (time-varying) mVAR models. An integer vector of length nrow(data), indicating the sequence of measurement points in a time series. This is only relevant for mVAR models and time series with unequal time intervals. Defaults to consec = NULL, which assumes equal time intervals. consec is ignored if a mgm or tvmgm object is provided to predict.mgm(). For details see ?mvar.

beepvar

Together with the argument dayvar, this argument is an alternative to the consec argument (see above) to specify the consecutiveness of measurements. This is tailored to ecological momentary assessment (EMA) studies, where the consecutiveness is defined by the number of notification on a given day (beepvar) and the given day (dayvar).

dayvar See beepvar.

... Additional arguments.

#### **Details**

Nodewise errors in time-varying models can be computed in two different ways: first, one computes the predicted value for each of the N cases in the time series for all models (estimated at different estimation points, see ?tvmgm or ?tvmvar). Then the error of each of the N cases for each of the models is weighted by the weight that has been used to estimate a given model at its estimation point. This means that the error of a data point close to the end of a time-series gets a high weight for models estimated in the end of the time-series and a low weight for models estimated in the beginning of the time series.

Second, we determine for each case in the time-series the closest estmation point, and use the model estimated at that estimation point to make predictions for that case.

Note that the error function normalized accuracy (nCC) is negative if the full model performs worse than the intercept model. This can happen if the model overfits the data.

#### Value

A list with the following entries:

36 print.int

call Contains all provided input arguments.

predicted A n x p matrix with predicted values, matching the dimension of the true values

in true.

probabilities A list with p entries corresponding to p nodes in the data. If a variable is categor-

ical, the corresponding entry contains a  $n \times k$  matrix with predicted probabilities, where k is the number of categories of the categorical variable. If a variable is

continuous, the corresponding entry is empty.

true Contains the true values. For mgm and tvmgm objects these are equal to the data

provided via data. For mvar and tvmvar objects, these are equal to the rows that can be predicted in a VAR model, depending on the largest specified lag

and (if specified) the consec argument.

errors A matrix containing the all types of errors specified via errorCon and errorCat,

for each variable. If tvMethod = "weighted", the matrix becomes an array, with

an additional dimension for the estimation point.

tverrors If tvMethod = "weighted", this list entry contains a list with errors of the format

of errors, separately for each estimation point. The errors are computed from predictions of the model at the given estimation points and weighted by the weight-vector at that estimation point. If tvMethod = "closestModel", this

entry is empty.

#### Author(s)

Jonas Haslbeck <jonashaslbeck@gmail.com>

# References

Haslbeck, J. M. B., & Waldorp, L. J. (2020). mgm: Estimating time-varying Mixed Graphical Models in high-dimensional Data. Journal of Statistical Software, 93(8), pp. 1-46. DOI: 10.18637/jss.v093.i08

## **Examples**

```
## Not run:
# See examples in ?mgm, ?tvmgm, ?mvar and ?tvmvar.
## End(Not run)
```

print.int

Print method for int objects

# Description

Returns basic information about objects created with showInteraction()

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# Usage

```
## S3 method for class 'int' print(x, ...)
```

# **Arguments**

- x The output object of showInteraction().
- ... Additional arguments.

# Value

Writes basic information about the object in the console.

# Author(s)

Jonas Haslbeck <jonashaslbeck@gmail.com>

print.mgm

Print method for mgm objects

# **Description**

Returns basic information about fit objects, prediction objects and bandwidth-selection objects.

# Usage

```
## S3 method for class 'mgm'
print(x, ...)
```

# **Arguments**

```
x The output object of mgm(), mvar(), tvmgm(), tvmvar(), predict.mgm() or
bwSelect().
... Additional arguments.
```

#### Value

Writes basic information about the object in the console.

# Author(s)

Jonas Haslbeck <jonashaslbeck@gmail.com>

38 resample

| resample | Resampling scheme for mgm objects |  |
|----------|-----------------------------------|--|
|          |                                   |  |

# **Description**

Fits mgm model types (mgm, mvar, tvmgm, tvmvar) to a specified number of bootstrap samples.

# Usage

#### Arguments

| object    | An mgm model object, the output of mgm(), tvmgm(), mvar(), tvmvar(). The model specifications for all fitted models are taken from this model object.         |
|-----------|---|
| data      | The n x p data matrix.  |
| nB        | The number of bootstrap samples.  |
| blocks    | The number of blocks for the block bootstrap used for time-varying models.  |
| quantiles | A vector with two values in $[0, 1]$ , specifying quantiles computed on the bootstrapped sampling distributions. Defaults to quantiles = $c(.05, .95)$        |
| pbar      | If TRUE, a progress bar is shown. Defaults to pbar = TRUE.  |
| verbatim  | If TRUE, the seed of the current bootstrap sample is printed in the console. Useful to exclude zero-variance bootstrap samples in datasets with low variance. |
|           | Additional arguments.   |

# Details

resample() fits a model specified via the object argument to nB bootstrap samples obtained from the original dataset. For stationary models (mgm() and mvar()) objects, we use the standard bootstrap. For time-varying models (tvmgm() and tvmvar()) we use the block bootstrap.

