

# Package ‘UComp’

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**Version** 1.1

**Title** Automatic Unobserved Components Models

**Description** Comprehensive analysis and forecasting

of univariate time series using automatic  
unobserved components models and algorithms.

Harvey, AC (1989) <doi:10.1017/CBO9781107049994>.

Pedregal, DJ and Young PC (2002) <doi:10.1002/9780470996430>.

Durbin J and Koopman SJ (2012) <doi:10.1093/acprof:oso/9780199641178.001.0001>.

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## R topics documented:

|               |    |
|---------------|----|
| UComp-package | 2  |
| UC            | 3  |
| UCcomponents  | 5  |
| UCdisturb     | 5  |
| UCestim       | 6  |
| UCfilter      | 7  |
| UCmodel       | 8  |
| UCsetup       | 11 |
| UCsmooth      | 13 |
| UCvalidate    | 14 |

**Description**

Comprehensive analysis and forecasting of univariate time series using automatic unobserved components models and algorithms. Harvey, AC (1989) <doi:10.1017/CBO9781107049994>. Pedregal, DJ and Young PC (2002) <doi:10.1002/9780470996430>. Durbin J and Koopman SJ (2012) <doi:10.1093/acprof:oso/9780199641178.001.0001>.

**Details**

UComp is a package for time series modelling and forecasting of Unobserved Components models inspired on the structural family due to A.C. Harvey (Basic Structural Model: BSM), enhanced with automatic identification tools by Diego J. Pedregal. The package is designed for automatic identification among a wide range of possible models for trends, cycles, seasonal and irregular components. The model may include exogenous variables. ARMA irregular components and automatic detection of outliers are also possible.

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**References**

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- Pedregal, D. J., & Young, P. C. (2002). Statistical approaches to modelling and forecasting time series. In M. Clements, & D. Hendry (Eds.), Companion to economic forecasting (pp. 69–104). Oxford: Blackwell Publishers.
- Durbin J, Koopman SJ (2012). Time Series Analysis by State Space Methods. 38. Oxford University Press.
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|    |    |
|----|----|
| UC | UC |
|----|----|

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## Description

Runs all relevant functions for UC modelling

## Usage

```
UC(
  y,
  u = NULL,
  model = "?/none/?/?",
  h = NA,
  outlier = NA,
  tTest = FALSE,
  criterion = "aic",
  periods = NA,
  verbose = TRUE,
  stepwise = FALSE,
  p0 = NA,
  cLlik = TRUE,
  arma = TRUE
)
```

## Arguments

- y** a time series to forecast (it may be either a numerical vector or a time series object). This is the only input required. If a vector, the additional input **periods** should be supplied compulsorily (see below).
- u** a matrix of input time series. If the output wanted to be forecast, matrix **u** should contain future values for inputs.
- model** the model to estimate. It is a single string indicating the type of model for each component. It allows two formats "trend/seasonal/irregular" or "trend/cycle/seasonal/irregular". The possibilities available for each component are:
- Trend: ? / none / rw / irw / llt / dt;
  - Seasonal: ? / none / equal / different;
  - Irregular: ? / none / arma(0, 0) / arma(p, q) - with p and q integer positive orders;
  - Cycles: ? / none / combination of positive or negative numbers.
- Positive numbers fix the period of the cycle while negative values estimate the period taking as initial condition the absolute value of the period supplied. Several cycles with positive or negative values are possible and if a question mark is included, the model test for the existence of the cycles specified (check the examples below).

|                  |   |
|------------------|---|
| <b>h</b>         | forecast horizon. If the model includes inputs h is not used, the lenght of u is used instead.  |
| <b>outlier</b>   | critical level of outlier tests. If NA it does not carry out any outlier detection (default). A negative value indicates critical minimum t test for one run of outlier detection after identification. A positive value indicates the critical minium t test for outlier detection in any model during identification. |
| <b>tTest</b>     | augmented Dickey Fuller test for unit roots (TRUE / FALSE). The number of models to search for is reduced, depending on the result of this test.  |
| <b>criterion</b> | information criterion for identification ("aic", "bic" or "aicc").  |
| <b>periods</b>   | vector of fundamental period and harmonics.   |
| <b>verbose</b>   | intermediate results shown about progress of estimation (TRUE / FALSE).   |
| <b>stepwise</b>  | stepwise identification procedure (TRUE / FALSE).   |
| <b>p0</b>        | initial condition for parameter estimates.  |
| <b>cLlik</b>     | reserved input  |
| <b>arma</b>      | check for arma models for irregular components (TRUE / FALSE).  |

## Details

See help of UCmodel.

