Package 'ROI.plugin.lpsolve'

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Title 'lp_solve' Plugin for the 'R' Optimization Infrastructure
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Description Enhances the 'R' Optimization Infrastructure ('ROI') package with the 'lp_solve' solver.
Imports stats, methods, utils, ROI (>= 0.3-0), lpSolveAPI (>= 5.5.2.0-1)
Suggests slam
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control

Control Variables

Description

The control variables are all optional, but can in some cases be used to improve the solving time and the solutions.

Arguments

basis an optional named list used to set the initial basis of the LP, e.g., R> control <-list(basis=list(basis = c(1,2,3), + nonbasic = TRUE, default = TRUE)). The elements of basis are passed to the **lpSolveAPI** function set.basis as arguments. • basis a numeric vector giving the indices of the basis. • nonbasic an optional logical, if TRUE the nonbasic variables included in the • default an optional logical, if TRUE the default basis is used and the arguments basis and nonbasic are ignored. branch.mode an optional list used to set the branch and bound mode, e.g., R> control <-list(branch.mode=list(columns=c(1,2,3), + modes=c("ceiling", "auto", "floor")) The elements of branch.mode are passed to **lpSolveAPI** function set.branch.mode as arguments. • columns a vector of integer giving the column indices for which the mode • modes a character vector giving the modes of the columns specified in columns. branch.weights an optional numeric vector giving the weights for the decision variables. The length of the branch. weights must be equal to length of the objective function. a character string (for more information see lp.control). verbose anti.degen a character vector (for more information see lp.control). basis.crash a character string (for more information see lp.control). bb.depthlimit a integer giving the maximum branch-and-bound depth (for more information see lp.control). bb.floorfirst a character string (for more information see lp.control). bb.rule a character vector giving the branch-and-bound rule (for more information see lp.control). break.at.first a logical controlling whether the branch-and-bound algorithm should be stopped at the first solution or the branch-and-bound algorithm continuous until an optimal solution is found (for more information see lp.control). break.at.value a numeric, if given the branch-and-bound algorithm stops when the objective

function becomes smaller than the specified value. (for more information see

lp.control).

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```
a character string giving the type of thresholds (for more information see lp.control).
epslevel
                  a numeric giving the tolerance for the right-hand-side (for more information see
epsb
                  lp.control).
epsd
                  a numeric (for more information see lp.control).
epsel
                  a numeric (for more information see lp.control).
epsint
                  a numeric (for more information see lp.control).
                  a numeric (for more information see lp.control).
epsperturb
                  a numeric (for more information see lp.control).
epspivot
improve
                  a character vector (for more information see lp.control).
infinite
                  a numeric (for more information see lp.control).
maxpivot
                  a integer (for more information see lp. control).
                  a numeric vector (for more information see lp.control).
mip.gap
negrange
                  a numeric (for more information see lp.control).
obj.in.bas
                  a logical (for more information see lp.control).
                  a character vector (for more information see lp.control).
pivoting
                  a character vector (for more information see lp.control).
presolve
                  a numeric (for more information see lp.control).
scalelimit
                  a character vector (for more information see lp.control).
scaling
simplextype
                  a character vector which an take one of the following values c("primal"),
                  c("dual"), c("primal", "dual") or c("dual", "primal") (for more infor-
                  mation see lp.control).
timeout
                  a integer giving the number of seconds till a timeout occurs (for more informa-
                  tion see lp. control).
```

|--|

Description

maximize
$$2x_1 + 4x_2 + 3x_3$$

subject to:
 $3x_1 + 4x_2 + 2x_3 \le 60$
 $2x_1 + x_2 + 2x_3 \le 40$
 $x_1 + 3x_2 + 2x_3 \le 80$
 $x_1, x_2, x_3 \ge 0$

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Examples

read.lp

Read Optimization Problem

Description

Read a optimization problem from a file.

Usage

```
read.lp(file, type=c("lp", "mps", "freemps"))
```

Arguments

file a character giving the name of the file the optimization problem is read from.

type a character giving the name of the file format the optimization problem is stored in.

Details

The optimization problems can be read from the three file formats "lp", "mps" and "freemps". Where it seems important to note that the "lp" format refers to lpsolves native file format (http://lpsolve.sourceforge.net/5.5/lp-format.htm) and not to the CPLEX LP format.

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Examples

```
## Not run:
op <- read.lp("optimization_problem.lp")
sol <- ROI_solve(op)
solution(sol)
## End(Not run)</pre>
```

write.lp

Write Optimization Problem

Description

Write a optimization problem to a file.

Usage

```
write.lp(x, file, type=c("lp", "mps", "freemps"))
```

Arguments

x an object of type OP.

file a character giving the name of the file the optimization problem is written to.

type a character giving the name of the file format used to store the optimization

problem.

Details

The optimization problems can be written to the three file formats "lp", "mps" and "freemps". Where it seems important to note that the "lp" format refers to lpsolves native file format (http://lpsolve.sourceforge.net/5.5/lp-format.htm) and not to the CPLEX LP format.

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