

# Package ‘TrackReconstruction’

July 15, 2019

**Type** Package

**Title** Reconstruct Animal Tracks from Magnetometer, Accelerometer,  
Depth and Optional Speed Data

**Version** 1.2

**Date** 2019-07-14

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**Depends** R(>= 2.10.0), fields, RColorBrewer

**Suggests** lattice, onion, plotrix, rgl, scatterplot3d

**Description** Reconstructs animal tracks from magnetometer, accelerometer, depth and optional speed data. Designed primarily using data from Wildlife Computers Daily Diary tags deployed on northern fur seals.

**License** GPL (>= 2)

**LazyLoad** yes

**NeedsCompilation** no

**Repository** CRAN

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## R topics documented:

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TrackReconstruction-package

*Reconstruct Animal Tracks from Biologger Data.*

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## Description

Given accelerometer, magnetometer, depth and optional speed data, this package will reconstruct animal paths. Given GPS data, pseudotracks can be geolocated. The package was designed using northern fur seals (*Callorhinus ursinus*) but is probably suitable as a launching pad for other animals.

## Details

Package: TrackReconstruction  
 Type: Package  
 Version: 1.2  
 Date: 2019-07-13  
 License: GPL (>=2)

Includes functions to Standardize logger data, format GPS data, find gaps in the raw data, navigation functions to calculate distance, bearing, latitude and longitude, functions to calculate pseudotracks, to georeference the tracks and finally to plot the tracks with color bathymetry. A vignette includes some additional Perl code to deal with large data files as well as additional plotting code to make 3D plots and 2D animations.

DeadReckoning

GapFinder  
 GeoReference  
 GeoRef (a wrapper for GeoReference)  
 GPStable  
 GraphLimits  
 Mapper  
 Navigation Functions (CalcBearing CalcLatitude CalcLongitude CalcDistance)  
 Splitter  
 Standardize

#### Author(s)

Brian Battaile  
 Maintainer: Brian Battaile <brian.battaile@gmail.com>

#### References

Wilson R.P., Liebsch, N., Davies, I.M., Quintana, F., Weimerskirch, H., Storch, S., Lucke, K., Siebert, U., Zankl, S., Muller, G., Zimmer, I., Scolaro, A., Campagna, C., Plotz, J., Bornemann, H., Teilmann, J. and McMahon, C.R. (2007) All at sea with animal tracks; methodological and analytical solutions for the resolution of movement. *Deep-Sea Research II* 54:193-210

Shepard E.L.C., Wilson, R.P., Halsey, L.G., Quintana, F., Laich, A.G., Gleiss, A.C., Liebsch, N., Myers, A.E., Norman, B. (2008) Derivation of body motion via appropriate smoothing of acceleration data. *Aquatic Biology* 4:235-241

Wilson R.P., Wilson M.P. (1988) Dead reckoning: a new technique for determining penguin movements at sea. *Meeresforschung* 32:2 155-158

#### See Also

R packages diveMove, adehabitat, animalTrack, argosfilter and crawl

#### Examples

```

betas<-Standardize(1,1,-1,1,1,1,-57.8,68.76,-61.8,64.2,-70.16,58.08,
-10.1,9.55,-9.75,9.72,-9.91,9.43)
#get declination and inclination data for study area
decinc<-c(10.228,65.918)
#data set with 6 associated GPS fixes in the "gpsdata" data set
data(rawdata)
DRoutput<-DeadReckoning(rawdata,betas,decinc,HZ=16,RmL=2,DepthHz=1,SpdCalc=3,MaxSpd=3.5)
#prepare GPS data
data(gpsdata02)
gpsformat<-GPStable(gpsdata02)
Georeferenced<-GeoRef(DRoutput,gpsformat)
plot(Georeferenced$Longitude,Georeferenced$Latitude,pch=".")
points(gpsformat$Longitude[2],gpsformat$Latitude[2],pch="S",col="Red") #Start
points(gpsformat$Longitude[7],gpsformat$Latitude[7],pch="F",col="Blue") #Finish
  
```

```

#Intermediate GPS points
points(gpsformat$Longitude[3:6],gpsformat$Latitude[3:6],pch="*",col="Red")

## Not run:
#plot the data with a bathymetric background, note how the axis dimensions have changed to
#give a more realistic path relative to that produced in the simple plot call. See the vignette
#or ?bathymetry for information on how to get bathymetric data for your study area.
data(bathymetry)
#This may take a minute or two
image.xyz=tapply(bathymetry$Depth, list(bathymetry$Long, bathymetry$Lat), unique)
Mapper(Georeferenced, gpsformat[2:7,], image.xyz, ExpFact = 500, minlat = 51, maxlat = 60,
minlong = -177, maxlong = -163, Title = "Fun Graph!!!")
#That entire animals trip plotted
data(georef1min02)
data(gpsdata02)
Mapper(georef1min02, gpsdata02, image.xyz, ExpFact = 500, minlat = 51, maxlat = 60,
minlong = -177, maxlong = -163, Title = "Fun Graph!!!")

## End(Not run)

```

---

bathymetry

*Bathymetry data for the Eastern Bering Sea*


---

### Description

Bathymetry data for the Eastern Bering Sea at a resolution of 30 arc seconds downloaded from <http://www.gebco.net>

### Usage

```
data(bathymetry)
```

### Format

A data frame with 1814400 observations on the following 3 variables.

Long a numeric vector

Lat a numeric vector

Depth a numeric vector

### Details

If you want to do color graphing of the tracks within R I have provided a Mapper function to do this but it requires gridded (raster) bathymetric data to create the background map. The source for this example data set comes from the General Bathymetric Chart of the Oceans or GEBCO at <http://www.gebco.net>.

