

Package ‘groc’

February 7, 2020

Version 1.0.7

Date 2020-02-07

Title Generalized Regression on Orthogonal Components

Author Pierre Lafaye De Micheaux [aut, cre],

Martin Bilodeau [aut],

Jiahui Wang [cph] (covRob and related functions from orphaned package robust),

Ruben Zamar [cph] (covRob and related functions from orphaned package robust),

Alfio Marazzi [cph] (covRob and related functions from orphaned package robust),

Victor Yohai [cph] (covRob and related functions from orphaned package robust),

Matias Salibian-Barrera [cph] (covRob and related functions from orphaned package robust),

Ricardo Maronna [cph] (covRob and related functions from orphaned package robust),

Eric Zivot [cph] (covRob and related functions from orphaned package robust),

David Rocke [cph] (covRob and related functions from orphaned package robust),

Doug Martin [cph] (covRob and related functions from orphaned package robust),

Martin Maechler [cph] (covRob and related functions from orphaned package robust),

Kjell Konis [cph] (covRob and related functions from orphaned package robust)

Maintainer Pierre Lafaye De Micheaux <lafaye@unsw.edu.au>

Imports pls, mgcv, robustbase, MASS

Depends rrcov

Suggests pppls

Description Robust multiple or multivariate linear regression, nonparametric regression on orthogonal components, classical or robust partial least squares models.

License GPL (>= 2)

LazyLoad yes**NeedsCompilation** yes**Repository** CRAN**Date/Publication** 2020-02-07 01:10:06 UTC**R topics documented:**

corrob	2
covRob	3
covrob	5
covRob.control	6
dcov	7
groc	8
groc.fit	14
grocCrossval	16
model.frame.groc	17
plot.groc	18
predict.groc	19
prim7	20
summary.groc	21
Index	23

corrob	<i>Robust correlation measure</i>
--------	-----------------------------------

Description

Compute robust estimates of the correlation between two variables using the Orthogonalized Gnanadesikan-Kettenring pairwise estimator.

Usage

```
corrob(t, u)
```

Arguments

t	a numeric vector containing the data for the first variable.
u	a numeric vector containing the data for the second variable.

Details

This function uses the `covRob` function from the **robust** package.

Value

Value of the robust correlation.

Author(s)

Martin Bilodeau (<bilodeau@dms.umontreal.ca>) and Pierre Lafaye de Micheaux (<lafaye@unsw.edu.au>)

References

Jiahui Wang, Ruben Zamar, Alfio Marazzi, Victor Yohai, Matias Salibian-Barrera, Ricardo Maronna, Eric Zivot, David Rocke, Doug Martin, Martin Maechler and Kjell Konis. (2013). robust: Robust Library. R package version 0.4-11. <https://CRAN.R-project.org/package=robust>

See Also

[covrob](#), [dcov](#)

Examples

```
data(stackloss)
corrob(stackloss$Air.Flow, stackloss$Water.Temp)
```

 covRob

Robust Covariance/Correlation Matrix Estimation

Description

Compute robust estimates of multivariate location and scatter.

Usage

```
covRob(data, corr = FALSE, distance = TRUE, na.action = na.fail,
        estim = "auto", control = covRob.control(estim, ...), ...)
```

Arguments

<code>data</code>	a numeric matrix or data frame containing the data.
<code>corr</code>	a logical flag. If <code>corr = TRUE</code> then the estimated correlation matrix is computed.
<code>distance</code>	a logical flag. If <code>distance = TRUE</code> the squared Mahalanobis distances are computed.
<code>na.action</code>	a function to filter missing data. The default <code>na.fail</code> produces an error if missing values are present. An alternative is <code>na.omit</code> which deletes observations that contain one or more missing values.
<code>estim</code>	a character string specifying the robust estimator to be used. The choices are: "mcd" for the Fast MCD algorithm of Rousseeuw and Van Driessen, "weighted" for the Reweighted MCD, "donostah" for the Donoho-Stahel projection based estimator, "M" for the constrained M estimator provided by Rocke, "pairwiseQC" for the orthogonalized quadrant correlation pairwise estimator, and "pairwiseGK" for the Orthogonalized Gnanadesikan-Kettenring pairwise estimator. The default "auto" selects from "donostah", "mcd", and "pairwiseQC" with the goal of producing a good estimate in a reasonable amount of time.

`control` a list of control parameters to be used in the numerical algorithms. See `covRob.control` for the possible control parameters and their default settings. This argument is ignored when `estim = "auto"`.

... control parameters may be passed directly when `estim != "auto"`.

Details

This function was part of the 'robust' package and it has been copied to the current package due to an ORPHANED Maintainer.

