

Package ‘diffeqr’

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Type Package

Title Solving Differential Equations (ODEs, SDEs, DDEs, DAEs)

Version 0.1.3

Description An interface to 'DifferentialEquations.jl' <<http://docs.juliadiffeq.org/latest/>> from the R programming language. It has unique high performance methods for solving ordinary differential equations (ODE), stochastic differential equations (SDE), delay differential equations (DDE), differential-algebraic equations (DAE), and more. Much of the functionality, including features like adaptive time stepping in SDEs, are unique and allow for multiple orders of magnitude speedup over more common methods. 'diffeqr' attaches an R interface onto the package, allowing seamless use of this tooling by R users.

Depends R (>= 3.4.0)

Encoding UTF-8

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URL <https://github.com/JuliaDiffEq/diffeqr>

LazyData true

SystemRequirements Julia (>= 0.6.0), DifferentialEquations.jl

Imports JuliaCall, stringr

RoxygenNote 6.1.1

Suggests testthat, knitr, rmarkdown

VignetteBuilder knitr

NeedsCompilation no

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dae.solve	<i>Solve Differential-Algebraic Equations (DAE)</i>
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Description

Solves a DAE with $f(du,u,p,t)=0$ for $u(0)=u0$ over the `tspan`

Usage

```
dae.solve(f, du0, u0, tspan, p = NULL, alg = "nothing",
  reltol = 0.001, abstol = 1e-06, maxiters = 1e+06, saveat = NULL,
  differential_vars = NULL)
```

Arguments

<code>f</code>	the implicit ODE function.
<code>du0</code>	the initial derivative. Can be a number or (arbitrary dimension) array.
<code>u0</code>	the initial condition. Can be a number or (arbitrary dimension) array.
<code>tspan</code>	the timespan to solve over. Should be a list of two values: (initial time, end time).
<code>p</code>	the parameters. Defaults to no parameters. Can be a number or an array.
<code>alg</code>	the algorithm used to solve the differential equation. Defaults to an adaptive choice. Algorithm choices are done through a string which matches the <code>DifferentialEquations.jl</code> form.
<code>reltol</code>	the relative tolerance of the ODE solver. Defaults to $1e-3$.
<code>abstol</code>	the absolute tolerance of the ODE solver. Defaults to $1e-6$.
<code>maxiters</code>	the maximum number of iterations the adaptive solver is allowed to try before exiting. Default value is 1000000.
<code>saveat</code>	the time points to save values at. Should be an array of times. Defaults to automatic.
<code>differential_vars</code>	boolean array declaring which variables are differential. All falses correspond to purely algebraic variables.

Value

sol. Has the sol\$t for the time points and sol\$u for the values.

Examples

```
## diffeq_setup() is time-consuming and requires Julia+DifferentialEquations.jl

diffeqr::diffeq_setup()

f <- function (du,u,p,t) {
  resid1 = - 0.04*u[1] + 1e4*u[2]*u[3] - du[1]
  resid2 = + 0.04*u[1] - 3e7*u[2]^2 - 1e4*u[2]*u[3] - du[2]
  resid3 = u[1] + u[2] + u[3] - 1.0
  c(resid1,resid2,resid3)
}
u0 = c(1.0, 0, 0)
du0 = c(-0.04, 0.04, 0.0)
tspan = list(0.0,100000.0)
differential_vars = c(TRUE,TRUE,FALSE)
sol = diffeqr::dae.solve(f,du0,u0,tspan,differential_vars=differential_vars)
udf = as.data.frame(sol$u)
#plotly::plot_ly(udf, x = sol$t, y = ~V1, type = 'scatter', mode = 'lines') %>%
#plotly::add_trace(y = ~V2) %>%
#plotly::add_trace(y = ~V3)

f = JuliaCall::julia_eval("function f(out,du,u,p,t)
  out[1] = - 0.04u[1] + 1e4*u[2]*u[3] - du[1]
  out[2] = + 0.04u[1] - 3e7*u[2]^2 - 1e4*u[2]*u[3] - du[2]
  out[3] = u[1] + u[2] + u[3] - 1.0
end")
sol = diffeqr::dae.solve('f',du0,u0,tspan,differential_vars=differential_vars)
```

dde.solve

Solve Delay Differential Equations (DDE)

Description

Solves a DDE with $f(u,p,t)=0$ for $u(0)=u_0$ over the tspan

Usage

```
dde.solve(f, u0, h, tspan, p = NULL, alg = "nothing", reltol = 0.001,
  abstol = 1e-06, maxiters = 1e+06, saveat = NULL,
  constant_lags = NULL)
```