**Examples**

```

data(bathymetry)
str(bathymetry)
head(bathymetry);tail(bathymetry)
bathymetryBogs<-subset(bathymetry,Long<=(-166) & Long >=(-169)
& Lat<= 54.5 & Lat >=53,select=Long:Depth)

image.xyz=tapply(bathymetryBogs$Depth, list(bathymetryBogs$Long, bathymetryBogs$Lat), unique)
#create palette for depth colors
Bathymetry.palette<-colorRampPalette(brewer.pal(9, "Blues"),bias=3)
#Plot the background map image
image.plot(image.xyz,
col=c(rev(Bathymetry.palette(200)),terrain.colors(100)),#gray(0:20/20),
breaks=round(c(seq(from=min(image.xyz),to=0,length.out=201),seq(from=max(image.xyz)/101
,to=max(image.xyz),length.out=100)))
#,smallplot=2 #plots legend off x axis
)
## Not run:
#If you want to map the entire bathymetry file, it takes a while
image.xyz=tapply(bathymetry$Depth, list(bathymetry$Long, bathymetry$Lat), unique)
#create palette for depth colors
Bathymetry.palette<-colorRampPalette(brewer.pal(9, "Blues"),bias=3)
#Plot the background map image
image.plot(image.xyz,
col=c(rev(Bathymetry.palette(200)),terrain.colors(100)),#gray(0:20/20),
breaks=round(c(seq(from=min(image.xyz),to=0,length.out=201),seq(from=max(image.xyz)/101
,to=max(image.xyz),length.out=100)))
#,smallplot=2 #plots legend off x axis
)

## End(Not run)

```

---

CalcBearing

*Calculate Bearing*


---

**Description**

Calculates Bearing given initial latitude and longitude and ending latitude and longitude in decimal degrees and returns bearing in radians.

**Usage**

```
CalcBearing(initialLat, initialLong, finalLat, finalLong)
```

**Arguments**

initialLat	initial Latitude
initialLong	initial Longitude
finalLat	ending Latitude
finalLong	ending Longitude

**Details**

Data must be provided in decimal degrees (e.g. 162.546). Longitude values west of the prime meridian are 0 to -180. Latitude values south of the equator are 0 to -90. As one travels from point A to point B, the bearing to point B changes. This function calculates the bearing from point A to point B at point A. This function is primarily used internally in the GPStable and GeoReference functions.

**Value**

Bearing in Radians

**Author(s)**

Brian Battaile

**References**

<https://www.movable-type.co.uk/scripts/latlong.html>

**Examples**

```
#Bearing to Los Angeles from New York
Bearing<-CalcBearing(40.7697,-73.9735,34.0522,-118.2428)
Bearing
Bearing*360/(2*pi) #transform radians to degrees
```

---

CalcDistance

*Calculate Distance Between Two Points*

---

**Description**

Calculates the distance between two points on the globe given latitude and longitude in decimal degrees and returning distance in kilometers.

**Usage**

```
CalcDistance(initialLat, initialLong, finalLat, finalLong)
```

**Arguments**

initialLat	initial Latitude
initialLong	initial Longitude
finalLat	ending Latitude
finalLong	ending Longitude

**Details**

Data must be provided in decimal degrees (e.g. 162.546). Longitude values west of the prime meridian are 0 to -180. Latitude values south of the equator are 0 to -90. This function is primarily used internally in the GPStable and GeoReference functions.

**Value**

Distance in Kilometers

**Author(s)**

Brian Battaile

**References**

<https://www.movable-type.co.uk/scripts/latlong.html>

**Examples**

```
##Distance from New York to Los Angeles given Latitude and Longitude of New York and Los Angeles.
Howfar<-CalcDistance(40.7697,-73.9735,34.0522,-118.2428)
Howfar
```

---

CalcLatitude

*Calculate Latitude*

---

**Description**

Calculates an unknown latitude given an initial latitude, distance traveled in meters and bearing.

**Usage**

```
CalcLatitude(initialLat, distance, bearing)
```

**Arguments**

initialLat	initial Latitude
distance	distance in meters
bearing	bearing in radians

**Details**

Data must be provided in decimal degrees (e.g.162.546). Longitude values west of the prime meridian are 0 to -180. Latitude values south of the equator are 0 to -90. Calculates an unknown latitude given an initial latitude, distance traveled in meters and bearing in radians. This function is primarily used internally in the gpstable and GeoReference functions.

**Value**

Latitude in radians

**Author(s)**

Brian Battaile

**References**

<https://www.movable-type.co.uk/scripts/latlong.html>

**Examples**

```
#Calculate the latitude of Los Angeles given a starting point in Manhattan and the distance
#and bearing to Los Angeles.
Lat<-CalcLatitude (40.7697,3938000,-1.507516)
#transform to degrees
Lat*360/(2*pi)
```

---

CalcLongitude

*Calculate Longitude*

---

**Description**

Calculate the longitude of a destination given initial latitude and longitude, distance traveled, bearing and final latitude.

**Usage**

```
CalcLongitude(initialLat, destinationLat, initialLong, distance, bearing)
```

**Arguments**

initialLat	initial Latitude
destinationLat	final Latitude
initialLong	initial Longitude
distance	distance from initial to final in meters
bearing	bearing from point of departure to final destination

**Details**

Calculates a destination's longitude given initial latitude and longitude in degrees (e.g.162.546, Longitude values west of the prime meridian are 0 to -180. Latitude values south of the equator are 0 to -90), destination latitude in RADIANS (result of CalcLatitude function), distance traveled in meters and bearing in radians. This function is primarily used internally in the GPStable and GeoReference functions.



**Value**

Longitude of final destination in radians.

**Author(s)**

Brian Battaile

**References**

<https://www.movable-type.co.uk/scripts/latlong.html>

**Examples**

```
#Longitude of Los Angeles starting in Manhattan
Long <- CalcLongitude(40.7697,0.5943228,-73.9735,3938000,-1.507516)
#transform to degrees
Long*360/(2*pi)

##Use results of CalcLatitude
Lat<-CalcLatitude (40.7697,3938000,-1.507516)
Long <- CalcLongitude(40.7697,Lat,-73.9735,3938000,-1.507516)
#transform to degrees
Long*360/(2*pi)
```

---

DeadReckoning

*Calculates Dead Reckoning*

---

**Description**

This function takes triaxial magnetometer, accelerometer and optional speed data to estimate the path traveled (pseudotrack) by a tagged animal based on Wilson et al. (2007).