The `covRob` function selects a robust covariance estimator that is likely to provide a *good* estimate in a reasonable amount of time. Presently this selection is based on the problem size. The Donoho-Stahel estimator is used if there are less than 1000 observations and less than 10 variables or less than 5000 observations and less than 5 variables. If there are less than 50000 observations and less than 20 variables then the MCD is used. For larger problems, the Orthogonalized Quadrant Correlation estimator is used.

The MCD and Reweighted-MCD estimates (`estim = "mcd"` and `estim = "weighted"` respectively) are computed using the `covMcd` function in the `robustbase` package. By default, `covMcd` returns the reweighted estimate; the actual MCD estimate is contained in the components of the output list prefixed with `raw`.

The M estimate (`estim = "M"`) is computed using the `covMest` function in the `rrcov` package. For historical reasons the Robust Library uses the MCD to compute the initial estimate.

The Donoho-Stahel (`estim = "donostah"`) estimator is computed using the `CovSde` function provided in the `rrcov` package.

The pairwise estimators (`estim = "pairwisegk"` and `estim = "pairwiseqc"`) are computed using the `CovOgk` function in the `rrcov` package.

Value

an object of class "covRob" with components:

`call` an image of the call that produced the object with all the arguments named.

`cov` a numeric matrix containing the final robust estimate of the covariance/correlation matrix.

`center` a numeric vector containing the final robust estimate of the location vector.

`dist` a numeric vector containing the squared Mahalanobis distances computed using robust estimates of covariance and location contained in `cov` and `center`. If `distance = FALSE` this element will be missing.

`raw.cov` a numeric matrix containing the initial robust estimate of the covariance/correlation matrix. If there is no initial robust estimate then this element is set to NA.

`raw.center` a numeric vector containing the initial robust estimate of the location vector. If there is no initial robust estimate then this element is set to NA.

`raw.dist` a numeric vector containing the squared Mahalanobis distances computed using the initial robust estimates of covariance and location contained in `raw.cov` and `raw.center`. If `distance = FALSE` or if there is no initial robust estimate then this element is set to NA.

corr	a logical flag. If corr = TRUE then cov and raw.cov contain robust estimates of the correlation matrix of data.
estim	a character string containing the name of the robust estimator.
control	a list containing the control parameters used by the robust estimator.

Note

Version 0.3-8 of the Robust Library: all of the functions originally contributed by the S-Plus Robust Library have been replaced by dependencies on the robustbase and rrcov packages. Computed results may differ from earlier versions of the Robust Library. In particular, the MCD estimators are now adjusted by a small sample size correction factor. Additionally, a bug was fixed where the final MCD covariance estimate produced with estim = "mcd" was not rescaled for consistency.

References

- R. A. Maronna and V. J. Yohai (1995) The Behavior of the Stahel-Donoho Robust Multivariate Estimator. *Journal of the American Statistical Association* **90** (429), 330–341.
- P. J. Rousseeuw and K. van Driessen (1999) A fast algorithm for the minimum covariance determinant estimator. *Technometrics* **41**, 212–223.
- D. L. Woodruff and D. M. Rocke (1994) Computable robust estimation of multivariate location and shape on high dimension using compound estimators. *Journal of the American Statistical Association*, **89**, 888–896.
- R. A. Maronna and R. H. Zamar (2002) Robust estimates of location and dispersion of high-dimensional datasets. *Technometrics* **44** (4), 307–317.

covrob	<i>Robust covariance measure</i>
--------	----------------------------------

Description

Compute robust estimates of the covariance between two variables using the robust tau estimate of univariate scale, as proposed by Maronna and Zamar (2002).

Usage

```
covrob(t, u)
```

Arguments

- | | |
|---|---|
| t | a numeric vector containing the data for the first variable. |
| u | a numeric vector containing the data for the second variable. |

Details

This function uses the [scaleTau2](#) function from the **robustbase** package.

Value

Value of the robust covariance.

Author(s)

Martin Bilodeau (<bilodeau@dms.umontreal.ca>) and Pierre Lafaye de Micheaux (<lafaye@unsw.edu.au>)

References

Maronna, R.A. and Zamar, R.H. (2002) Robust estimates of location and dispersion of high-dimensional datasets; *Technometrics* **44**(4), 307–317.

See Also

[corrob](#), [dcov](#)

Examples

```
data(stackloss)
covrob(stackloss$Air.Flow, stackloss$Water.Temp)
```

covRob.control

Control Parameters for Robust Covariance Estimation

Description

This function is used to create a list of control parameters for the underlying robust estimator used in the covRob function.

Usage

```
covRob.control(estim, ...)
```

Arguments

<code>estim</code>	a character vector of length one giving the name of the estimator to generate the control parameters for.
<code>...</code>	control parameters appropriate for the robust estimator specified in <code>estim</code> in the form <code>name = value</code> and separated by commas. Omitted parameters receive their default values.

