Package 'FLightR'

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Type Package

Title Reconstruct Animal Paths from Solar Geolocation Loggers Data

Version 0.5.0 **Date** 2020-05-11

Description Spatio-temporal locations of an animal are computed from annotated data with a hidden Markov model via particle filter algorithm. The package is relatively robust to varying degrees of shading.

The hidden Markov model is described in Movement Ecology (Rakhimberdiev et al., 2015) <doi:10.1186/s40462-015-0062-5>, general package description is in the Methods in Ecology and Evolution (Rakhimberdiev et al., 2017) <doi:10.1111/2041-210X.12765> and package accuracy assessed in the Journal of Avian Biology (Rakhimberdiev et al. 2016) <doi:10.1111/jav.00891>.

URL https://CRAN.R-project.org/package=FLightR

BugReports http://github.com/eldarrak/FLightR/issues

Depends R (>= 3.0.2)

Imports bit, ggsn, ggmap, ggplot2, CircStats, circular, GeoLight, fields, maptools, methods, mgcv, nlme, parallel, raster, RcppArmadillo, rgdal, rgeos, sp, truncnorm

License GPL-3

ByteCompile true

RoxygenNote 7.1.0

Suggests covr, testthat, knitr, rmarkdown

VignetteBuilder knitr

NeedsCompilation no

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R topics documented:

Description

this function converts combines twilights detected in BAStag with raw data and writes them down in TAGS format that can be easily read by get.tags.data

Usage

```
BAStag2TAGS(raw, twl, threshold, filename = NULL)
```

Arguments

raw	original data - dataframe with two columns first column must contain time and second measured light levels
twl	twilights object from preprocess.light function
threshold	threshold value used for twilight definition in preprocess.light

find.stationary.location 3

filename

if NULL data.frame in TAGS format will be returned otherwise .csv file in TAGS format will be written

Details

TAGS format returned or written as .csv by this function is a dataframe with columns

- datetime date and time in ISO 8601 format e.g. 2013-06-16T00:00:11.000Z
- light light value measured by tag
- twilight assigned by the software numeric indication of whether the record belongs to sunrise (1), sunset (2) or none of those (0)
- excluded indication of whether a twilight was excluded during manual inspection (logical, TRUE | FALSE)
- interp indication of whether the light value at twilight was interpolated (logical, TRUE | FALSE)

The fields excluded and interp may have values of TRUE only for twilight > 0.

Value

NULL if filename is provided or TAGS formatted dataframe.

Author(s)

Eldar Rakhimberdiev & Simeon Lisovski

See Also

```
twGeos2TAGS and GeoLight2TAGS
```

```
find.stationary.location
```

find unknown calibration location

Description

Functions attempts to find a location where The function attempts to find a location for a time period assuming animal was not moving. Does not work well will shaded data!

Usage

```
find.stationary.location(
   Proc.data,
   calibration.start,
   calibration.stop,
   plot = TRUE,
   initial.coords = NULL,
   print.optimization = TRUE,
   reltol = 1e-04
)
```

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Arguments

```
Proc.data
                  processed data object generated by get.tags.data
calibration.start
                  POSIXct time when stationary period started
calibration.stop
                  POSIXct time when stationary period ended
plot
                  plots every iteration
initial.coords location vector with initial values for location (longitude and latitude). Should
                  be close (+-2000 km from the real location)
print.optimization
                  do you want every optimization iteration to be printed? If TRUE - Lon, Lat,
                  calibration mean and calibration sd are being printed. Optimization tries to min-
                  imize the latter.
reltol
                  tolerance for optimization, see optim for more details
```

Details

The idea behind the function is that it tries to minimize variance between slopes for the whole period by optimizing location. It can be seen as an extension of Hill-Ekstrom calibration idea.