For mvar models, bootParameters is a p x p x nlags x nB array, where p is the number of variables, nlags is the number of specified lags, and nB is the number of bootstrap samples. Thus bootParameters[7,3,2,] returns the bootstrapped sampling distribution of the lagged effect from variable 3 on 7 for the 2nd specified lag. See also ?mvar.

For tymar models, bootParameters is a p x p x nlags x nestpoints x nB array, analogously to mvar models. nestpoints is the number of specified estpoints. See also ?tvmvar.

Resampling is currently only supported for pairwise MGMs (k = 2). For mgms, bootParameters is a p x p x nB array. For tvmgms, bootParameters is a p x p x nestpoint x nB array.

The seeds for the bootstrap samples are randomly sampled. For MGMs, the seeds are resampled until there are nB bootstrap samples on which an MGM can be estimated. This resampling has been implemented, because especially for small data sets, one can obtain bootstrap samples in which one or several variables have zero variance. For the other model classes, an informative error is returned in case the respective model cannot be estimated on one or more of the bootstrap samples.

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#### Value

The output consists of a list with the entries

call Contains the function call.

models A list with nB entries, containing the models fit to the bootstrapped sampels.

bootParameters Contains all the bootstrapped sampling distribution of all parameters. The di-

mension of this object depends on the type of model. Specifically, this object has the same dimension as the main parameter output of the corresponding estimation function, with one dimension added for the bootstrap iterations. See

"Details" above.

bootQuantiles Contains the specified quantiles of the bootstrapped sampling distribution for

each parameter. Has the same structure as bootParameters. See "Details"

above.

Times Returns the running time for each bootstrap model in seconds.

totalTime Returns the running time for all bootstrap models together in seconds.

seeds nB integers indicating the seeds used to sample the nB bootstrap samples.

#### Author(s)

Jonas Haslbeck <jonashaslbeck@gmail.com>

#### References

Haslbeck, J. M. B., & Waldorp, L. J. (2020). mgm: Estimating time-varying Mixed Graphical Models in high-dimensional Data. Journal of Statistical Software, 93(8), pp. 1-46. DOI: 10.18637/jss.v093.i08

# Examples

## Not run:

40 showInteraction

showInteraction

Retrieving details of interactions

# **Description**

Retrieves details of a specified interaction from mgm model objects.

# Usage

```
showInteraction(object, int)
```

# **Arguments**

object The output of one of the estimation functions mgm(), tvmgm(), mvar(), tvmvar().

int An integer vector specifying the interaction. For mVAR models, this vector has

length 2. For MGMs the vector can be larger to request details of interaction of

order > 2.

### Details

Currently the function only returns details of pairwise interactions from output objects of mgm().

#### Value

variables Integer vector returning the variables specified via the argument int type Character vector returning the type of the specified variables variables

level Integer vector returning the number of levels of the specified variables variables

parameters A list of length equal to the order k of the specified interaction. The entries

contain the set of parameters obtained from the nodewise regressions on the k variables. Depending on the type of the variables in the interaction, these sets can obtain one or several parameters. For details see ?mgm or Haslbeck &

Waldorp (2017).

# Author(s)

Jonas Haslbeck <jonashaslbeck@gmail.com>

#### References

Haslbeck, J. M. B., & Waldorp, L. J. (2020). mgm: Estimating time-varying Mixed Graphical Models in high-dimensional Data. Journal of Statistical Software, 93(8), pp. 1-46. DOI: 10.18637/jss.v093.i08

# See Also

```
mgm, tvmgm, mvar, tvmvar
```

# **Examples**

tvmgm

Estimating time-varying Mixed Graphical Models

# **Description**

Estimates time-varying k-order Mixed Graphical Models (MGMs) via elastic-net regularized kernel smoothed Generalized Linear Models

#### **Usage**

```
tvmgm(data, type, level, timepoints, estpoints, bandwidth, ...)
```

#### **Arguments**

data n x p data matrix.

type p vector indicating the type of variable for each column in data: "g" for Gaus-

sian, "p" for Poisson, "c" for categorical.

level p vector indicating the number of categories of each variable. For continuous

variables set to 1.

timepoints A strictly increasing numeric vector of length nrow(data) indicating the time

points of the measurements in data. If timepoints is not specified, it is assumed that the time points are equally spaced. For details, see Haslbeck and

Waldorp (2018).

estpoints Vector indicating estimation points on the unit interval [0, 1] (the provided time

scale is normalized interally to [0,1]).

bandwidth We use a gaussian density on the unit time-interval [0,1] to determine the weights

for each observation at each estimated time point. The bandwidth specifies the standard deviation the Gaussian density. To get some intuition, which bandwidth results in the combination of how many data close in time one can plot Gaussians on [0,1] for different bandwidths. The bandwidth can also be selected

in a data driven way using the function (see bwSelect).