Details

This function was part of the 'robust' package and it has been copied to the current package due to an ORPHANED Maintainer.

The control parameters are estimator specific. Information on the control parameters (and their default values) can be found in the help files of each of the robust covariance estimators.

Value

a list of control parameters appropriate for the robust estimator given in `estim`. The value of `estim` occupies the first element of the list.

See Also

This function is a utility function for `covRob`.

The underlying robust estimators are: `CovSde`, `covMcd` and `CovOgk`. Power-users should consider calling these functions directly.

Examples

```
mcd.control <- covRob.control("mcd", quan = 0.75, ntrial = 1000)

ds.control <- covRob.control("donostah", prob = 0.95)

qc.control <- covRob.control("pairwiseqc")
```

`dcov`*Distance covariance matrix.*

Description

Compute the distance covariance measure of Szekely, Rizzo, and Bakirov (2007) between two samples. Warning: Only valid to compute the distance covariance for two random variables X and Y. This means that X and Y cannot be random Vectors. If this is the case, consider the package **energy**.

Usage

```
dcov(x, y, Cpp = TRUE)
```

Arguments

<code>x</code>	data of first sample
<code>y</code>	data of second sample
<code>Cpp</code>	logical. If TRUE (the default), computations are performed using a C version of the code.

Details

See **energy**.

Value

returns the sample distance covariance.

Author(s)

Martin Bilodeau (<bilodeau@dms.umontreal.ca>) and Pierre Lafaye de Micheaux (<lafaye@unsw.edu.au>)

References

Szekely, G.J., Rizzo, M.L., and Bakirov, N.K. (2007), Measuring and Testing Dependence by Correlation of Distances, *Annals of Statistics*, Vol. 35 No. 6, pp. 2769-2794.
<http://dx.doi.org/10.1214/009053607000000505>

See Also

[covrob](#), [corrob](#)

Examples

```
data(stackloss)
dcov(stackloss$Air.Flow, stackloss$Water.Temp)
```

groc

groc method

Description

Generalized regression on orthogonal components.

Usage

```
## Default S3 method:
groc(formula, ncomp, data, subset, na.action, plsrob =
      FALSE, method = c("lm", "lo", "s", "lts"), D = NULL,
      gamma = 0.75, Nc = 10, Ng = 20, scale = FALSE, Cpp =
      TRUE, model = TRUE, x = FALSE, y = FALSE, sp = NULL, ...)
groc(...)
```

Arguments

formula	a model formula. Most of the lm formula constructs are supported. See below.
ncomp	the number of components (orthogonal components) to include in the model.
data	an optional data frame with the data to fit the model from.
subset	an optional vector specifying a subset of observations to be used in the fitting process.
na.action	a function which indicates what should happen when the data contain missing values.
plsrob	logical. If TRUE, we use the D=covrob measure of dependence with the least trimmed squares method="lts".

method	character giving the name of the method to use. The user can supply his own function. The methods available are linear models, "lm", local polynomials, "lo", smoothing splines, "s", and least trimmed squares, "lts".
D	function with two arguments, each one being a vector, which measures the dependence between two variables using n observations from them. If NULL, the covariance measure will be used. The user can supply his own function.
gamma	parameter used with the option <code>plsrob=TRUE</code> . It defines the quantile used to compute the "lts" regression. The default <code>gamma=0.75</code> gives a breakdown of 25% for a good compromise between robustness and efficiency. The value <code>gamma=0.5</code> gives the maximal breakdown of 50%.
Nc	Integer, Number of cycles in the grid algorithm.
Ng	Integer, Number of points for the grid in the grid algorithm.
scale	Logical, Should we scale the data.
Cpp	Logical, if TRUE this function will use a C++ implementation of the grid algorithm. The FALSE value should not be used, unless to get a better understanding of the grid algorithm or to compare the speed of computation between R and C++ versions of this algorithm
model	a logical. If TRUE, the model frame is returned.
x	a logical. If TRUE, the model matrix is returned.
y	a logical. If TRUE, the response is returned.
sp	A vector of smoothing parameters can be provided here. Smoothing parameters must be supplied in the order that the smooth terms appear in the model formula. Negative elements indicate that the parameter should be estimated, and hence a mixture of fixed and estimated parameters is possible. 'length(sp)' should be equal to 'ncomp' and corresponds to the number of underlying smoothing parameters.
...	further arguments to be passed to or from methods.

Value

Y	vector or matrix of responses.
fitted.values	an array of fitted values.
residuals	residuals
T	a matrix of orthogonal components (scores). Each column corresponds to a component.
R	a matrix of directions (loadings). Each column is a direction used to obtain the corresponding component (scores).
Gobjects	contain the objects produced by the fit of the responses on the orthogonal components.
Hobjects	contain the objects produced by the "lts" fit of each deflated predictors on the orthogonal components. Hobjects are produced when <code>plsrob=TRUE</code> .
B	matrix of coefficients produced by the "lm" fit of each deflated predictors on the last component. B is produced when <code>plsrob=FALSE</code> .