**Usage**

```
DeadReckoning(rawdata, betas, decinc, Hz = 16, RmL = 2, DepthHz = 1, SpdCalc=1,
MaxSpd=NULL)
```

**Arguments**

rawdata	matrix or data frame of magnetometer and accelerometer with column headings specified in Details.
betas	matrix or data frame of coefficients (slope and intercept) that standardizes magnetometer and accelerometer data between -1 and +1. This can come from the Standardize function.
decinc	vector of c(Declination, Inclination) values in decimal degrees format in that order.

Hz	frequency of data collection in Hz of magnetometers. The assumption here is that the accelerometer Hz is at least as high as the magnetometers and that all the magnetometer channels have the same Hz. See Details.
RmL	Running mean length in seconds, required to separate "dynamic" and "static" acceleration.
DepthHz	Frequency of data collection in Hz of Depth channel.
SpdCalc	Integer of value 1,2,3 or 4 (5 and 6 are unsupported) depending on type of speed data supplied, see details.
MaxSpd	If SpdCalc=3, the max speed of your animal in m/s. If SpdCalc=4, the constant speed of your animal in m/s.

### Details

Rawdata must have columns DateTime or separated as Date and Time, plus Depth, MagSurge, MagHeave, MagSway, AccSurge, AccHeave, AccSway and optional Speed in a data frame with those exact column names (Mag=Magnetometer and Acc= Accelerometer). It must have an extra number of rows =Hz\*RmL\*0.5 at beginning and end that will be trimmed on final output. Because some users may program tags to collect acceleration data at a higher Hz than magnetometer data (for example when looking for a Jerk signal), the DeadReckoning function automatically subsets the data set to those samples (rows) that do NOT have "NA" in the MagSurge column.

Betas is a [2,6] data frame with intercept in the first row and slope in the second row and can be directly taken from Standardize function output or user input. If you do not use the output of the Standardize function, the row names must be c("B0 Intercept","B1 Slope") and the column names must be c("MagSurge","MagHeave","MagSway","AccSurge","AccHeave","AccSway") though the order is not important. See the help on the Standardize function for more information.

Declination and inclination data can be found at various internet sites such as the World Magnetic Model 2010 Calculator from the British Geological Survey (see references).

RmL-please read Shepard et al.(2008) and perhaps Wilson et al.(2007) for information on an appropriate Running Mean Length for your data and study animal.

#### SpdCalc

=1 if Speed is supplied in rawdata at the same Hz as Acc and Mag Hz in m/s.

=2 if Speed is supplied in m/s but at Hz lower than Acc and Mag.

=3 if no speed is supplied and should be estimated from integrating (a running sum) the dynamic portion of the surge channel of acceleration and normalized using a linear model to meters/second from 0 to your max speed (MaxSpd) input.

=4 a constant speed is assumed which is entered as the MaxSpd.

=5 if no speed is supplied and should be estimated from ascent and descent rates. \*\*\*Not yet implemented.\*\*\*

=6 if speed is to be calculated from sound data. \*\*\*Not yet implemented\*\*\*

### Value

data.frame with columns DateTime, Xdim, Ydim, Depth and Speed. DateTime is the data and time columns pasted together using as.character. Xdim and Ydim are cartesian coordinates from the origin in meters. Depth has been linearly interpolated from initial Depth Hz to Magnetometer Hz and Speed is either that supplied by the user or calculated via one of the methods outlined above.

**Author(s)**

Brian Battaile

**References**

One possible source for declination and inclination data [http://www.geomag.bgs.ac.uk/data\\_service/models\\_compass/wmm\\_calc.html](http://www.geomag.bgs.ac.uk/data_service/models_compass/wmm_calc.html)

Wilson R.P., Liebsch,N., Davies,I.M., Quintana,F., Weimerskirch,H., Storch,S., Lucke,K., Siebert,U., Zankl,S., Muller,G., Zimmer,I., Scolaro,A., Campagna,C., Plotz,J., Bornemann,H., Teilmann,J. and McMahon,C.R. (2007) All at sea with animal tracks; methodological and analytical solutions for the resolution of movement. *Deep-Sea Research II* 54:193-210

Shepard E.L.C., Wilson, R.P., Halsey, L.G., Quintana, F., Laich, A.G., Gleiss, A.C., Liebsch, N., Myers, A.E., Norman, B. (2008) Derivation of body motion via appropriate smoothing of acceleration data. *Aquatic Biology* 4:235-241

**Examples**

```
#A simple square example
betas<-Standardize(1,1,1,1,1,1,-1,1,-1,1,-1,1,-1,1,-1,1)
data(square)
decinc<-c(0,65)
DRoutput<-DeadReckoning(square,betas,decinc,HZ=1,RmL=2,DepthHz=1,SpdCalc=1)
plot(DRoutput$Ydim,DRoutput$Xdim)

#Standardize tag output
betas<-Standardize(1,1,-1,1,1,1,-57.8,68.76,-61.8,64.2,-70.16,58.08,
-10.1,9.55,-9.75,9.72,-9.91,9.43)
#Declination and inclination data for study area
decinc<-c(10.228,65.918)
#data set with 7 associated GPS fixes in the "gpsdata02" data set
data(rawdata)
DRoutput<-DeadReckoning(rawdata,betas,decinc,HZ=16,RmL=2,DepthHz=1,SpdCalc=3,MaxSpd=3.5)
plot(DRoutput$Ydim,DRoutput$Xdim)
```

---

GapFinder

*Find gaps in your data file*

---

**Description**

The function looks at the DateTime or Date and Time stamps of your data file and sees if any consecutive entries have a difference of greater than the timediff parameter.