Author(s)

Eldar Rakhimberdiev

Examples

```
#this example takes about 15 minutes to run
## Not run:
File<-system.file("extdata", "Godwit_TAGS_format.csv", package = "FLightR")
Proc.data<-get.tags.data(File)
plot_slopes_by_location(Proc.data=Proc.data, location=c(5.43, 52.93))
abline(v=as.POSIXct("2013-08-20")) # end of first calibration period
abline(v=as.POSIXct("2014-05-05")) # start of the second calibration period
Location<-find.stationary.location(Proc.data, '2013-07-20', '2013-08-20', initial.coords=c(10, 50))
## End(Not run)</pre>
```

find.times.distribution

extracts times of arrival and departure to/from spatial extent

Description

Idea of this functions is to extract schedules for known location

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Usage

```
find.times.distribution(Result, Spatial.Index)
```

Arguments

Result FLightR result object obtained from run.particle.filter

Spatial.Index Row numbers for spatial grid (Result\$Spatial\$Grid) to estimate schedules

for.

Value

dataframe with columns for 0.025, 0.25, 0.5, 0.75, 0.975 probability of line crossing and rows for every crossing.

Author(s)

Eldar Rakhimberdiev

FLightR2Movebank Summary of estimated locations for Movebank

Description

Summarize result object in the format required for upload to Movebank

Usage

```
FLightR2Movebank(Result, alpha = 0.5, filename = NULL)
```

Arguments

Result FLightR result object obtained from run.particle.filter

alpha coverage of the credible intervals for now only two options: 0.95 or 0.5.

filename if NULL data.frame in TAGS format will be returned otherwise .csv file in TAGS

format will be written

Details

This function accepts FLightR results object.

Value

NULL if filename is provided or Movebank formatted dataframe.

Author(s)

GeoLight2TAGS

GeoLight2TAGS	Function to write down twilights annotated in GeoLight package data in so-called TAGS format
OCOLIGITEZ FACO	0 0 1 0

Description

this function converts combines twilights detected in BAStag to twGeos with raw data and writes them down in TAGS format that can be easily read by get.tags.data

Usage

```
GeoLight2TAGS(raw, gl_twl, threshold, filename = NULL)
```

Arguments

raw	original data - dataframe with two columns first column must contain time and second measured light levels
gl_twl	twilights object from GeoLight
threshold	threshold value used for twilight definition in GeoLight
filename	if NULL data.frame in TAGS format will be returned otherwise .csv file in TAGS format will be written

Details

TAGS format returned or written as .csv by this function is a dataframe with columns

- datetime date and time in ISO 8601 format e.g. 2013-06-16T00:00:11.000Z
- light light value measured by tag
- twilight assigned by the software numeric indication of whether the record belongs to sunrise (1), sunset (2) or none of those (0)
- excluded indication of whether a twilight was excluded during manual inspection (logical, TRUE | FALSE)
- interp indication of whether the light value at twilight was interpolated (logical, TRUE | FALSE)

The fields excluded and interp may have values of TRUE only for twilight > 0.

Value

NULL if filename is provided or TAGS formatted dataframe.

Author(s)

Eldar Rakhimberdiev & Simeon Lisovski

See Also

 $tw Geos 2 TAGS \ and \ BAStag 2 TAGS$

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get.tags.data

read TAGS formatted data

Description

Reads the data frame with detected twilight events into the FLightR

Usage

```
get.tags.data(
   filename = NULL,
   start.date = NULL,
   end.date = NULL,
   log.light.borders = "auto",
   log.irrad.borders = "auto",
   saves = c("auto", "max", "mean"),
   measurement.period = NULL,
   impute.on.boundaries = FALSE
)
```

Arguments

filename

the name of the file which the data are to be read from. File is supposed to be comma separated file of TAGS format. If it does not contain an absolute path, the file name is relative to the current working directory, getwd(). Tilde-expansion is performed where supported. This can be a compressed file (see file). Alternatively, file can be a readable text-mode connection (which will be opened for reading if necessary, and if so closed (and hence destroyed) at the end of the function call). File can also be a complete URL. For the supported URL schemes, see help for url.

start.date

date of beginning of relevant data collection in POSIXct format.

end.date

date of end of relevant data collection in POSIXct format.

log.light.borders

Numeric vector with length of 2 for minimum and maximum log(light) levels to use. Alternatively character value 'auto', that will allow FLightR to assign these values according to detected tag type.

log.irrad.borders

Numeric vector with length of 2 for minimum and maximum log(irradiance) values to use. Alternatively character value 'auto', that will allow FLightR to assign these values according to detected tag type.

saves

character values informing FLightR if min or max values were used by logger.

measurement.period

Value in seconds defining how often tag was measuring light levels. If NULL value will be taken from known values for detected tag type.