Xmeans	a vector of means of the X variables.
Ymeans	a vector of means of the Y variables.
D	Dependence measure used.
V	a matrix whose columns contain the right singular vectors of the data. Computed in the preprocessing to principal component scores when the number of observations is less than the number of predictors.
dnames	dimnames of 'fitted.values'
ncomp	the number of components used in the modelling.
method	the method used.
scale	Logical. TRUE if the responses have been scaled.
call	the function call.
terms	the model terms.
plsrob	Logical. If plsrob=TRUE, a robust partial least squares fit.
model	if model=TRUE, the model frame.

Author(s)

Martin Bilodeau (<bilodeau@dms.umontreal.ca>) and Pierre Lafaye de Micheaux (<lafaye@unsw.edu.au>) and Smail Mahdi (<smail.mahdi@cavehill.uwi.edu>)

References

Martin Bilodeau, Pierre Lafaye de Micheaux, Smail Mahdi (2015), The R Package groc for Generalized Regression on Orthogonal Components, *Journal of Statistical Software*, 65(1), 1-29, <http://www.jstatsoft.org/v65/i01/>

Examples

```
## Not run:
library(MASS)
#####
# Codes for Example 1 #
#####
require("groc")
data("wood")
out <- groc(y ~ x1 + x2 + x3 + x4 + x5, ncomp = 1, data = wood,
           D = corrob, method = "lts")
corrob(wood$y, fitted(out)) ^ 2
plot(out)

#####
# Codes for Example 2 #
#####
data("trees")
out <- groc(Volume ~ Height + Girth, ncomp = 1, D = spearman,
           method = "s", data = trees)
```

```

cor(trees$Volume, fitted(out)) ^ 2
plot(out$T, trees$Volume, xlab = "First component",
      ylab = "Volume", pch = 20)
lines(sort(out$T), fitted(out)[order(out$T)])
out <- boxcox(Volume ~ Height + Girth, data = trees,
              lambda = seq(-0.5, 0.5, length = 100), plotit = FALSE)
lambda <- out$x[which.max(out$y)]
out <- lm(Volume ^ lambda ~ Height + Girth, data = trees)
cor(trees$Volume, fitted(out)^(1/lambda)) ^ 2

#####
# Codes for Example 3 #
#####
data("wood")
plsr.out <- plsr(y ~ x1 + x2 + x3 + x4 + x5, data = wood)
groc.out <- groc(y ~ x1 + x2 + x3 + x4 + x5, data = wood)
apply(abs((fitted(plsr.out) - fitted(groc.out)) /
          fitted(plsr.out)), 3, max) * 100

#####
# Codes for Example 4 #
#####
set.seed(1)
n <- 200
x1 <- runif(n, -1, 1)
x2 <- runif(n, -1, 1)
y <- x1 * x2 + rnorm(n, 0, sqrt(.04))
data <- data.frame(x1 = x1, x2 = x2, y = y)
plsr.out <- plsr(y ~ x1 + x2, data = data)
groc.out <- groc(y ~ x1 + x2, D = dcov, method = "s", data = data)
plsr.v <- crossval(plsr.out, segment.type = "consecutive")
groc.v <- grocCrossval(groc.out, segment.type = "consecutive")
groc.v$validation$PRESS
plsr.v$validation$PRESS
gam.data <- data.frame(y = y, t1 = groc.out$T[, 1], t2 = groc.out$T[, 2])
gam.out <- gam(y ~ s(t1) + s(t2), data = gam.data)
par(mfrow = c(1, 2))
plot(gam.out)
par(mfrow = c(1, 1))
PRESS <- 0
for(i in 1 : 10){
  data.in <- data[-(((i - 1) * 20 + 1) : (i * 20)), ]
  data.out <- data[((i - 1) * 20 + 1) : (i * 20), ]
  ppr.out <- ppr(y ~ x1 + x2, nterms = 2, optlevel = 3, data = data.in)
  PRESS <- PRESS + sum((predict(ppr.out, newdata = data.out)-data.out$y) ^ 2)
}
PRESS

#####
# Codes for Example 5 #
#####
data("yarn")
dim(yarn$NIR)