**Usage**

```
GapFinder(rawdata, timediff = 1, timeformat = "%d-%b-%Y %H:%M:%S")
```

**Arguments**

rawdata	Data with a combined DateTime or separate Date and Time stamp columns labeled as such.
timediff	The amount of time in seconds that is expected between each entry (row). Typically this would be your data collection Hz (for Hz=16, timediff=1/16, for Hz=0.5, timediff=2) but results will depend on whether or not you have information on decimal seconds. One second is probably small enough for most people and will avoid issues with decimal seconds, but this depends on the scale that is important to you.
timeformat	Format of the DateTime or separate Date and Time stamp after it is pasted together with a space between. See the strptime function for codes. The default value is the value of the example files.

**Value**

Returns a data frame with 4 columns indicating the row that the gap occurs, the amount of time between the gap, and the DateTime stamp on either end of the gap. The data frame holds a maximum of 1000 entries, so if you have more gaps, then you can alter the program to create a larger dataframe. Hopefully you don't have anywhere near that many gaps.

**Author(s)**

Brian Battaile

**Examples**

```
data(rawdatagap)
gaps<-GapFinder(rawdatagap, timediff = 1, timeformat = "%d-%b-%Y %H:%M:%S")

#how timediff and a lack of decimal seconds information interact given a Hz of 16.
gaps<-GapFinder(rawdatagap, timediff = 1/16, timeformat = "%d-%b-%Y %H:%M:%S")
```

---

GeoRef

*Georeference the Dead Reckoning data*

---

**Description**

A wrapper function for the GeoReference function that georeferences a deadreckoning track with multiple GPS relocations.

**Usage**

```
GeoRef(drdata, gpsfdata)
```

**Arguments**

drdata	Data frame from, or similar in format as that produced by the DeadReckoning function.
gpsfdata	Data frame from, or similar in format as that produced by the GPStable function.

**Details**

Data that is not bookended by the DateTime stamp of the GPS relocations will be discarded. The DateTime stamp of the drdata and gpsfdata must be in the same format, see the strptime function help file for details.

**Value**

Returns a data frame with DateTime, Distance, LatRad, LongRad, Latitude, Longitude, Depth, Speed, NewX, NewY, and Bering of the Georeferenced Deadreckoned tracks. NewX and NewY are cartesian coordinates in meters. Distance is the distance from the origin to the georeferenced point in 2D.

**Author(s)**

Brian Battaile

**References**

Wilson R.P., Liebsch,N., Davies,I.M., Quintana,F., Weimerskirch,H., Storch,S., Lucke,K., Siebert,U., Zankl,S., Muller,G., Zimmer,I., Scolaro,A., Campagna,C., Plotz,J., Bornemann,H., Teilmann,J. and McMahon,C.R. (2007) All at sea with animal tracks; methodological and analytical solutions for the resolution of movement. Deep-Sea Research II 54:193-210

**Examples**

```
#Standardize tag output
betas<-Standardize(1,1,-1,1,1,1,-57.8,68.76,-61.8,64.2,-70.16,58.08,
-10.1,9.55,-9.75,9.72,-9.91,9.43)
#get declination and inclination data for study area
decinc<-c(10.228,65.918)
#data set with 6 associated GPS fixes in the "gpsdata" data set
data(rawdata)
DRoutput<-DeadReckoning(rawdata,betas,decinc,HZ=16,RmL=2,DepthHz=1,SpdCalc=3,MaxSpd=3.5)
#prepare GPS data
data(gpsdata02)
gpsformat<-GPStable(gpsdata02)
Georeferenced<-GeoRef(DRoutput,gpsformat)
plot(Georeferenced$Longitude,Georeferenced$Latitude,pch=".")
points(gpsformat$Longitude[2],gpsformat$Latitude[2],pch="S",col="Red") #Start
points(gpsformat$Longitude[7],gpsformat$Latitude[7],pch="F",col="Blue") #Finish
#Intermediate GPS points
points(gpsformat$Longitude[3:6],gpsformat$Latitude[3:6],pch="*",col="Red")
```

---

georef1min01	<i>GeoReferenced fur seal track</i>
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---

### Description

Georeferenced data from a fur seal track in the Bering Sea. Data has been thinned to relocations every 1 minute. This data set is used as an example in the vignette. `gpsdata01` is the complementary gps data for this pseudotrack.

### Usage

```
data(georef1min01)
```

### Format

A data frame with 6681 observations on the following 6 variables.

`DateTime` a character vector

`LatRad` a numeric vector, latitude given in radians

`LongRad` a numeric vector, longitude given in radians

`Latitude` a numeric vector, latitude given in decimal degrees

`Longitude` a numeric vector, longitude given in decimal degrees

`Depth` a numeric vector, in meters

### Details

Date files `georef1min02`, `georef1min03`, `georef1min26` and `georef1min95` have the same structure

### Examples

```
data(georef1min01)
head(georef1min01);tail(georef1min01)
str(georef1min01)
plot(georef1min01$Longitude, georef1min01$Latitude,pch=".")
data(gpsdata01)
points(gpsdata01$Longitude,gpsdata01$Latitude,col="red",pch="*")
```

---

georef1min02	<i>GeoReferenced fur seal track</i>
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---

## Description

Georeferenced data from a fur seal track in the Bering Sea. Data has been thinned to relocations every 1 minute. This data set is used as an example in the vignette and the Mapper function. `gpsdata02` is the complementary `gps` data for this pseudotrack.

## Usage

```
data(georef1min02)
```

## Format

A data frame with 9147 observations on the following 6 variables.