Arguments

<code>f</code>	the implicit ODE function.
<code>u0</code>	the initial condition. Can be a number or (arbitrary dimension) array.
<code>h</code>	is the history function (p,t) which gives values of the solution before the initial time point.
<code>tspan</code>	the timespan to solve over. Should be a list of two values: (initial time, end time).
<code>p</code>	the parameters. Defaults to no parameters. Can be a number or an array.
<code>alg</code>	the algorithm used to solve the differential equation. Defaults to an adaptive choice. Algorithm choices are done through a string which matches the DifferentialEquations.jl form.
<code>reltol</code>	the relative tolerance of the ODE solver. Defaults to 1e-3.
<code>abstol</code>	the absolute tolerance of the ODE solver. Defaults to 1e-6.
<code>maxiters</code>	the maximum number of iterations the adaptive solver is allowed to try before exiting. Default value is 1000000.
<code>saveat</code>	the time points to save values at. Should be an array of times. Defaults to automatic.
<code>constant_lags</code>	a vector of floats for the constant-time lags. Defaults to NULL.

Value

`sol`. Has the `sol$t` for the time points and `sol$u` for the values.

Examples

```

## diffeq_setup() is time-consuming and requires Julia+DifferentialEquations.jl

diffeqr::diffeq_setup()

f = JuliaCall::julia_eval("function f(du, u, h, p, t)
  du[1] = 1.1/(1 + sqrt(10)*(h(p, t-20)[1])^(5/4)) - 10*u[1]/(1 + 40*u[2])
  du[2] = 100*u[1]/(1 + 40*u[2]) - 2.43*u[2]
end")
u0 = c(1.05767027/3, 1.030713491/3)
h <- function (p,t){
  c(1.05767027/3, 1.030713491/3)
}
tspan = list(0.0, 100.0)
constant_lags = c(20.0)
sol = diffeqr::dde.solve('f',u0,h,tspan,constant_lags=constant_lags)
udf = as.data.frame(sol$u)
#plotly::plot_ly(udf, x = sol$t, y = ~V1, type = 'scatter', mode = 'lines') %>%
#plotly::add_trace(y = ~V2)

```

diffeq_setup	<i>Setup diffeqr</i>
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Description

This function initializes Julia and the DifferentialEquations.jl package. The first time will be long since it includes precompilation.

Usage

```
diffeq_setup(...)
```

Arguments

... Parameters are passed down to JuliaCall::julia_setup

Examples

```
## diffeq_setup() is time-consuming and requires Julia+DifferentialEquations.jl
diffeqr::diffeq_setup()
```

ode.solve	<i>Solve Ordinary Differential Equations (ODE)</i>
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Description

Solves an ODE with $u'=f(u,p,t)$, for $u(0)=u_0$ over the `tspan`

Usage

```
ode.solve(f, u0, tspan, p = NULL, alg = "nothing", reltol = 0.001,
          abstol = 1e-06, maxiters = 1e+06, saveat = NULL)
```

Arguments

<code>f</code>	the derivative function.
<code>u0</code>	the initial condition. Can be a number or (arbitrary dimension) array.
<code>tspan</code>	the timespan to solve over. Should be a list of two values: (initial time, end time).
<code>p</code>	the parameters. Defaults to no parameters. Can be a number or an array.

<code>alg</code>	the algorithm used to solve the differential equation. Defaults to an adaptive choice. Algorithm choices are done through a string which matches the <code>DifferentialEquations.jl</code> form.
<code>reltol</code>	the relative tolerance of the ODE solver. Defaults to $1e-3$.
<code>abstol</code>	the absolute tolerance of the ODE solver. Defaults to $1e-6$.
<code>maxiters</code>	the maximum number of iterations the adaptive solver is allowed to try before exiting. Default value is 1000000.
<code>saveat</code>	the time points to save values at. Should be an array of times. Defaults to automatic.

Value

`sol`. Has the `sol$t` for the time points and `sol$u` for the values.

Examples

```

## diffeq_setup() is time-consuming and requires Julia+DifferentialEquations.jl

diffeqr::diffeq_setup()

# Scalar ODEs

f <- function(u,p,t) {
  return(1.01*u)
}
u0 = 1/2
tspan <- list(0.0,1.0)
sol = diffeqr::ode.solve(f,u0,tspan)
plot(sol$t,sol$u,"1")

saveat=1:10/10
sol2 = diffeqr::ode.solve(f,u0,tspan,saveat=saveat)
sol3 = diffeqr::ode.solve(f,u0,tspan,alg="Vern9()")
sol4 = diffeqr::ode.solve(f,u0,tspan,alg="Rosenbrock23()")

# Systems of ODEs

f <- function(u,p,t) {
  du1 = p[1]*(u[2]-u[1])
  du2 = u[1]*(p[2]-u[3]) - u[2]
  du3 = u[1]*u[2] - p[3]*u[3]
  return(c(du1,du2,du3))
}

u0 = c(1.0,0.0,0.0)
tspan <- list(0.0,100.0)
p = c(10.0,28.0,8/3)
sol = diffeqr::ode.solve(f,u0,tspan,p=p)
udf = as.data.frame(sol$u)
matplot(sol$t,udf,"1",col=1:3)