```

```

n <- nrow(yarn)
system.time(plsr.out <- plsr(density ~ NIR, ncomp = n - 2, data = yarn))
system.time(groc.out <- groc(density ~ NIR, Nc = 20, ncomp = n - 2, data = yarn))
max(abs((fitted(plsr.out) - fitted(groc.out)) / fitted(plsr.out))) * 100
plsr.v <- crossval(plsr.out, segments = n, trace = FALSE)
plsr.v$validation$PRESS
groc.v <- grocCrossval(groc.out, segments = n, trace = FALSE)
groc.v$validation$PRESS
groc.v$validation$PREMAD

#####
# Codes for Example 6 #
#####
data("prim7")
prim7.out <- groc(X1 ~ ., ncomp = 3, D = dcov, method = "s", data = prim7)
prim7.out$R
pca <- princomp(~ ., data = as.data.frame(prim7[, -1]))
prim7.pca <- data.frame(X1 = prim7$X1, scores = pca$scores)
prim7.pca.out <- groc(X1 ~ ., ncomp = 3, D = dcov, method = "s",
                    data = prim7.pca)
pca$loadings
groc.v <- grocCrossval(prim7.out, segment.type = "consecutive")
groc.v$validation$PRESS
plsr.out <- plsr(X1 ~ ., ncomp = 3, data = prim7)
plsr.v <- crossval(plsr.out, segment.type = "consecutive")
plsr.v$validation$PRESS
PRESS <- 0
for(i in 1 : 10){
  data.in <- prim7[-(((i - 1) * 50 + 1) : (i * 50)), ]
  data.out <- prim7[((i - 1) * 50 + 1) : (i * 50), ]
  ppr.out <- ppr(X1 ~ ., nterms = 3, optlevel = 3, data = data.in)
  PRESS <- PRESS + sum((predict(ppr.out, newdata = data.out) - data.out$X1) ^ 2)
}
PRESS

#####
# Codes for Example 7 #
#####
n <- 50 ; B <- 30
mat.cor <- matrix(0, nrow = B, ncol = 3) ; mat.time <- matrix(0, nrow = B, ncol = 3)
for (i in 1:B) {
  X <- matrix(runif(n * 5, -1, 1), ncol = 5)
  A <- matrix(runif(n * 50, -1, 1), nrow = 5)
  y <- (X[,1] + X[,2])^2 + (X[,1] + 5 * X[,2])^2 + rnorm(n)
  X <- cbind(X, X)
  D <- data.frame(X = X, y = y)
  mat.time[i,1] <- system.time(out1 <- plsr(y ~ X, , ncomp = 2, data = D))[1]
  mat.time[i,2] <- system.time(out2 <- ppr(y ~ X, , nterms = 2, data = D))[1]
  mat.time[i,3] <- system.time(out3 <- groc(y ~ X, D = dcov, method = "s", ncomp = 2, data = D))[1]
  mat.cor[i,] <- cor(y, cbind(fitted(out1)[,2], fitted(out2), fitted(out3)[,2]))
}
colMeans(mat.cor)
colMeans(mat.time)

```

```
#####
# Codes for Example 8 #
#####
data("oliveoil")
n <- nrow(oliveoil)
plsr.out <- plsr(sensory ~ chemical, data = oliveoil, method = "simpls")
groc.out <- groc(sensory ~ chemical, data = oliveoil)
max(abs((fitted(plsr.out) - fitted(groc.out)) / fitted(plsr.out))) * 100
groc.v <- grocCrossval(groc.out, segments = n)
groc.v$validation$PRESS
colMeans(groc.v$validation$PRESS)
Y <- oliveoil$sensory
for (j in 1 : ncol(Y)) print(cor(Y[, j], fitted(groc.out)[, j, 2]))

#####
# Codes for Example 9 #
#####
require("ppls")
data("cookie")
X <- as.matrix(log(cookie[1 : 40, 51 : 651]))
Y <- as.matrix(cookie[1 : 40, 701 : 704])
X <- X[, 2 : 601] - X[, 1 : 600]
data <- data.frame(Y = I(Y), X = I(X))
n <- nrow(data)
q <- ncol(Y)
x1 <- "Wavelength index"
y1 <- "First differences of log(1/reflectance)"
matplot(1:ncol(X), t(X), lty = 1, xlab = x1, ylab = y1, type = "l")
out1 <- plsr(Y ~ X, ncomp = n - 2, data = data)
cv <- crossval(out1, segments = n)
cv.mean <- colMeans(cv$validation$PRESS)
plot(cv.mean, xlab = "h", ylab = "Average PRESS", pch = 20)
h <- 3
for (j in 1 : q) print(cor(Y[, j], fitted(out1)[, j, h]))
set.seed(1)
out2 <- groc(Y ~ X, ncomp = h, data = data, plsrob = TRUE)
for (j in 1 : q) print(corrob(Y[, j], fitted(out2)[, j, h]))
plot(out2)

#####
# Codes for Example 10 #
#####
set.seed(2)
n <- 30
t1 <- sort(runif(n, -1, 1))
y <- t1 + rnorm(n, mean = 0, sd = .05)
y[c(14, 15, 16)] <- y[c(14, 15, 16)] + .5
data <- data.frame(x1 = t1, x2 = 2 * t1, x3 = -1.5 * t1, y = y)
out <- groc(y ~ x1 + x2 + x3, ncomp = 1, data = data, plsrob = TRUE)
tau <- scaleTau2(residuals(out), mu.too = TRUE)
std.res <- scale(residuals(out), center = tau[1], scale = tau[2])
index <- which(abs(std.res)>3)
```

```

prm.res <- read.table("prmresid.txt")
plot(t1, y, pch = 20)
matlines(t1, cbind(t1,fitted(out), y - prm.res), lty = 1 : 3)
legend(.4, -.5 , legend = c("true model", "groc", "prm"), lty = 1 : 3)
text(t1[index], y[index], index, cex = .8, pos = 3)

#####
# Codes for Example 11 #
#####
data("pulpfiber")
X <- as.matrix(pulpfiber[, 1:4])
Y <- as.matrix(pulpfiber[, 5:8])
data <- data.frame(X = I(X), Y = I(Y))
set.seed(55481)
out.rob <- groc(Y ~ X, data = data, plsrob = TRUE)
plot(out.rob, cex = .6)
out.simpls <- groc(Y ~ X, data = data)
cv.rob <- grocCrossval(out.rob, segment.type = "consecutive")
PREMAD.rob <- cv.rob$validation$PREMAD[,4]
PREMAD.rob
cv.simpls <- grocCrossval(out.simpls, segment.type = "consecutive")
PREMAD.simpls <- cv.simpls$validation$PREMAD[,4]
PREMAD.simpls
(PREMAD.rob - PREMAD.simpls) / PREMAD.simpls * 100

## End(Not run)