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```
impute.on.boundaries
```

logical, if FLightR should approximate values at boundaries. Set it to TRUE only if you have vary few active points at each twilight, e.g if tag was saving every 10 minutes or so.

Details

The returned object has many parts, the important are: (1) the recorded light data, (2) the detected twilight events, (3) light level data at the moment of each determined sunrise and sunset and around them (24 fixes before and 24 after), and (4) technical parameters of the tag, i. e. its type, saving and measuring period (the periodicity, in seconds, at which a tag measures and saves data).

Value

list, which is to be further processed with the FLightR.

Examples

```
File<-system.file("extdata", "Godwit_TAGS_format.csv", package = "FLightR")
Proc.data<-get.tags.data(File)</pre>
```

get_ZI_distances

Estimate distances moved between twilights

Description

This function estimate distances with all zeros from stationary periods. This means many of the resulting movements will have 0 as the distance

Usage

```
get_ZI_distances(Result)
```

Arguments

Result

An object created by run.particle.filter.

Value

a data frame containing median and quartiles for the distances and also departure and arrival time

Author(s)

make.calibration 9

make.calibration	Creates a calibration object, further used for calculation of coordi-
	nates in the run.particle.filter.

Description

Function estimates all necessary parameters from the calibration data logged in a known location or locations.

Usage

```
make.calibration(
  Proc.data,
  Calibration.periods,
 model.ageing = FALSE,
 plot.each = FALSE,
  plot.final = FALSE,
  likelihood.correction = "auto",
  fixed.logSlope = c(NA, NA),
  suggest.irrad.borders = FALSE,
  return.slopes = FALSE
)
```

Arguments

Proc.data processed data object generated by get.tags.data

Calibration.periods

a data frame containing start and end dates of all the calibration periods (POSIXct) and geographic coordinates of the corresponding calibration locations.

model.ageing

if set to TRUE, accounts for the tag ageing (with opacification of its transparent shell of a light sensor), resulting into decreasing sensitivity of the device. This option is useful only if there were several calibration periods or if calibration period was very long (~ longer than a month).

plot.each

Do you want every twilight to be plotted while processing

plot.final

Do you want final calibration graph to be plotted. On the graph you can see all the observed versus expected light levels. All slopes should be similar.

likelihood.correction

will estimate correction of likelihood for the current calibration parameters. Highly recommended not to be change from 'auto'. In this case FLightR will switch it to FALSE in case tag saved dat on 10 minutes or longer period.

fixed.logSlope these are mean (1) and SD (2) for distribution of slopes. Should normally be estimated from the data (and thus default is c(NA, NA)). Change any of these two finite values if you want them to be predetermined and not estimated from the calibration data.

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```
suggest.irrad.borders
```

experimental parameter! If set to TRUE function will try to find the best values for the log.irrad.borders

return.slopes if true function will return estimated individual twilight slopes.

Author(s)

Eldar Rakhimberdiev

Examples

make.grid

makes spatial grid

Description

This function makes a rectangular grid with use defined boundaries and probabilities of being stationary.

