

Package ‘errors’

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Description Support for measurement errors in R vectors, matrices and arrays:
automatic uncertainty propagation and reporting.
Documentation about 'errors' is provided in the paper by Ucar, Pebesma &
Azcorra (2018, <doi:10.32614/RJ-2018-075>), included in this package as a
vignette; see 'citation("`errors"') for details.

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BugReports <https://github.com/r-quantities/errors/issues>

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errors-package	errors: <i>Uncertainty Propagation for R Vectors</i>
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Description

Support for measurement errors in R vectors, matrices and arrays: automatic uncertainty propagation and reporting.

Details

Every measurement has an unknown error associated. Uncertainty is the acknowledgement of that error: we are aware that our representation of reality may differ from reality itself. This package provides support for measurement errors in R vectors, matrices and arrays. Uncertainty metadata is associated to quantity values (see [errors](#)), and this uncertainty is automatically propagated when you operate with errors objects (see [groupGeneric.errors](#)), or with errors and numeric objects (then numeric values are automatically coerced to errors objects with no uncertainty).

Correlations between measurements are also supported. In particular, any operation (e.g., $z \leftarrow x + y$) results in a correlation between output and input variables (i.e., z is correlated to x and y , even if there was no correlation between x and y). And in general, the user can establish correlations between any pair of variables (see [correl](#)).

This package treats uncertainty as coming from Gaussian and linear sources (note that, even for non-Gaussian non-linear sources, this is a reasonable assumption for averages of many measurements),

and propagates them using the first-order Taylor series method for propagation of uncertainty. Although the above assumptions are valid in a wide range of applications in science and engineering, the practitioner should evaluate whether they apply for each particular case.

Author(s)

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References

Iñaki Ucar, Edzer Pebesma and Arturo Azcorra (2018). Measurement Errors in R. *The R Journal*, 10(2), 549-557. doi: [10.32614/RJ2018075](https://doi.org/10.32614/RJ2018075)

See Also

[datasets](#) for a description of the datasets used in the examples below.

Examples

```
## Simultaneous resistance and reactance measurements

# Obtain mean values and uncertainty from measured values
V <- mean(set_errors(GUM.H.2$V))
I <- mean(set_errors(GUM.H.2$I))
phi <- mean(set_errors(GUM.H.2$phi))

# Set correlations between variables
correl(V, I) <- with(GUM.H.2, cor(V, I))
correl(V, phi) <- with(GUM.H.2, cor(V, phi))
correl(I, phi) <- with(GUM.H.2, cor(I, phi))

# Computation of resistance, reactance and impedance values
(R <- (V / I) * cos(phi))
(X <- (V / I) * sin(phi))
(Z <- (V / I))

# Correlations between derived quantities
correl(R, X)
correl(R, Z)
correl(X, Z)

## Calibration of a thermometer

# Least-squares fit for a reference temperature of 20 degC
fit <- lm(bk ~ I(tk - 20), data = GUM.H.3)

# Extract coefficients and set correlation using the covariance matrix
y1 <- set_errors(coef(fit)[1], sqrt(vcov(fit)[1, 1]))
y2 <- set_errors(coef(fit)[2], sqrt(vcov(fit)[2, 2]))
covar(y1, y2) <- vcov(fit)[1, 2]

# Predicted correction for 30 degC
```

```
(b.30 <- y1 + y2 * set_errors(30 - 20))
```

as.data.frame.errors *Coerce to a Data Frame*

Description

S3 method for errors objects (see [as.data.frame](#)).

Usage

```
## S3 method for class 'errors'
as.data.frame(x, row.names = NULL, optional = FALSE, ...)
```

Arguments

x	any R object.
row.names	NULL or a character vector giving the row names for the data frame. Missing values are not allowed.
optional	logical. If TRUE, setting row names and converting column names (to syntactic names: see make.names) is optional. Note that all of R's base package <code>as.data.frame()</code> methods use <code>optional</code> only for column names treatment, basically with the meaning of <code>data.frame(*, check.names = !optional)</code> . See also the <code>make.names</code> argument of the <code>matrix</code> method.
...	additional arguments to be passed to or from methods.

Examples

```
x <- set_errors(1:3, 0.1)
y <- set_errors(4:6, 0.2)
(z <- cbind(x, y))
as.data.frame(z)
```

as.list.errors *Coerce to a List*

Description

S3 method for errors objects (see [as.list](#)).

Usage

```
## S3 method for class 'errors'
as.list(x, ...)
```

Arguments

x object to be coerced or tested.
... objects, possibly named.

Examples

```
x <- set_errors(1:3, 0.1)
as.list(x)
```

as.matrix.errors *Coerce to a Matrix*

Description

S3 method for errors objects (see [as.matrix](#)).