... Arguments passed to mgm, specifying the MGM. See ?mgm.

#### Details

Estimates a sequence of MGMs at the time points specified at the locations specified via estpoints. tvmgm() is a wrapper around mgm() and estimates a series of MGM with different weightings which are defined by the estimation locations in estpoints and the bandwidth parameter specified in bandwidth. For details see Haslbeck and Waldorp (2018).

Note that MGMs are not normalizable for all parameter values. See Chen, Witten & Shojaie (2015) for an overview of when pairwise MGMs are normalizable. To our best knowledge, for MGMs with interactions of order > 2 that include non-categorical variables, the conditions for normalizablity are unknown.

# Value

A list with the following entries:

call Contains all provided input arguments. If saveData = TRUE, it also contains the

data.

pairwise Contains a list with all information about estimated pairwise interactions. wadj

contains a p x p x estpoints array containing the weighted adjacency matrix for each estimation point specified in estpoints, if p is the number of variables in the network. signs has the same dimensions as wadj and contains the signs for the entries of wadj: 1 indicates a positive sign, -1 a negative sign and 0

an undefined sign. A sign is undefined if an edge is a function of more than one parameter. This is the case for interactions involving a categorical variable with more than 2 categories. edgecolor also has the same dimensions as wadj contains a color for each edge, depending on signs. It is provided for more convenient plotting. If only pairwise interactions are modeled (k = 2), wadj contains all conditional independence relations.

interactions

Contains a list with one entry for each estimation point specified in estpoints; each entry is a list with three entries that relate each interaction in the model to all its parameters. indicator contains a list with k-1 entries, one for each order of modeled interaction, which contain the estimated (nonzero) interactions. weights contains a list with k-1 entries, which in turn contain R lists, where R is the number of interactions (and rows in the corresponding list entry inindicator) that were estimated (nonzero) in the given entry. signs has the same structure as weights and provides the sign of the interaction, if defined.

intercepts

Contains a list with one entry for each estimation point specified in estpoints; each entry is a list with p entries, which contain the intercept/thresholds for each node in the network. In case a given node is categorical with m categories, there are m thresholds for this variable (one for each category).

tvmodels

Contains the MGM model estimated by mgm() at each time point specified via estpoints. See ?mgm for a detailed description of this output.

#### Author(s)

Jonas Haslbeck <jonashaslbeck@gmail.com>

#### References

Chen S, Witten DM & Shojaie (2015). Selection and estimation for mixed graphical models. Biometrika, 102(1), 47.

Haslbeck, J. M. B., & Waldorp, L. J. (2020). mgm: Estimating time-varying Mixed Graphical Models in high-dimensional Data. Journal of Statistical Software, 93(8), pp. 1-46. DOI: 10.18637/jss.v093.i08

Yang, E., Baker, Y., Ravikumar, P., Allen, G. I., & Liu, Z. (2014, April). Mixed Graphical Models via Exponential Families. In AISTATS (Vol. 2012, pp. 1042-1050).