Usage

```
make.grid(
  left = -180,
  bottom = -90,
  right = 180,
  top = 90,
  distance.from.land.allowed.to.use = c(-Inf, Inf),
  distance.from.land.allowed.to.stay = c(-Inf, Inf),
  plot = TRUE,
  return.distances = FALSE,
  probability.of.staying = 0.5
)
```

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- left boundary in degrees (-180 <= left <= 180)

Arguments

left

```
bottom
                  - lower boundary in degrees (-90 <= bottom <= 90)
right
                  - right boundary in degrees (-180 <= right <= 180)
                  - top boundary in degrees (-90 \le \text{right} \le 90)
top
distance.from.land.allowed.to.use
                  - define how far from the shore animal could occur. Unit - km, negative values
                  are for inland and positive for offshore directions. Inf stays for infinity
distance.from.land.allowed.to.stay
                  - define how far from the shore animal could stay stationary between twilights.
                  Unit - km, negative values are for inland and positive for offshore directions.
                   Inf stays for infinity
plot
                   show a plot of final grid.
return.distances
                  - return distances to the shoreline
probability.of.staying
                   - assigned probability value for grid cells that do not satisfy distance.from.water.allowed.to.stay
```

Value

dataframe with coordinates(lon and lat) and probability.of.staying

Author(s)

Eldar Rakhimberdiev

Examples

```
Grid<-make.grid(left=-14, bottom=30, right=13, top=57,
  distance.from.land.allowed.to.use=c(-Inf, Inf),
  distance.from.land.allowed.to.stay=c(-Inf, Inf))</pre>
```

make.prerun.object

combines data, calibration and sets up priors

Description

This function is one step before run.particle.filter. It combines data, calibration, spatial extent and movement priors and estimates spatial likelihoods that used later in the particle filter.

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Usage

```
make.prerun.object(
  Proc.data,
  Grid,
  start,
  end = start,
  Calibration,
  threads = -1,
  Decision = 0.05,
  Direction = 0,
  Kappa = 0,
  M.mean = 300,
  M.sd = 500,
  likelihood.correction = TRUE
)
```

Arguments

Proc.data	Processed data object created by get. tags. data.
Grid	Spatial grid created by make.grid.

start release location (lat, lon).

end end of the track location. Will use start by default. Use NA in case of unknown

end point.

Calibration Calibration object created by make.calibration.

threads number of parallel threads to use. default is -1, which means FLightR will use

all available threads except 1. Value 1 will force sequential evaluation

Decision prior for migration probability values from 0 to 1 are allowed

Direction Direction prior for direction of migration (in degrees) with 0 pointing to the

North

Kappa concentration parameter for vonMises distribution, 0 means uniform or even

distribution. Will set some prior for direction for all the track, so is not recom-

mended to be changed

M. mean Prior for mean distance travelled between consecutive twilights, km

M.sd Prior for sd of distance travelled between consecutive twilights, the higher the

value is the wider is the distribution

likelihood.correction

Should likelihood correction estimated during make.calibration run be used?

Value

Object to be uses in the run.particle.filter

Author(s)

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Examples

```
File<-system.file("extdata", "Godwit_TAGS_format.csv", package = "FLightR")
# to run example fast we will cut the real data file by 2013 Aug 20
Proc.data<-get.tags.data(File, end.date=as.POSIXct('2013-07-02', tz='GMT'))
Calibration.periods<-data.frame(</pre>
       calibration.start=NA,
       calibration.stop=as.POSIXct("2013-08-20"),
       lon=5.43, lat=52.93)
    #use c() also for the geographic coordinates, if you have more than one calibration location
       # (e. g., lon=c(5.43, 6.00), lat=c(52.93,52.94))
print(Calibration.periods)
# NB Below likelihood.correction is set to FALSE for fast run!
# Leave it as default TRUE for real examples
Calibration<-make.calibration(Proc.data, Calibration.periods, likelihood.correction=FALSE)
Grid<-make.grid(left=0, bottom=50, right=10, top=56,
  distance.from.land.allowed.to.use=c(-Inf, Inf),
  distance.from.land.allowed.to.stay=c(-Inf, Inf))
all.in<-make.prerun.object(Proc.data, Grid, start=c(5.43, 52.93),
                             Calibration=Calibration, threads=2)
```

map.FLightR.ggmap

plots result over map

Description

plots track over map with probability cloud. Can plot only part of the track if dates are specified. Note that you can use it only after obtaining and registering in you current session Google Api Key. For details on the API key check [here](http://ornithologyexchange.org/forums/topic/38315-mapflightrggmap-error).