`DateTime` a character vector

`LatRad` a numeric vector, latitude given in radians

`LongRad` a numeric vector, longitude given in radians

`Latitude` a numeric vector, latitude given in decimal degrees

`Longitude` a numeric vector, longitude given in decimal degrees

`Depth` a numeric vector, in meters

## Details

Date files `georef1min01`, `georef1min03`, `georef1min26` and `georef1min95` have the same structure

## Examples

```
data(georef1min02)
head(georef1min02);tail(georef1min02)
str(georef1min02)
plot(georef1min02$Longitude, georef1min02$Latitude,pch=".")
data(gpsdata02)
points(gpsdata02$Longitude,gpsdata02$Latitude,col="red",pch="*")
```

---

`georef1min03`*GeoReferenced fur seal track*

---

**Description**

Georeferenced data from a fur seal track in the Bering Sea. Data has been thinned to relocations every 1 minute. This data set is used as an example in the vignette. `gpsdata03` is the complementary gps data for this pseudotrack.

**Usage**

```
data(georef1min03)
```

**Format**

A data frame with 6724 observations on the following 6 variables.

`DateTime` a character vector

`LatRad` a numeric vector, latitude given in radians

`LongRad` a numeric vector, longitude given in radians

`Latitude` a numeric vector, latitude given in decimal degrees

`Longitude` a numeric vector, longitude given in decimal degrees

`Depth` a numeric vector, in meters

**Details**

Date files `georef1min01`, `georef1min02`, `georef1min26` and `georef1min95` have the same structure

**Examples**

```
data(georef1min03)
head(georef1min03);tail(georef1min03)
str(georef1min03)
plot(georef1min03$Longitude, georef1min03$Latitude,pch=".")
data(gpsdata03)
points(gpsdata03$Longitude,gpsdata03$Latitude,col="red",pch="*")
```



---

georef1min26	<i>GeoReferenced fur seal track</i>
--------------	-------------------------------------

---

## Description

Georeferenced data from a fur seal track in the Bering Sea. Data has been thinned to relocations every 1 minute. This data set is used as an example in the Mapper function. `gpsdata26` is the complementary `gps` data for this pseudotrack.

## Usage

```
data(georef1min26)
```

## Format

A data frame with 430 observations on the following 6 variables.

`DateTime` a character vector

`LatRad` a numeric vector, latitude given in radians

`LongRad` a numeric vector, longitude given in radians

`Latitude` a numeric vector, latitude given in decimal degrees

`Longitude` a numeric vector, longitude given in decimal degrees

`Depth` a numeric vector, in meters

## Details

Date files `georef1min01`, `georef1min02`, `georef1min03` and `georef1min95` have the same structure

## Examples

```
data(georef1min26)
head(georef1min26);tail(georef1min26)
str(georef1min26)
plot(georef1min26$Longitude, georef1min26$Latitude,pch=".")
data(gpsdata26)
points(gpsdata26$Longitude,gpsdata26$Latitude,col="red",pch="*")
```

---

`georef1min95`*GeoReferenced fur seal track*

---

## Description

Georeferenced data from a fur seal track in the Bering Sea. Data has been thinned to relocations every 1 minute. This data set is used as an example in the Mapper function. `gpsdata95` is the complementary `gps` data for this pseudotrack.

## Usage

```
data(georef1min95)
```

## Format

A data frame with 6566 observations on the following 6 variables.

`DateTime` a character vector

`LatRad` a numeric vector, latitude given in radians

`LongRad` a numeric vector, longitude given in radians

`Latitude` a numeric vector, latitude given in decimal degrees

`Longitude` a numeric vector, longitude given in decimal degrees

`Depth` a numeric vector, in meters

## Details

Date files `georef1min01`, `georef1min02`, `georef1min03` and `georef1min26` have the same structure

## Examples

```
data(georef1min95)
head(georef1min95);tail(georef1min95)
str(georef1min95)
plot(georef1min95$Longitude, georef1min95$Latitude,pch=".")
data(gpsdata95)
points(gpsdata95$Longitude,gpsdata95$Latitude,col="red",pch="*")
```

**Description**

Takes relocation data and forces it to go through two known points (such as GPS fixes) at the beginning and end by rotating the track and either expanding or contracting each section by a constant percentage. The primary function used in the wrapper function GeoRef, you should use GeoRef if you have more than two GPS locations for your animal track.

**Usage**

```
GeoReference(drdata, gpsdata)
```

**Arguments**

drdata	Data frame from, or in a similar format as that produced by the DeadReckoning function
gpsdata	Data frame from, or in a similar format as that produced by the GPStable function.

**Details**

TimeDate stamp of first entry of drdata and gpsdata must be the same. The GeoRef function does this for you by matching the DateTime stamp in the drdata and gpsdata. The DateTime stamp of the drdata and gpsdata must be in the same format.

**Value**

Returns a data frame with DateTime, Distance, LatRad, LongRad, Latitude, Longitude, Depth, Speed, NewX, NewY, and Bearing of the Georeferenced Deadreckoning tracks. NewX and NewY are cartesian coordinates in meters. Distance is the distance from the origin to the new point in 2D.

**Author(s)**

Brian Battaile

**References**

Wilson R.P., Liebsch,N., Davies,I.M., Quintana,F., Weimerskirch,H., Storch,S., Lucke,K., Siebert,U., Zankl,S., Muller,G., Zimmer,I., Scolaro,A., Campagna,C., Plotz,J., Bornemann,H., Teilmann,J. and McMahon,C.R. (2007) All at sea with animal tracks; methodological and analytical solutions for the resolution of movement. *Deep-Sea Research II* 54:193-210

**Examples**

```
#Standardize tag output
betas<-Standardize(1,1,-1,1,1,1,-57.8,68.76,-61.8,64.2,-70.16,58.08,
-10.1,9.55,-9.75,9.72,-9.91,9.43)
#get declination and inclination data for study area
decinc<-c(10.228,65.918)
#data set with 7 associated GPS fixes in the "gpsdata02" data set
data(rawdata)
DRoutput<-DeadReckoning(rawdata,betas,decinc,HZ=16,RmL=2,DepthHz=1,SpdCalc=3,MaxSpd=3.5)
#prepare GPS data
data(gpsdata02)
gpsformat<-GPStable(gpsdata02)
Georeferenced<-GeoReference(DRoutput,gpsformat[c(2,3),])
plot(Georeferenced$Longitude,Georeferenced$Latitude,pch=".")
points(gpsformat$Longitude[2],gpsformat$Latitude[2],pch="S",col="Red")
points(gpsformat$Longitude[3],gpsformat$Latitude[3],pch="F",col="Blue")
```

---

gpsdata01

*GPS raw data*

---

**Description**

Complete gps file for northern fur seal track in the Bering Sea. Data taken by a wildlife computers mk10-F tag. georef1min01 is the complementary pseudotrack data for these gps points.