# **Examples**

```
## Not run:

## We specify a time-varying MGM and recover it using tvmgm()

# 1) Specify Model

# a) Define Graph
p <- 6
type = c("c", "c", "g", "g", "p", "p")
level = c(2, 3, 1, 1, 1, 1)</pre>
```

```
n_timepoints <- 1000
# b) Define Interaction
factors <- list()</pre>
factors[[1]] \leftarrow matrix(c(1,2,
                           3,4), ncol=2, byrow = T) # no pairwise interactions
factors[[2]] \leftarrow matrix(c(1,2,3,
                           2,3,4), ncol=3, byrow = T) # one 3-way interaction
interactions <- list()</pre>
interactions[[1]] <- vector("list", length = 3)</pre>
interactions[[2]] <- vector("list", length = 2)</pre>
# 3 2-way interactions
interactions[[1]][[1]] <- array(0, dim = c(level[1], level[2], n_timepoints))</pre>
interactions[[1]][[2]] <- array(0, dim = c(level[2], level[3], n_timepoints))</pre>
interactions[[1]][[3]] <- array(0, dim = c(level[3], level[4], n_timepoints))</pre>
# 2 3-way interactions
interactions[[2]][[1]] <- array(0, dim = c(level[1], level[2], level[3], n_timepoints))</pre>
interactions[[2]][[2]] <- array(0, dim = c(level[2], level[3], level[4], n_timepoints))</pre>
theta <- .3
interactions[[1]][[1]][1, 1, ] \leftarrow theta
interactions[[1]][[2]][1, 1, ] \leftarrow theta
interactions[[1]][[3]][1, 1, ] <- seq(0, theta, length = n_timepoints)</pre>
interactions[[2]][[1]][1, 1, 1, ] \leftarrow theta
interactions[[2]][[2]][1, 1, 1, ] \leftarrow theta
# c) Define Thresholds
thresholds <- list()</pre>
thresholds[[1]] <- matrix(0, nrow = n\_timepoints, ncol= level[1])
thresholds[[2]] <- matrix(0, nrow = n_timepoints, ncol= level[2])</pre>
thresholds[[3]] <- matrix(0, nrow = n_timepoints, ncol= level[3])</pre>
thresholds[[4]] <- matrix(0, nrow = n_timepoints, ncol= level[4])</pre>
thresholds[[5]] <- matrix(.1, nrow = n_timepoints, ncol= level[5])</pre>
thresholds[[6]] <- matrix(.1, nrow = n_timepoints, ncol= level[6])</pre>
# d) define sds
sds <- matrix(.2, ncol=p, nrow=n_timepoints)</pre>
# 2) Sample Data
set.seed(1)
d_iter <- tvmgmsampler(factors = factors,</pre>
                         interactions = interactions,
                         thresholds = thresholds,
                         sds = sds,
                         type = type,
                         level = level,
                         nIter = 100,
                         pbar = TRUE)
data <- d_iter$data
head(data)
# delete inf rows:
ind_finite <- apply(data, 1, function(x) if(all(is.finite(x))) TRUE else FALSE)</pre>
table(ind_finite) # all fine for this setup & seed
```

```
# in case of inf values (no theory on how to keep k-order MGM well-defined)
data <- data[ind_finite, ]</pre>
# 3) Recover
mgm_c_cv <- tvmgm(data = data,</pre>
                  type = type,
                  level = level,
                  k = 3,
                  estpoints = seq(0, 1, length=10),
                  bandwidth = .1,
                  lambdaSel = "CV"
                  ruleReg = "AND",
                  pbar = TRUE,
                  overparameterize = T,
                  signInfo = FALSE)
# Look at time-varying pairwise parameter 3-4
mgm_c_cv$pairwise$wadj[3,4,] # recovers increase
# 4) Predict values / compute nodewise Errors
pred_mgm_cv_w <- predict.mgm(mgm_c_cv,</pre>
                              data = data,
                              tvMethod = "weighted")
pred_mgm_cv_cM <- predict.mgm(mgm_c_cv,</pre>
                               data = data,
                               tvMethod = "closestModel")
pred_mgm_cv_w$errors
pred_mgm_cv_cM$errors # Pretty similar!
# For more examples see https://github.com/jmbh/mgmDocumentation
## End(Not run)
```

tvmgmsampler

Sample from time-varying k-order Mixed Graphical Model

# **Description**

Generates samples from a time-varying k-order Mixed Graphical Model

# Usage

#### **Arguments**

factors The same object as factors in mgmsampler(). An interaction is specified in factors if it should be nonzero at least at one time point in the time series. The values of each parameter at each time point is specified via interactions. interactions The same object as factors in mgmsampler(), except that each array indicating the parameters of an interaction has an additional (the last) dimension, indicating time. Corresponding to the time vector in factors, the time vector has to be a sequence of integers {1, 2, ..., N}. For an illustration see the examples below. thresholds A list with p entries for p variables, each of which contains a N x m matrix. The columns contain the m thresholds for m categories (for continuous variables m = 1 and the entry contains the threshold/intercept). The rows indicate how the thresholds change over time. sds N x p matrix indicating the standard deviations of Gaussians specified in type for {1, ..., N} time points. Entries not referring to Gaussians are ignored. type p character vector indicating the type of variable for each column in data. "g" for Gaussian, "p" for Poisson, "c" of each variable. level p integer vector indicating the number of categories of each variable. For con-

tinuous variables set to 1.

nIter Number of iterations in the Gibbs sampler until a sample is drawn. pbar If pbar = TRUE a progress bar is shown. Defaults to pbar = TRUE.

Additional arguments.

#### **Details**

tvmgmsampler is a wrapper function around mgmsampler. Its input is the same as for mgmsampler, except that each object has an additional dimension for time. The number of time points is specified via entries in the additional time dimension.