Usage

```
map.FLightR.ggmap(
  Result,
  dates = NULL,
  plot.cloud = TRUE,
  map.options = NULL,
  plot.options = NULL,
  save.options = NULL,
  zoom = "auto",
  return.ggobj = FALSE,
  seasonal.colors = TRUE,
  seasonal.donut.location = "topleft",
  seasonal.donut.proportion = 0.5,
```

```
save = TRUE
)
```

Arguments

Result FLightR result object obtained from run.particle.filter dates either NULL if all twilights should be included or data.frame with first column - start of the period and second end of the period. Each line represents a new period plot.cloud Should probability cloud be plotted? If TRUE cloud is estimated by stat_density2d map.options options passed to get_map, note that zoom option is defined separately plotting options. Not defined yet! plot.options save.options options passed to ggsave. Filename should be defined here. zoom Zoom for map. If 'auto' FLightR will try to find optimal zoom level by downloading different size maps and checking whether all the points fit the map. Should ggobj be returned for subsequent checks and/or replotting return.ggobj seasonal.colors if true points of the track will have seasonal colors seasonal.donut.location if NULL - no color wheel placed, otherwise select one of 'bottomleft', 'bottomright', 'topleft' seasonal.donut.proportion how much of X axis should color wheel occupy. return either NULL or ggplot2 class object save should function save results with ggsave?

Author(s)

Eldar Rakhimberdiev

Examples

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plot_likelihood

plot likelihood surface over map

Description

plots specific likelihood surface over map

Usage

```
plot_likelihood(object, date = NULL, twilight.index = NULL)
```

Arguments

object either output from make.prerun.object or run.particle.filter

date either NULL or a date (possibly with time) closest to the twilight you wan to be

plotted

twilight.index number of likelihood surface to be plotted

Details

function plots likelihoods before particle filter run, so these are pure results of calibrations without any movement model

Author(s)

plot_lon_lat

Examples

```
File<-system.file("extdata", "Godwit_TAGS_format.csv", package = "FLightR")
# to run example fast we will cut the real data file by 2013 Aug 20
Proc.data<-get.tags.data(File, end.date=as.POSIXct('2013-07-02', tz='GMT'))</pre>
Calibration.periods<-data.frame(</pre>
       calibration.start=as.POSIXct(c(NA, "2014-05-05")),
       calibration.stop=as.POSIXct(c("2013-08-20", NA)),
       lon=5.43, lat=52.93)
     #use c() also for the geographic coordinates, if you have more than one calibration location
       # (e. g., lon=c(5.43, 6.00), lat=c(52.93,52.94))
# NB Below likelihood.correction is set to FALSE for fast run!
# Leave it as default TRUE for real examples
Calibration<-make.calibration(Proc.data, Calibration.periods, likelihood.correction=FALSE)
Grid<-make.grid(left=0, bottom=50, right=10, top=56,</pre>
  distance.from.land.allowed.to.use=c(-Inf, Inf),
  distance.from.land.allowed.to.stay=c(-Inf, Inf))
all.in<-make.prerun.object(Proc.data, Grid, start=c(5.43, 52.93),
                             Calibration=Calibration, threads=2)
plot_likelihood(all.in, twilight.index=10)
```

plot_lon_lat

plots result by longitude and latitude

Description

This function plots result by latitude and longitude in either vertical or horizontal layout.

Usage

```
plot_lon_lat(Result, scheme = c("vertical", "horizontal"))
```

Arguments

Result FLightR result object obtained from run.particle.filter

scheme either 'vertical' or 'horizontal' layouts return NULL

Author(s)