**Usage**

```
data(gpsdata01)
```

**Format**

A data frame with 233 observations on the following 3 variables.

DateTime a character vector

Latitude a numeric vector

Longitude a numeric vector

**Examples**

```
data(gpsdata01)
head(gpsdata01);tail(gpsdata01)
str(gpsdata01)
plot(gpsdata01$Longitude,gpsdata01$Latitude)
```

---

gpsdata02	<i>GPS raw data</i>
-----------	---------------------

---

**Description**

Complete gps file for northern fur seal track in the Bering Sea. Data taken by a wildlife computers mk10-F tag. This data set is used as an example in the `Mapper`, `GraphLimits`, `GeoRef`, `Splitter` and `GeoReference` functions and in the vignette. `georef1min02` is the complementary pseudotrack data for these gps points.

**Usage**

```
data(gpsdata02)
```

**Format**

A data frame with 276 observations on the following 3 variables.

`DateTime` a character vector

`Latitude` a numeric vector

`Longitude` a numeric vector

**Examples**

```
data(gpsdata02)
head(gpsdata02); tail(gpsdata02)
str(gpsdata02)
plot(gpsdata02$Longitude, gpsdata02$Latitude)
```

---

gpsdata03	<i>GPS raw data</i>
-----------	---------------------

---

**Description**

Complete gps file for northern fur seal track in the Bering Sea. Data taken by a wildlife computers mk10-F tag. `georef1min03` is the complementary pseudotrack data for these gps points.

**Usage**

```
data(gpsdata03)
```

**Format**

A data frame with 57 observations on the following 3 variables.

`DateTime` a character vector

`Latitude` a numeric vector

`Longitude` a numeric vector

**Examples**

```
data(gpsdata03)
head(gpsdata03);tail(gpsdata03)
str(gpsdata03)
plot(gpsdata03$Longitude,gpsdata03$Latitude)
```

---

gpsdata26

*GPS raw data*

---

**Description**

Complete gps file for northern fur seal track in the Bering Sea. Data taken by a wildlife computers mk10-F tag. This data set is used as an example in the Mapper function. georef1min26 is the complementary pseudotrack data for these gps points.

**Usage**

```
data(gpsdata26)
```

**Format**

A data frame with 9 observations on the following 3 variables.

DateTime a character vector

Latitude a numeric vector

Longitude a numeric vector

**Examples**

```
data(gpsdata26)
head(gpsdata26);tail(gpsdata26)
str(gpsdata26)
plot(gpsdata26$Longitude,gpsdata26$Latitude)
```

---

gpsdata95

*GPS raw data*

---

**Description**

Complete gps file for northern fur seal track in the Bering Sea. Data taken by a wildlife computers mk10-F tag. This data set is used as an example in the Mapper function. georef1min95 is the complementary pseudotrack data for these gps points.

**Usage**

```
data(gpsdata95)
```

**Format**

A data frame with 93 observations on the following 3 variables.

DateTime a character vector

Latitude a numeric vector

Longitude a numeric vector

**Examples**

```
data(gpsdata95)
head(gpsdata95);tail(gpsdata95)
str(gpsdata95)
plot(gpsdata95$Longitude,gpsdata95$Latitude)
```

---

 GPStable

*Format GPS data*


---

**Description**

Takes DateTime, Latitude and Longitude in decimal degrees and converts Latitude and Longitude into radians and calculates bearing and distance between consecutive locations

**Usage**

```
GPStable(rawdata)
```

**Arguments**

rawdata	data frame with DateTime, or Date and Time separately, in same format as dead-reckoning data, Latitude and Longitude in decimal degrees. Must use those column labels.
---------	--

**Details**

Data must be provided in decimal degrees (e.g. 162.546). Longitude values west of the prime meridian are 0 to -180. Latitude values south of the equator are 0 to -90. DateTime must be in the same format as output of DeadReckoning function or separated as Date and Time that can be pasted together to create the same format as output of the Deadreckoning function. Distance is calculated using the Spherical Law of Cosines (see references).

**Value**

Returns a data frame with columns DateTime, Latitude(Decimal Degrees), Longitude(Decimal Degrees), LatRad(Radians), LongRad(Radians), BearingRad, BearingDeg, DistanceKm. BearingRad and BearingDeg are the bearing calculated from point x to point x+1. DistanceKm is the distance between point x and point x-1.

**Author(s)**

Brian Battaile

**References**

<https://www.movable-type.co.uk/scripts/latlong.html>

**Examples**

```
data(gpsdata02)
head(gpsdata02)
gpsformat<-GPStable(gpsdata02)
head(gpsformat)
```

---

GraphLimits

*Determine Latitude and Longitude limits of a graph*

---

**Description**

Finds the minimum and maximum of the longitude and latitude and then adds on 2.5% of the latitude and longitude to create borders in the graph and accounts in a very simple way for projection distortion so long as maps are not too large.

**Usage**

```
GraphLimits(infile)
```

**Arguments**

`infile`            A file with columns of latitude and longitude labeled as Latitude and Longitude

**Details**

Internal function used in the Mapper function. It attempts to account for the change in distance covered between longitude as latitude changes by using the  $\cos(\text{latitude})$  of the center of the latitude of the graph, and adjusting the longitude to cover the same distance. Hence, the borders on the graph are set first by making the distances in latitude and longitude approximately equal in meters, then 2.5% is added on each end.