#### Value

A list containing:

Contains all provided input arguments. call data The N x p data matrix of sampled values

# Author(s)

Jonas Haslbeck < jonashaslbeck@gmail.com>

#### References

Haslbeck, J. M. B., & Waldorp, L. J. (2020). mgm: Estimating time-varying Mixed Graphical Models in high-dimensional Data. Journal of Statistical Software, 93(8), pp. 1-46. DOI: 10.18637/jss.v093.i08

Yang, E., Baker, Y., Ravikumar, P., Allen, G. I., & Liu, Z. (2014, April). Mixed Graphical Models via Exponential Families. In AISTATS (Vol. 2012, pp. 1042-1050).

# **Examples**

```
## Not run:
# ----- Example 1: p = 4 dimensional Gaussian -----
# ---- 1) Specify Model -----
# a) General Graph Info
type = c("g", "g", "g", "g") # Four Gaussians
level = c(1, 1, 1, 1)
n_timepoints = 500 # Number of time points
# b) Define Interaction
factors <- list()</pre>
factors[[1]] <- array(NA, dim=c(2, 2)) # two pairwise interactions</pre>
factors[[1]][1, 1:2] <- c(3,4)
factors[[1]][2, 1:2] <- c(1,2)
# Two parameters, one linearly increasing from 0 to 0.8, another one lin decreasing from 0.8 to 0
interactions <- list()</pre>
interactions[[1]] <- vector("list", length = 2)</pre>
interactions[[1]][[1]] <- array(0, dim = c(level[1], level[2], n_timepoints))</pre>
interactions[[1]][[1]][1,1, ] \leftarrow seq(.8, 0, length = n_timepoints)
interactions[[1]][[2]] <- array(0, dim = c(level[1], level[2], n_timepoints))</pre>
interactions[[1]][[2]][1,1, ] \leftarrow seq(0, .8, length = n_timepoints)
# c) Define Thresholds
thresholds <- vector("list", length = 4)</pre>
thresholds <- lapply(thresholds, function(x) matrix(0, ncol = level[1], nrow = n_timepoints))</pre>
# d) Define Standard deviations
sds \leftarrow matrix(1, ncol = length(type), nrow = n_timepoints) \# constant across variables and time
# ---- 2) Sample cases -----
set.seed(1)
dlist <- tvmgmsampler(factors = factors,</pre>
                       interactions = interactions,
                       thresholds = thresholds,
                       sds = sds,
                       type = type,
                       level = level,
                       nIter = 75,
                       pbar = TRUE)
# ---- 3) Recover model from sampled cases ----
set.seed(1)
```

```
tvmgm_obj <- tvmgm(data = dlist$data,</pre>
                   type = type,
                   level = level,
                   estpoints = seq(0, 1, length = 15),
                   bandwidth = .2,
                   k = 2,
                   lambdaSel = "CV",
                   ruleReg = "AND")
# How well did we recover those two time-varying parameters?
plot(tvmgm_obj$pairwise$wadj[3,4,], type="1", ylim=c(0,.8))
lines(tvmgm_obj$pairwise$wadj[1,2,], type="l", col="red")
# Looks quite good
# ----- Example 2: p = 5 binary; one 3-way interaction ------
# ----- 1) Specify Model -----
# a) General Graph Info
p <- 5 # number of variables
type = rep("c", p) # all categorical
level = rep(2, p) # all binary
n_timepoints <- 1000
# b) Define Interaction
factors <- list()</pre>
factors[[1]] <- NULL # no pairwise interactions</pre>
factors[[2]] <- array(NA, dim = c(1,3)) # one 3-way interaction
factors[[2]][1, 1:3] <- c(1, 2, 3)
interactions <- list()</pre>
interactions[[1]] <- NULL # no pairwise interactions</pre>
interactions[[2]] <- vector("list", length = 1) # one 3-way interaction
# 3-way interaction no1
interactions[[2]][[1]] <- array(0, dim = c(level[1], level[2], level[3], n_timepoints))</pre>
[[2]][[1]][1, 1, 1, ] \leftarrow seq(0, 2, length = n\_timepoints) \# fill in nonzero entries
# c) Define Thresholds
thresholds <- list()</pre>
for(i in 1:p) thresholds[[i]] <- matrix(0, nrow = n_timepoints, ncol = level[i])</pre>
# ---- 2) Sample cases ----
set.seed(1)
dlist <- tvmgmsampler(factors = factors,</pre>
                      interactions = interactions,
                      thresholds = thresholds,
                      type = type,
                       level = level,
                       nIter = 150,
```

pbar = TRUE)

```
# ---- 3) Check Marginals ----
dat <- dlist$data[1:round(n_timepoints/2),]</pre>
table(dat[,1], dat[,2], dat[,3])
dat <- dlist$data[round(n_timepoints/2):n_timepoints,]</pre>
table(dat[,1], dat[,2], dat[,3])
# Observation: much stronger effect in second hald of the time-series,
# which is what we expect
# ---- 4) Recover model from sampled cases ----
set.seed(1)
tvmgm_obj <- tvmgm(data = dlist$data,</pre>
                   type = type,
                   level = level,
                   estpoints = seq(0, 1, length = 15),
                   bandwidth = .2,
                   k = 3,
                   lambdaSel = "CV",
                   ruleReg = "AND")
tvmgm_obj$interactions$indicator
# Seems very difficult to recover this time-varying 3-way binary interaction
# See also the corresponding problems in the examples of ?mgmsampler
# For more examples see https://github.com/jmbh/mgmDocumentation
## End(Not run)
```

tvmvar

Estimating time-varying Mixed Vector Autoregressive Model (mVAR)