Examples

```
File<-system.file("extdata", "Godwit_TAGS_format.csv", package = "FLightR")</pre>
# to run example fast we will cut the real data file by 2013 Aug 20
Proc.data<-get.tags.data(File, end.date=as.POSIXct('2013-07-02', tz='GMT'))
Calibration.periods<-data.frame(</pre>
       calibration.start=as.POSIXct(c(NA, "2014-05-05")),
       calibration.stop=as.POSIXct(c("2013-08-20", NA)),
       lon=5.43, lat=52.93)
    #use c() also for the geographic coordinates, if you have more than one calibration location
       # (e. g., lon=c(5.43, 6.00), lat=c(52.93,52.94))
# NB Below likelihood.correction is set to FALSE for fast run!
# Leave it as default TRUE for real examples
Calibration<-make.calibration(Proc.data, Calibration.periods, likelihood.correction=FALSE)
Grid<-make.grid(left=0, bottom=50, right=10, top=56,
  distance.from.land.allowed.to.use=c(-Inf, Inf),
  distance.from.land.allowed.to.stay=c(-Inf, Inf))
all.in<-make.prerun.object(Proc.data, Grid, start=c(5.43, 52.93),
                             Calibration=Calibration, threads=2)
# here we will run only 1e4 partilces for a very short track.
# One should use 1e6 particles for the full run
Result<-run.particle.filter(all.in, threads=1,
           nParticles=1e3, known.last=TRUE,
           precision.sd=25, check.outliers=FALSE)
plot_lon_lat(Result)
```

```
plot_slopes_by_location
```

plots log of observed versus expected slope by time for a known location

Description

The function calculates and plots calibration slopes for sunsets and sunrises for every day of the tracking period, based on the assumption that the tag remained in the same (calibration) location all the time.

Usage

```
plot_slopes_by_location(
  Proc.data,
  location,
  log.light.borders = "auto",
  log.irrad.borders = "auto",
  ylim = NULL,
```

```
xlim = NULL
)
```

Arguments

Proc.data processed data object generated by get.tags.data

location vector with longitude and latitude of calibration location (degrees).

log.light.borders

numeric vector with length of 2 for minimum and maximum log(light) levels to use. Default value 'auto', will take these values from the Proc.data object.

log.irrad.borders

numeric vector with length of 2 for minimum and maximum log(irradiance) values to use. Default value 'auto', will take these values from the Proc.data

object.

ylim the y limits of the plot. The default value, NULL, indicates that the range of the

finite values to be plotted should be used.

x1im the x limits of the plot. The default value, NULL, otherwise can be POSIXct or

character in a form readable by as.POSIXct.

Details

The plot of calibration slopes is used for finding start and end dates of a calibration period (the time period, during which the tag remained in the calibration location with coordinates (x,y)). During the calibration period, the calibration slopes vary little both, between the twilight events (sunrises and sunsets) and in time. When the tag changes location, the slopes for sunrises and sunsets start to deviate. There may potentially be several calibration periods for the same location (if the bird returned to the same location several times). The boundaries (start and end dates) of each of these periods are captured visually. If there were more than one calibration location, the procedure is repeated, once for each location. All the obtained calibration periods can be entered in a data frame 'Calibration.periods', for further analysis. Each line of the data frame contains start and end dates (if applicable) of the calibration period and geographic coordinates of the location.

Author(s)

Eldar Rakhimberdiev

Examples

```
File<-system.file("extdata", "Godwit_TAGS_format.csv", package = "FLightR")
Proc.data<-get.tags.data(File)
plot_slopes_by_location(Proc.data=Proc.data, location=c(5.43, 52.93))
abline(v=as.POSIXct("2013-08-20")) # end of first calibration period
abline(v=as.POSIXct("2014-05-05")) # start of the second calibration period</pre>
```

plot_util_distr 19

plot_util_distr	plots resulting track over map with uncertainty shown by space utili- sation distribution

Description

May be use not only for the whole track but for a set of specific dates, e.g. to show spatial uncertainty during migration. Note that you can use it only after obtaining and registering in you current session Google Api Key. For details on the API key check [here](http://ornithologyexchange.org/forums/topic/38315-mapflightrggmap-error).