**Value**

Returns a list of 4 scalars defining the borders of the data

**Author(s)**

Brian Battaile



**Examples**

```
#Standardize tag output
betas<-Standardize(1,1,-1,1,1,1,-57.8,68.76,-61.8,64.2,-70.16,58.08,-10.1,9.55,-9.75,9.72,
-9.91,9.43)
#get declination and inclination data for study area
decinc<-c(10.228,65.918)
#data set with 11 associated GPS fixes in the "gpsdata" data set
data(rawdata)
DRoutput<-DeadReckoning(rawdata ,betas, decinc, Hz = 16, RmL = 2, DepthHz = 1, SpdCalc=3,
MaxSpd=3.5)
#prepare GPS data
data(gpsdata02)
gpsformat<-GPStable(gpsdata02)
Georeferenced<-GeoReference(DRoutput,gpsformat[1:2,])
Limits<-GraphLimits(Georeferenced)
Limits
```

Mapper

*Animal track plotting with a color map***Description**

Makes a color map of your animal track with terrain colors for land and shades of blue for depth

**Usage**

```
Mapper(inFile, gpsFile, bathyFile, ExpFact = 500, minlat = 51, maxlat = 60,
minlong = -177, maxlong = -163, Title = "Main")
```

**Arguments**

inFile	Track file of latitude and longitude columns with those names (output of GeoReference function)
gpsFile	GPS file of latitude and longitude columns with those names
bathyFile	Basemap file made from latitude, longitude and depth data, see ?bathymetry for format details
ExpFact	Expansion Factor- a multiplier of how smooth you want your new background graph to be. Larger numbers make it look smoother. Experiment with it.
minlat	minimum latitude of the data from the image.xyz file, MUST BE A WHOLE NUMBER
maxlat	maximum latitude of the data from the image.xyz file, MUST BE A WHOLE NUMBER
minlong	minimum longitude of the data from the image.xyz file, MUST BE A WHOLE NUMBER
maxlong	maximum longitude of the data from the image.xyz file, MUST BE A WHOLE NUMBER
Title	Title of your graph

## Details

See <http://www.gebco.net> do download the raw bathymetric data to create the bathyFile.

## Value

Given a bathymetric data file that is much larger than a given track, this function zooms the graph into where the data are and smooths out the background data if they are pixelated. The idea is to have a single bathymetry file to make many graphs for many animals no matter where they go so long as the tracks are all within the area of the bathymetry file limits. It creates a square graph that should adjust for the differences in actual distances between latitude and longitude graduals as latitude changes.

## Author(s)

Brian Battaile

## Examples

```
#A file from GeoRef function that has been thinned to data every 1 minute
data(georef1min26)
data(gpsdata26)
#See the vignette or ?bathymetry for information on how to get
#bathymetric data for your study area
data(bathymetry)
#This subset is just to save time creating the image.xyz
bathymetryBogs<-subset(bathymetry,Long<=(-168)& Long >=(-169)
& Lat<= 55 & Lat >=53,select=Long:Depth)
image.xyzBogs=tapply(bathymetryBogs$Depth, list(bathymetryBogs$Long, bathymetryBogs$Lat), unique)
Mapper(georef1min26, gpsdata26, image.xyzBogs, ExpFact = 500, minlat = 53,
maxlat = 55, minlong = -169, maxlong = -168, Title = "Fun Graph!!!")

## Not run:
#Plot the entire bathymetry file (this will take a minute or two)
image.xyz=tapply(bathymetry$Depth, list(bathymetry$Long, bathymetry$Lat), unique)
Bathymetry.palatte<-colorRampPalette(brewer.pal(9, "Blues"),bias=3)
#Plot the background map image
image.plot(image.xyz,
col=c(rev(Bathymetry.palatte(200)), terrain.colors(100)),#gray(0:20/20),
breaks=round(c(seq(from=min(image.xyz),to=0,length.out=201),seq(from=max(image.xyz)/101
,to=max(image.xyz),length.out=100)))
#,smallplot=2 #plots legend off x axis
)
#The next examples plot only the part of the background map that contains the relocation data
#Example 1
data(georef1min02)
data(gpsdata02)
Mapper(georef1min02, gpsdata02, image.xyz, ExpFact = 500, minlat = 51, maxlat = 60,
minlong = -177, maxlong = -163, Title = "Fun Graph!!!")

#Example 2
bathymetryBogs2<-subset(bathymetry,Long<=(-168)& Long >=(-169.2)
```

```

& Lat<= 54.3 & Lat >=53.1,select=Long:Depth)
image.xyzBogs2=tapply(bathymetryBogs2$Depth, list(bathymetryBogs2$Long, bathymetryBogs2$Lat),
unique)
image.plot(image.xyzBogs2,
col=c(rev(Bathymetry.palatte(200)),terrain.colors(100)),#gray(0:20/20),
breaks=round(c(seq(from=min(image.xyz),to=0,length.out=201),seq(from=max(image.xyz)/101
,to=max(image.xyz),length.out=100)))
#,smallplot=2 #plots legend off x axis
)
win.graph()
#Note the reduction in pixelation
data(georef1min95)
data(gpsdata95)
Mapper(georef1min95, gpsdata95, image.xyz, ExpFact = 500, minlat = 51, maxlat = 60,
minlong = -177, maxlong = -163, Title = "Fun Graph!!!")

## End(Not run)

```

---

rawdata

*Raw triaxial magnetometer and accelerometer data*


---

## Description

Raw data file from a northern fur seal with date, time, internal temp, depth, triaxial magnetometer, accelerometer, and wet/dry fields. This data set is bookended by the first 7 gps points in the gpsdata02 data set and is used in the examples for the DeadReckoning, GeoReference, GraphLimits, Splitter and GeoRef functions.

## Usage

```
data(rawdata)
```

## Format

A data frame with 133100 observations on the following 9 variables.