Usage

```
## S3 method for class 'errors'
as.matrix(x, ...)
```

Arguments

x an R object.
... additional arguments to be passed to or from methods.

Examples

```
as.matrix(set_errors(1:3, 0.1))
```

c.errors *Combine Values into a Vector or List*

Description

S3 method for errors objects (see [c](#)).

Usage

```
## S3 method for class 'errors'
c(..., recursive = FALSE)
```

Arguments

... objects to be concatenated.

recursive logical. If recursive = TRUE, the function recursively descends through lists (and pairlists) combining all their elements into a vector.

Examples

```
c(set_errors(1, 0.2), set_errors(7:9, 0.1), 3)
```

cbind.errors

Combine R Objects by Rows or Columns

Description

S3 methods for errors objects (see [cbind](#)).

Usage

```
## S3 method for class 'errors'
cbind(..., deparse.level = 1)

## S3 method for class 'errors'
rbind(..., deparse.level = 1)
```

Arguments

... (generalized) vectors or matrices. These can be given as named arguments. Other R objects may be coerced as appropriate, or S4 methods may be used: see sections ‘Details’ and ‘Value’. (For the “data.frame” method of cbind these can be further arguments to [data.frame](#) such as stringsAsFactors.)

deparse.level integer controlling the construction of labels in the case of non-matrix-like arguments (for the default method):
deparse.level = 0 constructs no labels; the default,
deparse.level = 1 or 2 constructs labels from the argument names, see the ‘Value’ section below.

See Also

[c.errors](#)

Examples

```
x <- set_errors(1, 0.1)
y <- set_errors(1:3, 0.2)
(m <- cbind(x, y)) # the '1' (= shorter vector) is recycled
(m <- cbind(m, 8:10)[, c(1, 3, 2)]) # insert a column
cbind(y, diag(3)) # vector is subset -> warning
cbind(0, rbind(x, y))
```

correl

Handle Correlations Between errors Objects

Description

Set or retrieve correlations or covariances between errors objects. See the details section below.

Usage

```
correl(x, y)

correl(x, y) <- value

set_correl(x, y, value)

covar(x, y)

covar(x, y) <- value

set_covar(x, y, value)
```

Arguments

x	an object of class errors.
y	an object of class errors.
value	a numeric vector of length 1 or the same length as x.

Details

The uncertainties associated to errors objects are supposed to be independent by default. If there is some known correlation, it can be defined using these methods, and it will be used for the propagation of the uncertainty by the mathematical and arithmetic operations.

The `correl` method sets or retrieves correlations, i.e., a value (or vector of values) between -1 and 1 (see base `cor` on how to compute correlations). A covariance is just a correlation value multiplied by the standard deviations (i.e., the standard uncertainty) of both variables. It can be defined using the `covar` method (see base `cov` on how to compute covariances). These methods are equivalent; in fact, `correl` calls `covar` internally.

Every errors object has a unique ID, and pairwise correlations are stored in an internal hash table. All the functions or methods that modify somehow the dimensions of errors objects (i.e., subsets, binds, concatenations, summaries...) generate new objects with new IDs, and correlations are not, and cannot be, propagated. Only mathematical and arithmetic operations propagate correlations, where appropriate, following the Taylor series method.

Value

correl and covar return a vector of correlations and covariances respectively (or NULL). set_correl and set_covar, which are pipe-friendly versions of the setters, return the x object.

Examples

```
x <- set_errors(1:5, 0.1)
y <- set_errors(1:5, 0.1)

# Self-correlation is of course 1, and cannot be changed
correl(x, x)
## Not run:
correl(x, x) <- 0.5
## End(Not run)

# Cross-correlation can be set, but must be a value between -1 and 1
correl(x, y)
## Not run:
correl(x, y) <- 1.5
## End(Not run)
correl(x, y) <- runif(length(x))
correl(x, y)
covar(x, y)
```

datasets

Datasets from the Guide to the Expression of Uncertainty in Measurement (GUM)

Description

Datasets found in Annex H of the GUM (see reference below).

Usage

GUM.H.2

GUM.H.3

Format

GUM.H.2, from Section 2 of Annex H (Table H.2), provides simultaneous resistance and reactance measurements. It is a data frame with 5 rows and 3 variables:

V Voltage amplitude, in Volts.

I Current amplitude, in Amperes.

phi Phase-shift angle of the voltage relative to the current, in radians.

GUM.H.3, from Section 3 of Annex H (Table H.6), provides thermometer readings and observed corrections to obtain a linear calibration curve for some reference temperature. It is a data frame with 11 rows and 2 variables:

tk Thermometer reading, in Celsius degrees.

bk Observed correction, in Celsius degrees.

An object of class `data.frame` with 11 rows and 2 columns.