## Value

An object of class UComp. See UCmodel.

## Author(s)

Diego J. Pedregal

## See Also

[UC](#), [UCmodel](#), [UCvalidate](#), [UCfilter](#), [UCsmooth](#), [UCdisturb](#), [UCcomponents](#)

## Examples

```
y <- log(AirPassengers)
m1 <- UC(y)
m1 <- UC(y, model = "llt/different/arma(0,0)")
```

---

UCcomponents

*UCcomponents*

---

### Description

Estimates components of UC models

### Usage

`UCcomponents(sys)`

### Arguments

`sys` an object of type UComp created with UCmodel

### Value

The same input object with the appropriate fields filled in, in particular:

|                    |  |
|--------------------|--|
| <code>comp</code>  | Estimated components in matrix form          |
| <code>compV</code> | Estimated components variance in matrix form |

### Author(s)

Diego J. Pedregal

### See Also

[UC](#), [UCmodel](#), [UCvalidate](#), [UCfilter](#), [UCsmooth](#), [UCdisturb](#)

### Examples

```
m1 <- UC(log(AirPassengers))
m1 <- UCcomponents(m1)
```

---

UCdisturb

*UCdisturb*

---

### Description

Runs the Disturbance Smoother for UC models

### Usage

`UCdisturb(sys)`

**Arguments**

`sys` an object of type `UComp` created with `UCmodel`

**Value**

The same input object with the appropriate fields filled in, in particular:

|                    |                                     |
|--------------------|-------------------------------------|
| <code>yFit</code>  | Fitted values of output             |
| <code>yFitV</code> | Variance of fitted values of output |
| <code>a</code>     | State estimates                     |
| <code>P</code>     | Variance of state estimates         |
| <code>eta</code>   | State perturbations estimates       |
| <code>eps</code>   | Observed perturbations estimates    |

**Author(s)**

Diego J. Pedregal

**See Also**

[UC](#), [UCmodel](#), [UCvalidate](#), [UCfilter](#), [UCsmooth](#), [UCcomponents](#)

**Examples**

```
m1 <- UCmodel(log(AirPassengers))
m1 <- UCdisturb(m1)
```

**Description**

Estimates and forecasts UC models

**Usage**

```
UCestim(sys)
```

**Arguments**

`sys` an object of type `UComp` created with `UCmodel`

**Details**

`UCestim` estimates and forecasts a time series using an UC model

**Value**

The same input object with the appropriate fields filled in, in particular:

|          |   |
|----------|---|
| p        | Estimated parameters  |
| v        | Estimated innovations (white noise in correctly specified models) |
| yFor     | Forecasted values of output                                       |
| yForV    | Variance of forecasted values of output                           |
| criteria | Value of criteria for estimated model                             |

**Author(s)**

Diego J. Pedregal

**See Also**

[UC](#), [UCmodel](#), [UCvalidate](#), [UCfilter](#), [UCsmooth](#), [UCdisturb](#), [UCcomponents](#)

**Examples**

```
m1 <- UCsetup(log(AirPassengers))
m1 <- UCestim(m1)
```

UCfilter

*UCfilter*

**Description**

Runs the Kalman Filter for UC models

**Usage**

```
UCfilter(sys)
```

**Arguments**

|     |  |
|-----|--|
| sys | an object of type UComp created with UCmodel |
|-----|--|

**Value**

The same input object with the appropriate fields filled in, in particular:

|       |                                     |
|-------|-------------------------------------|
| yFit  | Fitted values of output             |
| yFitV | Variance of fitted values of output |
| a     | State estimates                     |
| P     | Variance of state estimates         |

**Author(s)**

Diego J. Pedregal

**See Also**

[UC](#), [UCmodel1](#), [UCvalidate](#), [UCsmooth](#), [UCdisturb](#), [UCcomponents](#)

**Examples**

```
m1 <- UCmodel(log(AirPassengers))
m1 <- UCfilter(m1)
```

**UCmodel**

*UCmodel*

**Description**

Estimates and forecasts UC general univariate models

**Usage**

```
UCmodel(
  y,
  u = NULL,
  model = "?/none/?/?",
  h = NA,
  outlier = NA,
  tTest = FALSE,
  criterion = "aic",
  periods = NA,
  verbose = FALSE,
  stepwise = FALSE,
  p0 = NA,
  cLlik = TRUE,
  arma = TRUE
)
```