Date a character vector

Time a character vector

Depth a numeric vector

MagSurge a numeric vector

MagSway a numeric vector

MagHeave a numeric vector

AccSurge a numeric vector

AccSway a numeric vector

AccHeave a numeric vector

**Examples**

```
data(rawdata)
str(rawdata)
head(rawdata);tail(rawdata)
plot(rawdata$AccHeave)
```

---

rawdatagap

*Raw biologist data with a gap*

---

**Description**

Raw data file from a fur seal with a gap in the data file. Used as an example in the GapFinder function.

**Usage**

```
data(rawdatagap)
```

**Format**

A data frame with 13738 observations on the following 9 variables.

Date a character vector

Time a character vector

Depth a numeric vector

MagSurge a numeric vector

MagSway a numeric vector

MagHeave a numeric vector

AccSurge a numeric vector

AccSway a numeric vector

AccHeave a numeric vector

**Examples**

```
data(rawdatagap)
head(rawdatagap);tail(rawdatagap)
str(rawdatagap)
plot(rawdatagap$AccHeave)
```



**Value**

Creates a list of data frames in the format of the TagFile, but with a single DateTime column if the TagFiles had separate Date and Time columns.

**Author(s)**

Brian Battaile

**Examples**

```
#data set with 6 associated GPS fixes in the "gpsdata" data set
data(rawdata)
data(gpsdata02)
Begin=gpsdata02$DateTime[2:6]
End=gpsdata02$DateTime[3:7]
splits<-Splitter(rawdata,Begin,End,RmL=2,HZ=16)
## Not run:
#The following is code to write your many new files
setwd() #first fill in the path to the folder where you want the data to be written to
for(i in 1:length(splits))
{
  num<-i
  num=ifelse(num<10 & length(Begin)>10,paste("0",num,sep=""),num)
  num=ifelse(num<100 & length(Begin)>100,paste("0",num,sep=""),num)
  num=ifelse(num<1000 & length(Begin)>1000,paste("0",num,sep=""),num)
  num=ifelse(num<10000 & length(Begin)>10000,paste("0",num,sep=""),num)
  #Create a name for the file
  Nombre<-paste("Animal01Trip03GPS_Section",num,".txt",sep="")
  write.table(splits[[i]],Nombre,sep="\t",row.names=FALSE,quote=FALSE)
}

## End(Not run)
```

---

square

*Raw triaxial magnetometer and accelerometer data*

---

**Description**

Fabricated data file 100 observations long to make a square. Useful for exercises to understand how the DeadReckoning algorithm works.

**Usage**

```
data(rawdata)
```

**Format**

A data frame with 100 observations on the following 10 variables.

Date a character vector

Time a character vector

Depth a numeric vector

MagSurge a numeric vector

MagSway a numeric vector

MagHeave a numeric vector

AccSurge a numeric vector

AccSway a numeric vector

AccHeave a numeric vector

Speed a numeric vector

**Examples**

```
data(square)
str(square)
head(square);tail(square)
```

---

Standardize

*Standardize accelerometer and magnetometer data*

---

**Description**

Calculates intercept and slope values with a linear model to standardize accelerometer and magnetometer data to values between -1 and +1.

**Usage**

```
Standardize(MagOrSR, MagOrHV, MagOrSW, AccOrSR, AccOrHV, AccOrSW, magSRmin,
magSRmax, magHVmin, magHVmax, magSWmin, magSWmax, accSRmin, accSRmax, accHVmin,
accHVmax, accSWmin, accSWmax)
```

**Arguments**

MagOrSR	Surge Magnetometer Orientation -1 or 1
MagOrHV	Heave Magnetometer Orientation -1 or 1
MagOrSW	Sway Magnetometer Orientation -1 or 1
AccOrSR	Surge Accelerometer Orientation -1 or 1
AccOrHV	Heave Accelerometer Orientation -1 or 1
AccOrSW	Sway Accelerometer Orientation -1 or 1
magSRmin	Surge Magnetometer minimum

magSRmax	Surge Magnetometer maximum
magHVmin	Heave Magnetometer minimum
magHVmax	Heave Magnetometer maximum
magSWmin	Sway Magnetometer minimum
magSWmax	Sway Magnetometer maximum
accSRmin	Surge Accelerometer minimum
accSRmax	Surge Accelerometer maximum
accHVmin	Heave Accelerometer minimum
accHVmax	Heave Accelerometer maximum
accSWmin	Sway Accelerometer minimum
accSWmax	Sway Accelerometer maximum

### Details

Standardization/Calibration/normalization/relativizing of accelerometer and magnetometer data. The right-hand-rule indicates the orientation (polarity) of the magnetometers and accelerometers required for the pseudotrack reconstruction algorithm, so that when the front, top or left side of the tag is facing the earth, the accelerometers are at the maximal reading (+1) when the tag is not moving. A similar rule applies for the magnetometers except the maximal reading for each axis will be when the front, top or left side is facing north and at the angle of inclination of the magnetic field (the angle at which the magnetic field enters the earth) at that location on the planet. If the tag sensors conform to this rule all the orientation parameters should be 1, any sensors that are opposite to this should have -1 as an orientation value. Instead of labeling the tag in X,Y and Z dimensions, the directions are labeled as Surge, Heave and Sway where Surge indicates the front (anterior) to back (posterior) axis, the Heave is the top (dorsal) to bottom (ventral) axis and the Sway is the right to left (lateral) axis.

### Value

Returns a [2,6] matrix with intercept in the first row and slope in the second row and columns in the order of the orientation parameter input. Row names are c("B0 Intercept","B1 Slope") and column names are c("MagSurge","MagHeave","MagSway","AccSurge","AccHeave","AccSway").

### Author(s)

Brian Battaile

### Examples

```
betas<-Standardize(1,1,-1,1,1,1,-57.8,68.76,-61.8,64.2,-70.16,58.08,-10.1,9.55,-9.75,9.72,
-9.91,9.43)
betas
```



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