Package 'marqLevAlg'

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Type Package

Title A Parallelized General-Purpose Optimization Based on
Marquardt-Levenberg Algorithm

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Author Viviane Philipps, Cecile Proust-
Lima, Melanie Prague, Boris Hejblum, Daniel Commenges, Amadou Diakite

Maintainer Viviane Philipps <viviane.philipps@u-bordeaux.fr>

Depends R (>= 3.5.0)

LazyLoad yes

LazyData true

Description This algorithm provides a numerical solution to the
problem of minimizing (or maximizing) a function. It is particularly suited for complex prob-
lems and more efficient than
the Gauss-Newton-like algorithm when starting from points very
far from the final minimum (or maximum). Each iteration is parallelized and convergence re-
lies on a stringent stopping criterion based on the first and second derivatives.

License GPL (>= 2.0)

BugReports http://github.com/VivianePhilipps/marqLevAlgParallel/issues

NeedsCompilation yes

Imports doParallel, foreach

Suggests microbenchmark

RoxygenNote 6.0.1

Repository CRAN

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R topics documented:

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marqLevAlg-package   *A parallelized general-purpose optimization based on Marquardt-Levenberg algorithm*

Description

This algorithm provides a numerical solution to the problem of miniminzing/maximizing a function. This is more efficient than the Gauss-Newton-like algorithm when starting from points very far from the final minimum/maximum. A new convergence test is implemented (RDM) in addition to the usual stopping criterion : stopping rule is when the gradients are small enough in the parameters metric (GH^-1G).

Details

Package:	marqLevAlg
Type:	Package
Version:	2.0.2
Date:	2020-03-30
License:	GPL (>= 2.0)
LazyLoad:	yes

This algorithm provides a numerical solution to the problem of optimizing a function. This is more efficient than the Gauss-Newton-like algorithm when starting from points very far from the final maximum. A new convergence test is implemented (RDM) in addition to the usual stopping criterion : stopping rule is when the gradients are small enough in the parameters metric (GH-1G).

Author(s)

Viviane Philipps, Cecile Proust-Lima, Boris Hejblum, Melanie Prague, Daniel Commenges, Amadou Diakite

References

marqLevAlg Algorithm

Donald W. marquardt An algorithm for Least-Squares Estimation of Nonlinear Parameters. Journal of the Society for Industrial and Applied Mathematics, Vol. 11, No. 2. (Jun, 1963), pp. 431-441.

Convergence criteria : Relative distance to Maximum

Commenges D. Jacqmin-Gadda H. Proust C. Guedj J. A Newton-like algorithm for likelihood maximization : the robust-variance scoring algorithm arxiv:math/0610402v2 (2006)

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dataEx *Simulated dataset*

Description

Sample of 500 subjects simulated according to a linear mixed model. The fixed part of the model included an intercept, 2 natural cubic splines on time and their interactions with time-independent covariates $X1$, $X2$ and $X3$. A random intercept and a independant error term were also inclued.

Format

A data frame with 2429 observations on the following 6 variables.

i subject identification number

t time of measurement

X1 binary covariate

X2 continous Gaussian standard variable

X3 continous Gaussian variable

Y longitudinal outcome

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deriva *Numerical derivatives*

Description

The function computes the first derivates and the information score matrix. Central finite-differences and forward finite-differences are used for the first and second derivatives respectively.

Usage

```
deriva(nproc = 1, b, funcpa, .packages = NULL, ...)
```

Arguments

`nproc`	number of processors for parallel computing
`b`	value of parameters to be optimized over
`funcpa`	function to be minimized (or maximized), with argument the vector of parameters over which minimization isto take place. It should return a scalar result.
`.packages`	character vector of packages that funcpa depends on
`...`	other arguments of the funcpa function

Value

`v`	vector containing the upper part of the information score matrix and the first derivatives
`rl`	the value of the funcpa function at point b

Author(s)

Viviane Philipps, Boris Hejblum, Cecile Proust-Lima, Daniel Commenges

References

Donald W. Marquardt An algorithm for Least-Squares Estimation of Nonlinear Parameters. Journal of the Society for Industrial and Applied Mathematics, Vol. 11, No. 2. (Jun, 1963), pp. 431-441.