# Description

Estimates time-varying Mixed Vector Autoregressive Model (mVAR) via elastic-net regularized kernel smoothed Generalized Linear Models

# Usage

```
tvmvar(data, type, level, timepoints, estpoints, bandwidth, ...)
```

#### **Arguments**

data n x p data matrix.

type p vector indicating the type of variable for each column in data: "g" for Gaus-

sian, "p" for Poisson, "c" for categorical.

level p vector indicating the number of categories of each variable. For continuous

variables set to 1.

timepoints A strictly increasing numeric vector of length nrow(data) indicating time points

for the measurements in data. If timepoints is not specified, it is assumed that the time points are equally spaced. For details, see Haslbeck and Waldorp

(2018).

estpoints Vector indicating estimation points on interval [0, 1]. Note that we define this

unit interval on the entire time series. This also includes measurements that are excluded because not enough previous measurements are available to fit the model. This ensures that the a model estimated at, for example, estimation point 0.15 is actually estimated on data close to data points around this time point. See Haslbeck and Waldorp (2018) Section 2.5 and 3.4 for a detailed description.

bandwidth We use a gaussian density on the unit time-interval [0,1] to determine the weights

for each observation at each estimated time point. The bandwidth specifies the standard deviation the Gaussian density. To get some intuition, which bandwidth results in the combination of how many data close in time one can plot Gaussians on [0,1] for different bandwidths. The bandwidth can also be selected

in a data driven way using the function (see bwSelect).

... Arguments passed to mvar, specifying how each single model should be esti-

mated. See ?mvar.

# **Details**

Estimates a sequence of mVAR models at the time points specified at the locations specified via estpoints. tvmvar() is a wrapper around mvar() and estimates a series of MGM with different weightings which are defined by the estimation locations in estpoints and the banwdith parameter specified in bandwidth. For details see Haslbeck and Waldorp (2018)

#### Value

A list with the following entries:

call Contains all provided input arguments. If saveData = TRUE, it also contains the

data.

wadj A p x p x n\_lags x S array, where n\_lags is the number of specified lags in lags

(see ?mvar) and S is the number of estimation points specified in estpoints. For instance, wadj[1, 2, 1, 10] is the cross-lagged predicting variable 1 at time point t by variable 2 at time point t - z, where z is specified by the first lag specified in lags (see ?mvar), in the model estimated at estimation point 10.

signs Has the same structure as wadj and specifies the signs corresponding to the

parameters in wadj, if defined. 1/-1 indicate positive and negative relationships, respectively. 0 indicates that no sign is defined, which is the case for interactions

that involve a categorical variable where an interaction can have more than one parameter. If binarySign = TRUE, a sign is calculated for interactions between binary variables and binary and continuous variables, where the interaction is still defined by one parameter and hence a sign can be specified. NA indicates that the corresponding parameter in wadj is zero. See also ?mvar.

intercepts

A list with S entries, where S is the number of estimated time points. Each entry of that list contains a list p entries with the intercept/thresholds for each node in the network. In case a given node is categorical with m categories, there are m thresholds for this variable.

tvmodels

Contains the mVAR model estimated by mvar() at each time point specified via estpoints. See ?mvar for a detailed description of this output.

# Author(s)

Jonas Haslbeck <jonashaslbeck@gmail.com>

#### References

Haslbeck, J. M. B., & Waldorp, L. J. (2020). mgm: Estimating time-varying Mixed Graphical Models in high-dimensional Data. Journal of Statistical Software, 93(8), pp. 1-46. DOI: 10.18637/jss.v093.i08