Source

BIPM, IEC, IFCC, ILAC, IUPAC, IUPAP, ISO, and OIML (2008). Evaluation of Measurement Data – Guide to the Expression of Uncertainty in Measurement, 1st edn. JCGM 100:2008. *Joint Committee for Guides in Metrology*. <https://www.bipm.org/en/publications/guides/gum.html>

See Also

See [errors-package](#) for examples.

diff.errors

Lagged Differences

Description

S3 method for errors objects (see [diff](#)).

Usage

```
## S3 method for class 'errors'
diff(x, lag = 1L, differences = 1L, ...)
```

Arguments

<code>x</code>	a numeric vector or matrix containing the values to be differenced.
<code>lag</code>	an integer indicating which lag to use.
<code>differences</code>	an integer indicating the order of the difference.
<code>...</code>	further arguments to be passed to or from methods.

Examples

```
diff(set_errors(1:10, 0.1), 2)
diff(set_errors(1:10, 0.1), 2, 2)
x <- cumsum(cumsum(set_errors(1:10, 0.1)))
diff(x, lag = 2)
diff(x, differences = 2)
```

drop_errors

Drop Uncertainty

Description

Drop Uncertainty

Usage

```
drop_errors(x)

## S3 method for class 'data.frame'
drop_errors(x)
```

Arguments

x an errors object.

Value

the numeric without any errors attributes, while preserving other attributes like dimensions or other classes.

Note

Equivalent to `errors(x) <- NULL` or `set_errors(x, NULL)`.

errors

Handle Uncertainty on a Numeric Vector

Description

Set or retrieve uncertainty to/from numeric vectors.

Usage

```
errors(x)

errors_max(x)

errors_min(x)

errors(x) <- value

set_errors(x, value = 0)

as.errors(x, value = 0)
```

Arguments

`x` a numeric object, or object of class `errors`.
`value` a numeric vector of length 1 or the same length as `x`.

Details

``errors<-`` sets the uncertainty values (and converts `x` into an object of class `errors`). `set_errors` is a pipe-friendly version of ``errors<-`` and returns an object of class `errors`. `as.errors` is an alias for `set_errors`.

See [correl](#) on how to handle correlations between pairs of variables.

Value

`errors` returns a vector of uncertainty. `errors_max` (`errors_min`) returns the values plus (minus) the uncertainty.

See Also

[groupGeneric.errors](#), [mean.errors](#), [Extract.errors](#), [c](#), [rep](#), [cbind.errors](#), [format.errors](#), [print.errors](#), [plot.errors](#), [as.data.frame.errors](#), [as.matrix.errors](#), [t](#).

Examples

```
x = 1:3
class(x)
x
errors(x) <- 0.1
class(x)
x

(x <- set_errors(x, seq(0.1, 0.3, 0.1)))
errors_max(x)
errors_min(x)
```

Extract.errors	<i>Extract or Replace Parts of an Object</i>
----------------	--

Description

S3 operators to extract or replace parts of errors objects.

Usage

```
## S3 method for class 'errors'
x[...]

## S3 method for class 'errors'
x[[...]]

## S3 replacement method for class 'errors'
x[...] <- value

## S3 replacement method for class 'errors'
x[[...]] <- value
```

Arguments

x	object from which to extract element(s) or in which to replace element(s).
...	additional arguments to be passed to base methods (see Extract).
value	typically an array-like R object of a similar class as x.

Examples

```
x <- set_errors(1:3, 0.1)
y <- set_errors(4:6, 0.2)
(z <- rbind(x, y))
z[2, 2]
z[2, 2] <- -1
errors(z[[1, 2]]) <- 0.8
z[, 2]
```

format.errors	<i>Encode errors</i>
---------------	----------------------

Description

Format an errors object for pretty printing.

Usage

```
## S3 method for class 'errors'
format(x, digits = NULL, scientific = FALSE,
       notation = getOption("errors.notation", "parenthesis"), ...)
```

Arguments

x	an errors object.
digits	how many significant digits are to be used for uncertainties. The default, NULL, uses <code>getOption("errors.digits", 1)</code> .
scientific	logical specifying whether the elements should be encoded in scientific format.
notation	error notation; "parenthesis" and "plus-minus" are supported through the "errors.notation" option.
...	ignored.

Examples

```
x <- set_errors(1:3*100, 1:3*100 * 0.05)
format(x)
format(x, digits=2)
format(x, scientific=TRUE)
format(x, notation="plus-minus")
```

groupGeneric.errors *S3 Group Generic Functions*

Description

Math, Ops and Summary group generic methods for errors objects with support for automatic uncertainty propagation (see [groupGeneric](#) for a comprehensive list of available methods).