Examples

```
b <- 0.1
f <- function(b){return((2*b[1]**2+3*b[1]))}
d <- deriva(b=b,funcpa=f)
```

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deriva_grad	*Numerical derivatives of the gradient function*

Description

The function computes the information score matrix in the case where the first derivatives of the function to optimize are analytically known. Therefore, minus the derivatives of the gradient are computed by central finite differences.

Usage

```
deriva_grad(nproc = 1, b, grad, .packages = NULL, ...)
```

Arguments

nproc	number of processors for parallel computing
b	value of parameters to be optimized over
grad	the gradient of the function to be minimized (or maximized)
.packages	character vector of packages that grad depends on
...	other arguments of the grad function

Value

hessian	vector containing the upper part of the information score matrix

Author(s)

Viviane Philipps, Boris Hejblum, Cecile Proust-Lima, Daniel Commenges

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ForInternalUse	*For internal use only ...*

Description

For internal use only ...

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gradLMM	*Gradient of the log-likelihood of a linear mixed model with random intercept*

Description

Gradient of the log-likelihood of a linear mixed model with random intercept

Usage

```
gradLMM(b, Y, X, ni)
```

Arguments

b	numeric vector specifying the parameter's values in the following order : first the fixed effects and then the standard deviation of the random intercept and of the independent error
Y	numeric vector including the dependent outcome vector ordered by subject
X	numeric matrix including the covariates
ni	interger vector giving the number of repeated measures for each subject

Value

a vector containing the gradient of the log-likelihood of the linear mixed model at point b

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loglikLMM	*Log-likelihood of a linear mixed model with random intercept*

Description

Log-likelihood of a linear mixed model with random intercept

Usage

```
loglikLMM(b, Y, X, ni)
```

Arguments

b	numeric vector specifying the parameter's values in the following order : first the fixed effects and then the standard deviation of the random intercept and of the independent error
Y	numeric vector including the dependent outcome vector ordered by subject
X	numeric matrix including the covariates
ni	interger vector giving the number of repeated measures for each subject

Value

the log-likelihood of the linear mixed model at point b

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marqLevAlg	*A parallelized general-purpose optimization based on Marquardt-Levenberg algorithm*

Description

This algorithm provides a numerical solution to the problem of optimizing a function. This is more efficient than the Gauss-Newton-like algorithm when starting from points very far from the final maximum. A new convergence test is implemented (RDM) in addition to the usual stopping criterion : stopping rule is when the gradients are small enough in the parameters metric (GH-1G).

Usage

```
marqLevAlg(b, m = FALSE, fn, gr = NULL, hess = NULL, maxiter = 500,
  epsa = 0.001, epsb = 0.001, epsd = 0.01, digits = 8,
  print.info = FALSE, blinding = TRUE, multipleTry = 25, nproc = 1,
  clustertype = NULL, file = "", .packages = NULL, minimize = TRUE, ...)

mla(b, m = FALSE, fn, gr = NULL, hess = NULL, maxiter = 500,
  epsa = 0.001, epsb = 0.001, epsd = 0.01, digits = 8,
  print.info = FALSE, blinding = TRUE, multipleTry = 25, nproc = 1,
  clustertype = NULL, file = "", .packages = NULL, minimize = TRUE, ...)
```