```

groc.fit

Fitting a groc model

Description

Fits a groc model with the grid algorithm.

Usage

```

groc.fit(X, Y, ncomp = min(nrow(X) - 1, ncol(X)), D = NULL, gamma =
0.75, method = NULL, plsrob = FALSE, Nc = 10, Ng = 20,
scale = FALSE, Cpp = TRUE, stripped = FALSE, maxiter =
100, sp = NULL, ...)

```

Arguments

X	a matrix of predictors. NAs and Infs are not allowed.
Y	a vector or matrix of responses. NAs and Infs are not allowed.
ncomp	the number of components to be used in the modelling.
D	Dependence measure.

gamma	Used to set the breakdown value when method="lts".
method	the method to be used. Currently only 'lm', 'lo', 's', and 'lts'.
plsrob	Logical. If TRUE, the function sets D=covrov and method="lts" for a robust partial least squares fit.
Nc	Integer. Number of cycles in the grid algorithm
Ng	Integer. Number of points for the grid in the grid algorithm.
scale	Logical. If TRUE the responses are scaled.
Cpp	Logical. If TRUE, computations are performed in a faster way using a C code.
stripped	logical. If TRUE the calculations are stripped as much as possible for speed; this is meant for use with cross-validation or simulations when only the coefficients are needed. Defaults to FALSE.
maxiter	Integer. Maximal number of iterations in the grid algorithm. Used only when there are more than one response.
sp	A vector of smoothing parameters can be provided here. Smoothing parameters must be supplied in the order that the smooth terms appear in the model formula. Negative elements indicate that the parameter should be estimated, and hence a mixture of fixed and estimated parameters is possible. 'length(sp)' should be equal to 'ncomp' and corresponds to the number of underlying smoothing parameters.
...	other arguments. Currently ignored.

Value

Y	data used as response.
fitted.values	an array of fitted values. Its element [i,j,k] is the fitted value for observation i, response j, and when k components are used.
residuals	an array of regression residuals. It has the same dimensions as fitted.values.
T	a matrix of orthogonal components (scores). Each column corresponds to a component.
R	a matrix of directions (loadings). Each column is a direction used to obtain the corresponding component (scores).
Gobjects	contain the objects produced by the fit of the responses on the orthogonal components.
Hobjects	contain the objects produced by the "lts" fit of each deflated predictors on the orthogonal components. Hobjects are produced when plsrob=TRUE.
B	matrix of coefficients produced by the "lm" fit of each deflated predictors on the last component. B is produced when plsrob=FALSE.
Xmeans	a vector of means of the X variables.
Ymeans	a vector of means of the Y variables.
D	Dependence measure used.
V	a matrix whose columns contain the right singular vectors of the data. Computed in the preprocessing to principal component scores when the number of observations is less than the number of predictors.
dimnames	dimnames of 'fitted.values'

Author(s)

Martin Bilodeau (<bilodeau@dms.umontreal.ca>) and Pierre Lafaye de Micheaux (<lafaye@unsw.edu.au>)

References

Martin Bilodeau, Pierre Lafaye de Micheaux, Smail Mahdi (2015), The R Package groc for Generalized Regression on Orthogonal Components, *Journal of Statistical Software*, 65(1), 1-29, <http://www.jstatsoft.org/v65/i01/>

grocCrossval

Cross-validation of groc models

Description

A “stand alone” cross-validation function for groc objects.