```

```
#plotly::plot_ly(udf, x = ~V1, y = ~V2, z = ~V3, type = 'scatter3d', mode = 'lines')

f <- JuliaCall::julia_eval("
function f(du,u,p,t)
  du[1] = 10.0*(u[2]-u[1])
  du[2] = u[1]*(28.0-u[3]) - u[2]
  du[3] = u[1]*u[2] - (8/3)*u[3]
end")
sol = diffeqr::ode.solve('f',u0,tspan)
```

sde.solve

*Solve Stochastic Differential Equations (SDE)***Description**

Solves an SDE with $du=f(u,p,t)dt + g(u,p,t)dW_t$, for $u(0)=u0$ over the `tspan`

Usage

```
sde.solve(f, g, u0, tspan, p = NULL, alg = "nothing",
  noise.dims = NULL, maxiters = 1e+06, reltol = 0.01,
  abstol = 0.01, saveat = NULL, seed = 0)
```

Arguments

<code>f</code>	the drift function.
<code>g</code>	the diffusion function.
<code>u0</code>	the initial condition. Can be a number or (arbitrary dimension) array.
<code>tspan</code>	the timespan to solve over. Should be a list of two values: (initial time, end time).
<code>p</code>	the parameters. Defaults to no parameters. Can be a number or an array.
<code>alg</code>	the algorithm used to solve the differential equation. Defaults to an adaptive choice. Algorithm choices are done through a string which matches the <code>DifferentialEquations.jl</code> form.
<code>noise.dims</code>	list of the dimensions for the noise rate term. Defaults to <code>NULL</code> which gives diagonal noise.
<code>maxiters</code>	the maximum number of iterations the adaptive solver is allowed to try before exiting. Default value is 1000000.
<code>reltol</code>	the relative tolerance of the ODE solver. Defaults to 1e-3.
<code>abstol</code>	the absolute tolerance of the ODE solver. Defaults to 1e-6.
<code>saveat</code>	the time points to save values at. Should be an array of times. Defaults to automatic.
<code>seed</code>	the seed for the random numbers. Defaults to zero for a random seed.

Value

sol. Has the sol\$t for the time points and sol\$u for the values.

Examples

```

## diffeq_setup() is time-consuming and requires Julia+DifferentialEquations.jl

diffeqr::diffeq_setup()

# Scalar SDEs

f <- function(u,p,t) {
  return(1.01*u)
}
g <- function(u,p,t) {
  return(0.87*u)
}
u0 = 1/2
tspan <- list(0.0,1.0)
sol = diffeqr::sde.solve(f,g,u0,tspan)
#plotly::plot_ly(udf, x = sol$t, y = sol$u, type = 'scatter', mode = 'lines')

# Diagonal Noise SDEs

f <- JuliaCall::julia_eval("
function f(du,u,p,t)
  du[1] = 10.0*(u[2]-u[1])
  du[2] = u[1]*(28.0-u[3]) - u[2]
  du[3] = u[1]*u[2] - (8/3)*u[3]
end")

g <- JuliaCall::julia_eval("
function g(du,u,p,t)
  du[1] = 0.3*u[1]
  du[2] = 0.3*u[2]
  du[3] = 0.3*u[3]
end")
tspan <- list(0.0,100.0)
sol = diffeqr::sde.solve('f','g',u0,tspan,p=p,saveat=0.05)
udf = as.data.frame(sol$u)
#plotly::plot_ly(udf, x = ~V1, y = ~V2, z = ~V3, type = 'scatter3d', mode = 'lines')

# Non-Diagonal Noise SDEs

f <- JuliaCall::julia_eval("
function f(du,u,p,t)
  du[1] = 10.0*(u[2]-u[1])
  du[2] = u[1]*(28.0-u[3]) - u[2]
  du[3] = u[1]*u[2] - (8/3)*u[3]
end")
g <- JuliaCall::julia_eval("

```



```
function g(du,u,p,t)
  du[1,1] = 0.3u[1]
  du[2,1] = 0.6u[1]
  du[3,1] = 0.2u[1]
  du[1,2] = 1.2u[2]
  du[2,2] = 0.2u[2]
  du[3,2] = 0.3u[2]
end")
u0 = c(1.0,0.0,0.0)
tspan <- list(0.0,100.0)
noise.dims = list(3,2)
sol = diffeqr::sde.solve('f','g',u0,tspan,saveat=0.005,noise.dims=noise.dims)
udf = as.data.frame(sol$u)
#plotly::plot_ly(udf, x = ~V1, y = ~V2, z = ~V3, type = 'scatter3d', mode = 'lines')
```

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