Arguments

b	an optional vector containing the initial values for the parameters. Default is 0.1 for every parameter.
m	number of parameters. Optional if b is specified.
fn	the function to be optimized, with first argument the vector of parameters over which optimization is to take place (argument b). It should return a scalar result.
gr	a function to return the gradient value for a specific point. If missing, finite-difference approximation will be used.
hess	a function to return the hessian matrix for a specific point. If missing, finite-difference approximation will be used.
maxiter	optional maximum number of iterations for the marqLevAlg iterative algorithm. Default is 500.
epsa	optional threshold for the convergence criterion based on the parameter stability. Default is 0.001.
epsb	optional threshold for the convergence criterion based on the objective function stability. Default is 0.001.
epsd	optional threshold for the relative distance to maximum. This criterion has the nice interpretation of estimating the ratio of the approximation error over the statistical error, thus it can be used for stopping the iterative process whathever the problem. Default is 0.01.
digits	number of digits to print in outputs. Default value is 8.
print.info	logical indicating if information about computation should be reported at each iteration. Default value is FALSE.
blinding	logical. Equals to TRUE if the algorithm is allowed to go on in case of an infinite or not definite value of function. Default value is FALSE.
multipleTry	integer, different from 1 if the algorithm is allowed to go for the first iteration in case of an infinite or not definite value of gradients or hessian. As many tries as requested in multipleTry will be done by changing the starting point of the algorithm. Default value is 25.
nproc	number of processors for parallel computing
clustertype	one of the supported types from [makeCluster]
file	optional character giving the name of the file where the outputs of each iteration should be written (if print.info=TRUE).
.packages	for parallel setting only, packages used in the fn function
minimize	logical indicating if the fn function should be minimized or maximized. By default minimize=TRUE, the function is minimized.
...	other arguments of the fn, gr and hess functions

Details

Convergence criteria are very strict as they are based on derivatives of the objective function in addition to the parameter and objective function stability. In some cases, the program may not converge and reach the maximum number of iterations fixed at 500. In this case, the user should

check that parameter estimates at the last iteration are not on the boundaries of the parameter space. If the parameters are on the boundaries of the parameter space, the identifiability of the model should be assessed. If not, the program should be run again with other initial values, with a higher maximum number of iterations or less strict convergence tolerances.

Value

`cl`	summary of the call to the function marqLevAlg.
`ni`	number of marqLevAlg iterations before reaching stopping criterion.
`istop`	status of convergence: =1 if the convergence criteria were satisfied, =2 if the maximum number of iterations was reached, =4 if the algorithm encountered a problem in the function computation.
`v`	vector containing the upper triangle matrix of variance-covariance estimates at the stopping point.
`grad`	vector containing the gradient at the stopping point.
`fn.value`	function evaluation at the stopping point.
`b`	stopping point value.
`ca`	convergence criteria for parameters stabilisation.
`cb`	convergence criteria for function stabilisation.
`rdm`	convergence criteria on the relative distance to minimum (or maximum).
`time`	a running time.

Author(s)

Melanie Prague, Viviane Philipps, Cecile Proust-Lima, Boris Hejblum, Daniel Commenges, Amadou Diakite

References

marqLevAlg Algorithm

Donald W. marquardt An algorithm for Least-Squares Estimation of Nonlinear Parameters. Journal of the Society for Industrial and Applied Mathematics, Vol. 11, No. 2. (Jun, 1963), pp. 431-441.

Convergence criteria : Relative distance to Minimim (or Maximum)

Commenges D. Jacqmin-Gadda H. Proust C. Guedj J. A Newton-like algorithm for likelihood maximization the robust-variance scoring algorithm arxiv:math/0610402v2 (2006)