# **Examples**

```
## Not run:
## We set up the same model as in the example of mvar(), but
## specify one time-varying parameter, and try to recover it with
## tvmvar()
# a) Specify time-varying VAR model
p <- 6 # Six variables
type <- c("c", "c", "c", "g", "g") # 4 categorical, 2 gaussians
level \leftarrow c(2, 2, 4, 4, 1, 1) # 2 categoricals with 2 categories, 2 with 5
max_level <- max(level)</pre>
n_timepoints <- 4000
lags <- c(1, 3, 9) # include lagged effects of order 1, 3, 9
n_lags <- length(lags)</pre>
# Specify thresholds
thresholds <- list()</pre>
thresholds[[1]] <- matrix(0, ncol=level[1], nrow=n_timepoints)</pre>
thresholds[[2]] <- matrix(0, ncol=level[2], nrow=n_timepoints)</pre>
thresholds[[3]] <- matrix(0, ncol=level[3], nrow=n_timepoints)</pre>
thresholds[[4]] <- matrix(0, ncol=level[4], nrow=n_timepoints)</pre>
thresholds[[5]] <- matrix(0, ncol=level[5], nrow=n_timepoints)</pre>
thresholds[[6]] <- matrix(0, ncol=level[6], nrow=n_timepoints)</pre>
```

```
# Specify standard deviations for the Gaussians
sds <- matrix(NA, ncol=p, nrow=n_timepoints)</pre>
sds[, 5:6] <- 1
# Create coefficient array
coefarray <- array(0, dim=c(p, p, max_level, max_level, n_lags, n_timepoints))</pre>
# a.1) interaction between continuous 5<-6, lag=3
coefarray[5, 6, 1, 1, 2, ] <- seq(0, .4, length = n_timepoints) # only time-varying parameter</pre>
# a.2) interaction between 1<-3, lag=1
m1 <- matrix(0, nrow=level[2], ncol=level[4])</pre>
m1[1,1:2] <- 1
m1[2,3:4] <- 1
\label{eq:coefarray} \mbox{\tt [1, 3, 1:level[2], 1:level[4], 1, ] <- m1 \# constant across time}
# a.3) interaction between 1<-5, lag=9</pre>
coefarray[1, 5, 1:level[1], 1:level[5], 3, ] \leftarrow c(0, 1) \# constant across time
# b) Sample
set.seed(1)
dlist <- tvmvarsampler(coefarray = coefarray,</pre>
                        lags = lags,
                        thresholds = thresholds,
                        sds = sds,
                        type = type,
                        level = level,
                        pbar = TRUE)
# c.1) Recover: stationary
set.seed(1)
mvar_obj <- mvar(data = dlist$data,</pre>
                  type = type,
                  level = level,
                  lambdaSel = "CV",
                  lags = c(1, 3, 9),
                  signInfo = FALSE)
# Did we recover the true parameters?
mvar_obj$wadj[5, 6, 2] # cross-lagged effect of 6 on 5 over lag lags[2] (lag 3)
mvar_obj$wadj[1, 3, 1] # cross-lagged effect of 3 on 1 over lag lags[1] (lag 1)
mvar_obj$wadj[1, 5, 3] # cross-lagged effect of 1 on 5 over lag lags[3] (lag 9)
# c.2) Recover: time-varying
set.seed(1)
mvar_obj <- tvmvar(data = dlist$data,</pre>
                    type = type,
                    level = level,
                    estpoints = seq(0, 1, length=10),
                    bandwidth = .15,
                    lambdaSel = "CV",
                    lags = c(1, 3, 9),
```

```
signInfo = FALSE)
# Did we recover the true parameters?
mvar_obj$wadj[5, 6, 2, ] # true sort of recovered
mvar_obj$wadj[1, 3, 1, ] # yes
mvar_obj$wadj[1, 5, 3, ] # yes
# Plotting parameter estimates over time
plot(mvar_obj$wadj[5, 6, 2, ],
     type="l", ylim=c(-.2,.7),
     lwd=2, ylab="Parameter value", xlab="Estimation points")
lines(mvar_obj$wadj[1, 3, 1, ], col="red", lwd=2)
lines(mvar_obj$wadj[1, 5, 3, ], col="blue", lwd=2)
legend("bottomright", c("5 <-- 6", "1 <-- 3", "1 <-- 5"),
       lwd = c(2,2,2), col=c("black", "red", "blue"))
# d) Predict values / compute nodewise error
mvar_pred_w <- predict.mgm(object=mvar_obj,</pre>
                           data=dlist$data,
                           tvMethod = "weighted")
mvar_pred_cM <- predict.mgm(object=mvar_obj,</pre>
                            data=dlist$data,
                            tvMethod = "closestModel")
mvar_pred_w$errors
mvar_pred_cM$errors
# For more examples see https://github.com/jmbh/mgmDocumentation
## End(Not run)
```

tvmvarsampler

Sampling from a time-varying mixed VAR model

# **Description**

Function to sample from a time-varying mixed VAR (mVAR) model

# Usage

# Arguments

coefarray  $A p x p x max(level) x max(level) x n_lags x N array, where p are the number of$ 

variables, level is the input argument level and n\_lags is the number of specified lags in lags, so n\_lags = length(n\_lags), and N is the number of time points in the time series. The first four dimensions specify the parameters involved in the cross-lagged effects of the lag specified in the 5th dimension. I.e. coefarray[5, 6, 1, 1, 3, 100] indicates the cross-lagged effect of variable 6 on variable 5 (if both are continuous), for the third lag specified in lags at time point 100. If variable 1 and 3 are categorical with m = 2 and = 4 categories, respectively, then coefarray[1, 3, 1:2, 1:4, 1, 250] indicates the m\*s=8 parameters specifying this interaction for the first lag specified in lags at time point 250. See the examples

below for an illustration.