**Arguments**

- |              |   |
|--------------|---|
| <b>y</b>     | a time series to forecast (it may be either a numerical vector or a time series object). This is the only input required. If a vector, the additional input <code>periods</code> should be supplied compulsorily (see below).           |
| <b>u</b>     | a matrix of input time series. If the output wanted to be forecast, matrix <code>u</code> should contain future values for inputs.  |
| <b>model</b> | the model to estimate. It is a single string indicating the type of model for each component. It allows two formats "trend/seasonal/irregular" or "trend/cycle/seasonal/irregular". The possibilities available for each component are: |

- Trend: ? / none / rw / irw / llt / dt;
- Seasonal: ? / none / equal / different;
- Irregular: ? / none / arma(0, 0) / arma(p, q) - with p and q integer positive orders;
- Cycles: ? / none / combination of positive or negative numbers.  
Positive numbers fix the period of the cycle while negative values estimate the period taking as initial condition the absolute value of the period supplied. Several cycles with positive or negative values are possible and if a question mark is included, the model test for the existence of the cycles specified (check the examples below).

|                  |   |
|------------------|---|
| <b>h</b>         | forecast horizon. If the model includes inputs h is not used, the lenght of u is used instead.  |
| <b>outlier</b>   | critical level of outlier tests. If NA it does not carry out any outlier detection (default). A negative value indicates critical minimum t test for one run of outlier detection after identification. A positive value indicates the critical minium t test for outlier detection in any model during identification. |
| <b>tTest</b>     | augmented Dickey Fuller test for unit roots (TRUE / FALSE). The number of models to search for is reduced, depending on the result of this test.  |
| <b>criterion</b> | information criterion for identification ("aic", "bic" or "aicc").  |
| <b>periods</b>   | vector of fundamental period and harmonics.   |
| <b>verbose</b>   | intermediate results shown about progress of estimation (TRUE / FALSE).   |
| <b>stepwise</b>  | stepwise identification procedure (TRUE / FALSE).   |
| <b>p0</b>        | initial condition for parameter estimates.  |
| <b>cLlik</b>     | reserved input  |
| <b>arma</b>      | check for arma models for irregular components (TRUE / FALSE).  |

## Details

UCmodel is a function for modelling and forecasting univariate time series according to Unobserved Components models (UC). It sets up the model with a number of control variables that govern the way the rest of functions in the package will work. It also estimates the model parameters by Maximum Likelihood and forecasts the data.

## Value

An object of class UComp. It is a list with fields including all the inputs and the fields listed below as outputs. All the functions in this package fill in part of the fields of any UComp object as specified in what follows (function UC fills in all of them at once):

After running UCmodel or UCestim:

|              |   |
|--------------|---|
| <b>p</b>     | Estimated parameters  |
| <b>v</b>     | Estimated innovations (white noise in correctly specified models) |
| <b>yFor</b>  | Forecasted values of output                                       |
| <b>yForV</b> | Variance of forecasted values of output                           |

**criteria**      Value of criteria for estimated model

After running **UCvalidate**:

**table**      Estimation and validation table

After running **UCcomponents**:

**comp**      Estimated components in matrix form

**compV**      Estimated components variance in matrix form

After running **UCfilter**, **UCsmooth** or **UCdisturb**:

**yFit**      Fitted values of output

**yFitV**      Variance of fitted values of output

**a**      State estimates

**P**      Variance of state estimates

**aFor**      Forecasts of states

**PFor**      Forecasts of states variances

After running **UCdisturb**:

**eta**      State perturbations estimates

**eps**      Observed perturbations estimates

## Author(s)

Diego J. Pedregal

## See Also

[UCvalidate](#), [UCfilter](#), [UCsmooth](#), [UCdisturb](#), [UCcomponents](#)

## Examples

```
y <- log(AirPassengers)
m1 <- UCmodel(y)
m1 <- UCmodel(y, , model = "llt/equql/arma(0,0)")
```

---

*UCsetup**UCsetup*

---

**Description**

Sets up UC general univariate models

**Usage**

```
UCsetup(
  y,
  u = NULL,
  model = "?/none/?/?",
  h = NA,
  outlier = NA,
  tTest = FALSE,
  criterion = "aic",
  periods = NA,
  verbose = FALSE,
  stepwise = FALSE,
  p0 = NA,
  cLlik = TRUE,
  arma = TRUE
)
```