Examples

```
### example 1
### initial values
b <- c(8,9)
### your function
f1 <- function(b){
return(-4*(b[1]-5)^2-(b[2]-6)^2)
```

```
}
### gradient
g1 <- function(b){
    return(c(-8*(b[1]-5),-2*(b[2]-6)))
}
## Call
test1 <- mla(b=b, fn=f1, minimize=FALSE)

## Not run:
microbenchmark::microbenchmark(mla(b=b, fn=f1, minimize=FALSE),
                              mla(b=b, fn=f1, minimize=FALSE, nproc=2),
                              mla(b=b, fn=f1, gr=g1, minimize=FALSE),
                              mla(b=b, fn=f1, gr=g1, minimize=FALSE, nproc=2),
                              times=10)

## End(Not run)



### example 2
## initial values
b <- c(3,-1,0,1)
## your function
f2 <- function(b){
return(-((b[1]+10*b[2])^2+5*(b[3]-b[4])^2+(b[2]-2*b[3])^4+10*(b[1]-b[4])^4))
}
## Call
test2 <- mla(b=b, fn=f2, minimize=FALSE)
test2$b

test2_par <- mla(b=b, fn=f2, minimize=FALSE, nproc=2)
test2_par$b

## Not run:
microbenchmark::microbenchmark(mla(b=b, fn=f2, minimize=FALSE),
                              mla(b=b, fn=f2, minimize=FALSE, nproc=2),
                              times=10)

## End(Not run)



## Not run:
### example 3 : a linear mixed model
## the log-likelihood is implemented in the loglikLMM function
## the gradient is implemented in the gradLMM function

## data
Y <- dataEx$Y
X <- as.matrix(cbind(1,dataEx[,c("t","X1","X3")],dataEx$t*dataEx$X1))
ni <- as.numeric(table(dataEx$i))

## initial values
binit <- c(0,0,0,0,0,1,1)
```

```
## estimation in sequential mode, with numeric derivatives
estim <- marqLevAlg(b=binit, fn=loglikLMM, minimize=FALSE, X=X, Y=Y, ni=ni)
## estimation in parallel mode, with numeric derivatives
estim2 <- marqLevAlg(b=binit, fn=loglikLMM, minimize=FALSE, X=X, Y=Y, ni=ni,
nproc=2, clustertype="FORK")
## estimation in sequential mode, with analytic gradient
estim3 <- marqLevAlg(b=binit, fn=loglikLMM, gr=gradLMM, minimize=FALSE, X=X, Y=Y, ni=ni)
## estimation in parallel mode, with analytic gradient
estim4 <- marqLevAlg(b=binit, fn=loglikLMM, gr=gradLMM, minimize=FALSE, X=X, Y=Y, ni=ni,
nproc=2, clustertype="FORK")

## End(Not run)
```

---

print.marqLevAlg   *Summary of a* marqLevAlg *object*

Description

The function provides a summary of a marqLevAlg optimisation.

Usage

```
## S3 method for class 'marqLevAlg'
print(x, digits, ...)
```

Arguments

x	an marqLevAlg object.
digits	Number of digits to print in outputs. Default value is 8.
...	other unusued arguments.

Author(s)

D. Commenges - M. Prague - A. Diakite

See Also

marqLevAlg, summary.marqLevAlg

Examples

```
f1 <- function(b){
return(4*(b[1]-5)^2+(b[2]-6)^2)
}
test.marq <- marqLevAlg(b=c(8,9),m=2,maxiter=100,epsa=0.001,epsb=0.001,
epsd=0.001,fn=f1)

test.marq
```

summary.marqLevAlg   *summary of optimization.*

Description

A short summary of parameters estimates by marqLevAlg algorithm.

Usage

```
## S3 method for class 'marqLevAlg'
summary(object, digits, ...)
```

Arguments

object	a marqLevAlg object.
digits	Number of digits to print in outputs. Default value is 8.
...	other unusued arguments.

Author(s)

D. Commenges - M. Prague - A. Diakite

See Also

[marqLevAlg](#), [print.marqLevAlg](#)

Examples

```
f1 <- function(b){
return(4*(b[1]-5)^2+(b[2]-6)^2)
}
test.marq <- marqLevAlg(b=c(8,9),m=2,maxiter=100,epsa=0.001,epsb=0.001,
epsd=0.001,fn=f1)

summary(test.marq)
```

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