lags A vector indicating the lags in the mVAR model. E.g. lags = c(1,4,9) spec-

ifies lags of order 1, 3, 9. The number of specified lags has to match the 5th

dimension in coefarray.

thresholds A list with p entries, each consisting of a matrix indicating a threshold for each

category of the given variable (column) and time point (row). For continuous

variable, the matrix has 1 column.

sds A N x p matrix specifying the standard deviation of Gaussian variables (columns)

at each time point (rows)If non-Gaussian variables are included in the mVAR

model, the corresponding columns are ignored.

type p vector indicating the type of variable for each column in data. "g" for Gaus-

sian, "p" for Poisson, "c" for categorical.

level p vector indicating the number of categories of each variable. For continuous

variables set to 1.

pbar = TRUE, a progress bar is shown.

#### **Details**

We sample from the mVAR model by separately sampling from its corresponding p conditional distributions.

# Value

A list with two entries:

call The function call

data The sampled n x p data matrix

# Author(s)

Jonas Haslbeck <jonashaslbeck@gmail.com>

#### References

Haslbeck, J. M. B., & Waldorp, L. J. (2020). mgm: Estimating time-varying Mixed Graphical Models in high-dimensional Data. Journal of Statistical Software, 93(8), pp. 1-46. DOI: 10.18637/jss.v093.i08

# **Examples**

```
## Not run:
## We specify a tymvar model, sample from it and recover it
# a) Set up time-varying mvar model
p <- 6 # Six variables</pre>
type <- c("c", "c", "c", "c", "g", "g") # 4 categorical, 2 gaussians
level <- c(2, 2, 4, 4, 1, 1) # 2 categoricals with 2 categories, 2 with 5
max_level <- max(level)</pre>
lags <- c(1, 3, 9) # include lagged effects of order 1, 3, 9
n_lags <- length(lags)</pre>
N <- 5000
# Specify thresholds
thresholds <- list()</pre>
thresholds[[1]] <- matrix(0, ncol=2, nrow=N)</pre>
thresholds[[2]] <- matrix(0, ncol=2, nrow=N)</pre>
thresholds[[3]] <- matrix(0, ncol=4, nrow=N)</pre>
thresholds[[4]] <- matrix(0, ncol=4, nrow=N)</pre>
thresholds[[5]] <- matrix(0, ncol=1, nrow=N)</pre>
thresholds[[6]] <- matrix(0, ncol=1, nrow=N)</pre>
# Specify standard deviations for the Gaussians
sds <- matrix(NA, ncol=6, nrow=N)</pre>
sds[,5:6] <- 1
# Create coefficient array
coefarray <- array(0, dim=c(p, p, max_level, max_level, n_lags, N))</pre>
# a.1) interaction between continuous 5<-6, lag=3
coefarray[5, 6, 1, 1, 2, ] \leftarrow c(rep(.5, N/2), rep(0, N/2))
# a.2) interaction between 1<-3, lag=1
m1 <- matrix(0, nrow=level[2], ncol=level[4])</pre>
m1[1, 1:2] <- 1
m1[2, 3:4] <- 1
coefarray[1, 3, 1:level[2], 1:level[4], 1, ] <- m1</pre>
# a.3) interaction between 1<-5, lag=9
coefarray[1, 5, 1:level[1], 1:level[5], 3, ] <- c(0, 1)</pre>
dim(coefarray)
# b) Sample
set.seed(1)
dlist <- tvmvarsampler(coefarray = coefarray,</pre>
                         lags = lags,
```

```
thresholds = thresholds,
                       sds = sds,
                       type = type,
                       level = level,
                       pbar = TRUE)
# c) Recover: time-varying mVAR model
set.seed(1)
tvmvar_obj <- tvmvar(data = dlist$data,</pre>
                     type = type,
                     level = level,
                     lambdaSel = "CV",
                     lags = c(1, 3, 9),
                     estpoints = seq(0, 1, length=10),
                     bandwidth = .05)
tvmvar_obj$wadj[5, 6, 2, ] # parameter goes down, as specified
tvmvar_obj$wadj[1, 3, 1, ]
tvmvar_obj$wadj[1, 5, 3, ]
# For more examples see https://github.com/jmbh/mgmDocumentation
## End(Not run)
```

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