**Arguments**

- y** a time series to forecast (it may be either a numerical vector or a time series object). This is the only input required. If a vector, the additional input **periods** should be supplied compulsorily (see below).
- u** a matrix of input time series. If the output wanted to be forecast, matrix **u** should contain future values for inputs.
- model** the model to estimate. It is a single string indicating the type of model for each component. It allows two formats "trend/seasonal/irregular" or "trend/cycle/seasonal/irregular". The possibilities available for each component are:
- Trend: ? / none / rw / irw / llt / dt;
  - Seasonal: ? / none / equal / different;
  - Irregular: ? / none / arma(0, 0) / arma(p, q) - with p and q integer positive orders;
  - Cycles: ? / none / combination of positive or negative numbers.
- Positive numbers fix the period of the cycle while negative values estimate the period taking as initial condition the absolute value of the period supplied. Several cycles with positive or negative values are possible and if a question mark is included, the model test for the existence of the cycles specified (check the examples below).

|                  |   |
|------------------|---|
| <b>h</b>         | forecast horizon. If the model includes inputs h is not used, the lenght of u is used instead.  |
| <b>outlier</b>   | critical level of outlier tests. If NA it does not carry out any outlier detection (default). A negative value indicates critical minimum t test for one run of outlier detection after identification. A positive value indicates the critical minium t test for outlier detection in any model during identification. |
| <b>tTest</b>     | augmented Dickey Fuller test for unit roots (TRUE / FALSE). The number of models to search for is reduced, depending on the result of this test.  |
| <b>criterion</b> | information criterion for identification ("aic", "bic" or "aicc").  |
| <b>periods</b>   | vector of fundamental period and harmonics.   |
| <b>verbose</b>   | intermediate results shown about progress of estimation (TRUE / FALSE).   |
| <b>stepwise</b>  | stepwise identification procedure (TRUE / FALSE).   |
| <b>p0</b>        | initial condition for parameter estimates.  |
| <b>cLlik</b>     | reserved input  |
| <b>arma</b>      | check for arma models for irregular components (TRUE / FALSE).  |

## Details

See help of UCmodel.

## Value

An object of class UComp. See UCmodel.

## Author(s)

Diego J. Pedregal

## See Also

[UC](#), [UCmodel](#), [UCvalidate](#), [UCfilter](#), [UCsmooth](#), [UCdisturb](#), [UCcomponents](#)

## Examples

```
y <- log(AirPassengers)
m1 <- UCsetup(y)
m1 <- UCsetup(y,  model = "llt/equal/arma(0,0)")
m1 <- UCsetup(y,  outlier = 4)
```

---

UCsmooth

UCsmooth

---

## Description

Runs the Fixed Interval Smoother for UC models

## Usage

UCsmooth(sys)

## Arguments

sys                   an object of type UComp created with UCmodel

## Value

The same input object with the appropriate fields filled in, in particular:

|       |                                     |
|-------|-------------------------------------|
| yFit  | Fitted values of output             |
| yFitV | Variance of fitted values of output |
| a     | State estimates                     |
| P     | Variance of state estimates         |

## Author(s)

Diego J. Pedregal

## See Also

[UC](#), [UCmodel](#), [UCvalidate](#), [UCfilter](#), [UCdisturb](#), [UCcomponents](#)

## Examples

```
m1 <- UCmodel(log(AirPassengers))
m1 <- UCsmooth(m1)
```

---

UCvalidate

---

*UCvalidate*

---

### Description

Shows a table of estimation and diagnostics results for UC models

### Usage

`UCvalidate(sys)`

### Arguments

`sys`                  an object of type `UComp` created with `UCmodel`

### Value

The same input object with the appropriate fields filled in, in particular:

`table`                  Estimation and validation table

### Author(s)

Diego J. Pedregal

### See Also

[UC](#), [UCmodel](#), [UCfilter](#), [UCsmooth](#), [UCdisturb](#), [UCcomponents](#)

### Examples

```
m1 <- UCmodel(log(AirPassengers))
m1 <- UCvalidate(m1)
```

# Index

UC, [3, 4–8, 12–14](#)  
UCcomponents, [4, 5, 6–8, 10, 12–14](#)  
UCdisturb, [4, 5, 5, 7, 8, 10, 12–14](#)  
UCestim, [6](#)  
UCfilter, [4–7, 7, 10, 12–14](#)  
UCmodel, [4–8, 8, 12–14](#)  
UComp (UComp-package), [2](#)  
UComp-package, [2](#)  
UCsetup, [11](#)  
UCsmooth, [4–8, 10, 12, 13, 14](#)  
UCvalidate, [4–8, 10, 12, 13, 14](#)