Usage

```
## S3 method for class 'errors'
Math(x, ...)

## S3 method for class 'errors'
Ops(e1, e2)

## S3 method for class 'errors'
Summary(..., na.rm = FALSE)
```

Arguments

x	objects.
...	further arguments passed to methods.
e1	objects.
e2	objects.
na.rm	logical: should missing values be removed?

Details

Math: The `sign` method returns a numeric value without uncertainty. `floor`, `ceiling`, `trunc`, `round` and `signif` add the rounding error to the original uncertainty. `lgamma`, `gamma`, `digamma` and `trigamma` are not implemented. The rest of the methods propagate the uncertainty as expected from the first-order Taylor series method.

Ops: Boolean operators drop the uncertainty (showing a warning once) and operate on the numeric values. The rest of the operators propagate the uncertainty as expected from the first-order Taylor series method. Any numeric operand is automatically coerced to errors (showing a warning once) with no uncertainty.

Summary: The methods `all` and `any` are not supported for errors objects and fail with an informative message. `min`, `max` (and `range`) return the minimum or (and) maximum value minus/plus its uncertainty. `sum` and `prod` propagate the uncertainty as expected from the first-order Taylor series method.

Examples

```
x <- set_errors(1:3, 0.1)
exp(x)
log(x)
cumsum(x)
cumprod(x)

y <- set_errors(4:6, 0.2)
x / sqrt(y) + y * sin(x)

# numeric values are automatically coerced to errors
x^2

# boolean operators drop uncertainty
y > x

c(min(x), max(x))
range(x)
sum(y)
prod(y)
```

mean.errors	<i>Arithmetic Mean and Median Value</i>
-------------	---

Description

S3 methods for errors objects.

Usage

```
## S3 method for class 'errors'
mean(x, ...)
```

```
## S3 method for class 'errors'
weighted.mean(x, ...)
```

```
## S3 method for class 'errors'
median(x, ...)
```

Arguments

x an errors object.
 ... further arguments passed to of from other methods.

Details

The mean and weighted.mean methods set the uncertainty as the maximum of the standard deviation of the mean and the (weighted) mean of the uncertainty.

The median method sets the uncertainty as $1.253 * \text{errors}(\text{mean}(x))$, which is derived from the asymptotic variance formula of the median. Note that this value is valid only if the sample is big enough.

Value

An errors object.

plot.errors	<i>Scatterplot with Error Bars</i>
-------------	------------------------------------

Description

S3 method for errors objects which automatically prints the error bars.

Usage

```
## S3 method for class 'errors'
plot(x, y, ...)
```

Arguments

x	the coordinates of points in the plot. Alternatively, a single plotting structure, function or <i>any R object with a plot method</i> can be provided.
y	the y coordinates of points in the plot, <i>optional</i> if x is an appropriate structure.
...	additional arguments (see plot).

Examples

```
cars <- as.matrix(cars)
cars <- as.data.frame(set_errors(cars, cars * 0.05))
plot(cars)
```

print.errors

Print Values

Description

S3 method for errors objects.

Usage

```
## S3 method for class 'errors'
print(x, ...)
```

Arguments

x	an errors object.
...	further arguments passed to or from other methods.

Examples

```
x <- set_errors(1:10, 1:10 * 0.05)
print(x)
print(x[1:3])
print(x[1])
print(x[1], digits=2)
print(x[1], notation="plus-minus")
```

rep.errors	<i>Replicate Elements of Vectors and Lists</i>
------------	--

Description

S3 method for errors objects (see [rep](#)).

Usage

```
## S3 method for class 'errors'
rep(x, ...)
```

Arguments

x	a vector (of any mode including a list) or a factor or (for rep only) a POSIXct or POSIXlt or Date object; or an S4 object containing such an object.
...	further arguments to be passed to or from other methods. For the internal default method these can include: <ul style="list-style-type: none"> times an integer-valued vector giving the (non-negative) number of times to repeat each element if of length length(x), or to repeat the whole vector if of length 1. Negative or NA values are an error. A double vector is accepted, other inputs being coerced to an integer or double vector. length.out non-negative integer. The desired length of the output vector. Other inputs will be coerced to a double vector and the first element taken. Ignored if NA or invalid. each non-negative integer. Each element of x is repeated each times. Other inputs will be coerced to an integer or double vector and the first element taken. Treated as 1 if NA or invalid.

Examples

```
rep(set_errors(1, 0.1), 4)
```

t.errors	<i>Matrix Transpose</i>
----------	-------------------------

Description

S3 method for errors objects (see [t](#)).

Usage

```
## S3 method for class 'errors'
t(x)
```

Arguments

x a matrix or data frame, typically.

Examples

```
a <- matrix(1:30, 5, 6)
errors(a) <- 1:30
t(a)
```

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