Usage

```
grocCrossval(object, segments = 10, segment.type = c("random",
  "consecutive", "interleaved"), length.seg, trace = 15, ...)
```

Arguments

object	a groc object; the regression to cross-validate.
segments	the number of segments to use, or a list with segments (see below).
segment.type	the type of segments to use.
length.seg	Positive integer. The length of the segments to use.
trace	if TRUE, tracing is turned on. If numeric, it denotes a time limit (in seconds). If the estimated total time of the cross-validation exceeds this limit, tracing is turned on.
...	additional arguments, sent to the underlying fit function.

Details

This function performs cross-validation on a model fit by groc. It can handle models such as $\text{groc}(Y \sim X, \dots)$.

Note that to use grocCrossval, the data *must* be specified with a data argument when fitting object.

If segments is a list, the arguments segment.type and length.seg are ignored. The elements of the list should be integer vectors specifying the indices of the segments.

Otherwise, segments of type segment.type are generated. How many segments to generate is selected by specifying the number of segments in segments, or giving the segment length in length.seg. If both are specified, segments is ignored.

When tracing is turned on, the segment number is printed for each segment.

Value

The supplied object is returned, with an additional component validation, which is a list with components

method	equals "CV" for cross-validation.
pred	an array with the cross-validated predictions.
PRESS	a matrix of PRESS values for models with 1, ..., ncomp components. Each row corresponds to one response variable.
PREMAD	a matrix of PREMAD values for models with 1, ..., ncomp components. Each row corresponds to one response variable.
RMSEP	a matrix of $\sqrt{\text{PRESS}/\text{nobj}}$ values for models with 1, ..., ncomp components. Each row corresponds to one response variable.
segments	the list of segments used in the cross-validation.
ncomp	the number of components.

Author(s)

Martin Bilodeau (<bilodeau@dms.umontreal.ca>) and Pierre Lafaye de Micheaux (<lafaye@unsw.edu.au>)

References

Martin Bilodeau, Pierre Lafaye de Micheaux, Smail Mahdi (2015), The R Package groc for Generalized Regression on Orthogonal Components, *Journal of Statistical Software*, 65(1), 1-29, <http://www.jstatsoft.org/v65/i01/>

Examples

```
data(yarn,package="pls")
yarn.groc <- groc(density ~ NIR, 6, data = yarn)
yarn.cv <- grocCrossval(yarn.groc, segments = 10)

yarn.cv$validation$PRESS
yarn.cv$validation$PREMAD
```

model.frame.groc *Extract Information From a Fitted groc Model*

Description

Functions to extract information from groc objects: the model frame, the model matrix.

Usage

```
## S3 method for class 'groc'
model.matrix(object, ...)
## S3 method for class 'groc'
model.frame(formula, ...)
```


Details

If `plsrob=FALSE`, a plot of robust Mahalanobis distances for residuals versus robust Mahalanobis distances for components. Useful for identification of good points, vertical outliers, good and bad leverage points.

If `plsrob=TRUE`, the previous plot is done with another similar plot of classical Mahalanobis distances to compare the identification of the various type of points obtained by classical or robust partial least squares.

Author(s)

Martin Bilodeau (<bilodeau@dms.umontreal.ca>) and Pierre Lafaye de Micheaux (<lafaye@unsw.edu.au>)

References

Martin Bilodeau, Pierre Lafaye de Micheaux, Smail Mahdi (2015), The R Package `groc` for Generalized Regression on Orthogonal Components, *Journal of Statistical Software*, 65(1), 1-29, <http://www.jstatsoft.org/v65/i01/>

Examples

```
## This example takes some time:
## Not run:
data("pulpfiber", package="robustbase")
X <- as.matrix(pulpfiber[, 1:4])
Y <- as.matrix(pulpfiber[, 5:8])
data <- data.frame(X=I(X), Y=I(Y))
set.seed(55481)
out.rob <- groc(Y ~ X, data=data, plsrob=TRUE)
plot(out.rob, cex=.6)

## End(Not run)
```

predict.groc

Predict Method for groc

Description

Prediction for `groc` models. New responses or scores are predicted using a fitted model and a new matrix of observations.

Usage

```
## S3 method for class 'groc'
predict(object, newdata, ncomp = object$ncomp, na.action = na.pass, ...)
```

Arguments

object	a groc object. The fitted model
newdata	a data frame. The new data. If missing, the training data is used.
ncomp	vector of positive integers. The components to use in the prediction.
na.action	function determining what should be done with missing values in newdata. By default, nothing is done.
...	further arguments. Currently not used

Value

A three dimensional array of predicted response values is returned. The dimensions correspond to the observations, the response variables and the model sizes, respectively.

Author(s)

Martin Bilodeau (<bilodeau@dms.umontreal.ca>) and Pierre Lafaye de Micheaux (<lafaye@unsw.edu.au>)

References

Martin Bilodeau, Pierre Lafaye de Micheaux, Smail Mahdi (2015), The R Package groc for Generalized Regression on Orthogonal Components, *Journal of Statistical Software*, 65(1), 1-29, <http://www.jstatsoft.org/v65/i01/>

See Also

[plot.groc](#)

Examples

```
data("wood", package="robustbase")
out <- groc(y ~ x1+x2+x3+x4+x5, ncomp=1, data=wood, D=corrob, method="lts")
predict(out)

newdata<- data.frame(x1= 0.5, x2=0.1, x3=0.4, x4=0.5, x5=0.8)
predict(out, newdata)
```

prim7

prim7 Dataset

Description

The data prim7 is a particle physics experiment analyzed by projection pursuit regression in Friedman and Stuetzle (1981). It has 7 variables on 500 observations. The data set is described in Friedman and Tukey (1974).

Format

This data frame contains the following columns:

- X1** First variable.
- X2** Second variable.
- X3** Third variable.
- X4** Fourth variable.
- X5** Fifth variable.
- X6** Sixth variable.
- X7** Seventh variable.

References

Friedman and Tukey (1974), A Projection Pursuit Algorithm for Exploratory Data Analysis, *IEEE Transactions on Computers* (Volume:C-23, Issue: 9)

Friedman, Jerome H.; Stuetzle, Werner (1981), Projection pursuit regression. *J. Amer. Statist. Assoc.* 76, no. 376, 817–823.

Examples

```
data(prim7)
```

```
summary.groc
```

Summary and Print Methods for groc objects

Description

Summary and print methods for groc objects.

Usage

```
## S3 method for class 'groc'
summary(object, what = "validation",
         digits = 4, print.gap = 2, ...)
## S3 method for class 'groc'
print(x, ...)
```

Arguments

x, object	a groc object
what	character, only "validation" for the moment
digits	integer. Minimum number of significant digits in the output. Default is 4.
print.gap	Integer. Gap between coloumns of the printed tables.
...	Other arguments sent to underlying methods.

Details

If what is "validation", the cross-validated PRESS, RPEMAD and RMSEPs (if available) are given.

Value

`print.groc` return the object invisibly.

Author(s)

P. Lafaye de Micheaux

References

Martin Bilodeau, Pierre Lafaye de Micheaux, Smail Mahdi (2015), The R Package `groc` for Generalized Regression on Orthogonal Components, *Journal of Statistical Software*, 65(1), 1-29, <http://www.jstatsoft.org/v65/i01/>

See Also

[groc](#), [grocCrossval](#)

Examples

```
data("yarn", package="pls")
yarn.groc <- groc(density ~ NIR, 6, data = yarn)
yarn.cv <- grocCrossval(yarn.groc, segments = 10)
print(yarn.groc)
summary(yarn.cv)
```

Index

- *Topic **datasets**
 - prim7, 20
 - *Topic **distribution**
 - groc, 8
 - *Topic **htest**
 - groc, 8
 - *Topic **multivariate**
 - covRob, 3
 - dcov, 7
 - groc.fit, 14
 - grocCrossval, 16
 - model.frame.groc, 17
 - plot.groc, 18
 - predict.groc, 19
 - summary.groc, 21
 - *Topic **regresion**
 - plot.groc, 18
 - *Topic **regression**
 - groc.fit, 14
 - grocCrossval, 16
 - model.frame.groc, 17
 - predict.groc, 19
 - summary.groc, 21
 - *Topic **robust**
 - corrob, 2
 - covRob, 3
 - covrob, 5
 - *Topic **utilities**
 - covRob.control, 6
-
- coef, 18
 - corrob, 2, 6, 8
 - covMcd, 4, 7
 - covMest, 4
 - CovOgk, 4, 7
 - covRob, 2, 3, 7
 - covrob, 3, 5, 8
 - covRob.control, 6
 - CovSde, 4, 7
 - dcov, 3, 6, 7
 - fitted, 18
 - groc, 8, 22
 - groc.fit, 14
 - grocCrossval, 16, 22
 - model.frame, 18
 - model.frame.groc, 17
 - model.matrix, 18
 - model.matrix.groc (model.frame.groc), 17
 - plot.groc, 18, 20
 - predict.groc, 19
 - prim7, 20
 - print.groc (summary.groc), 21
 - residuals, 18
 - scaleTau2, 5
 - summary.groc, 21