Usage

```
plot_util_distr(
  Result,
  dates = NULL,
 map.options = NULL,
  percentiles = c(0.4, 0.6, 0.8),
  zoom = "auto",
  geom_polygon.options = NULL,
  save.options = NULL,
  color.palette = NULL,
  use.palette = TRUE,
  background = NULL,
  plot = TRUE,
  save = TRUE,
  add.scale.bar = FALSE,
  scalebar.options = NULL
)
```

Arguments

Result	FLightR result object obtained from run.particle.filter	
dates	Use NULL if all twilights will be used for plotting, one integer if specific twilight should be plotted (line number in Result\$Results\$Quantiles). Use data.frame with first column - start of the period and second - end of the period and each line represents a new period to plot specific periods, e.g. wintering or migration.	
map.options	options passed to get_map, note that zoom option is defined separately	
percentiles	Probability breaks for utilisation distribution	
ZOOM	Zoom for map. If 'auto' FLightR will try to find optimal zoom level by downloading different size maps and checking whether all the points fit the map.	
<pre>geom_polygon.options</pre>		
	options passed to geom_polygon	
save.options	options passed to ggsave. Filename should be defined here.	
color.palette	colors for probability contours. Either NULL or colorRampPalette object	

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```
should the same colors be used for polygon boundaries as for polygon filling?

background if provided will be used as a background. Must be created by link[ggmap]{get_map}

plot should function produce a plot?

save should function save results with ggsave?

add.scale.bar will add scalebar with the scalebar

scalebar.options

options passed to scalebar
```

Value

list with two parts

res_buffers spatial buffers for defined probability values

ggplot object

Author(s)

Eldar Rakhimberdiev

Examples

```
File<-system.file("extdata", "Godwit_TAGS_format.csv", package = "FLightR")</pre>
# to run example fast we will cut the real data file by 2013 Aug 20
Proc.data<-get.tags.data(File, end.date=as.POSIXct('2013-06-25', tz='GMT'))
Calibration.periods<-data.frame(</pre>
       calibration.start=as.POSIXct(c(NA, "2014-05-05")),
       calibration.stop=as.POSIXct(c("2013-08-20", NA)),
       lon=5.43, lat=52.93)
    #use c() also for the geographic coordinates, if you have more than one calibration location
       # (e. g., lon=c(5.43, 6.00), lat=c(52.93,52.94))
# NB Below likelihood.correction is set to FALSE for fast run!
# Leave it as default TRUE for real examples
Calibration<-make.calibration(Proc.data, Calibration.periods, likelihood.correction=FALSE)
Grid<-make.grid(left=0, bottom=50, right=10, top=56,
 distance.from.land.allowed.to.use=c(-Inf, Inf),
 distance.from.land.allowed.to.stay=c(-Inf, Inf))
all.in<-make.prerun.object(Proc.data, Grid, start=c(5.43, 52.93),
                             Calibration=Calibration, threads=1)
# here we will run only 1e4 partilces for a very short track.
# One should use 1e6 particles for the full run
Result<-run.particle.filter(all.in, threads=1,
           nParticles=1e3, known.last=TRUE,
           precision.sd=25, check.outliers=FALSE)
## Not run:
plot_util_distr(Result, zoom=6, save=FALSE)
```

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```
## End(Not run)
```

Description

Main function of FLightR, it takes fully prepared object created by make.prerun.object and produces a result object that can be used for plotting etc.

Usage

```
run.particle.filter(
  all.out,
  cpus = NULL,
  threads = -1,
 nParticles = 1e+06,
 known.last = TRUE,
 precision.sd = 25,
 behav.mask.low.value = 0,
 k = NA,
 plot = TRUE,
 cluster.type = "PSOCK",
 a = 45,
 b = 1500,
 L = 90,
 adaptive.resampling = 0.99,
 check.outliers = FALSE,
 sink2file = FALSE,
 add.jitter = FALSE
)
```

Arguments

all.out	An object created by make.prerun.object.
cpus	another way to specify threads
threads	An amount of threads to use while running in parallel. default is -1. if value 1 submitted package will run sequentially
nParticles	total amount of particles to be used with the run. 10 000 (1e4) is recommended for the preliminary run and 1 000 000 (1e6) for the final
known.last	Set to FALSE if your bird was not at a known place during last twilight in the data
precision.sd	if known.last then what is the precision of this information. Will be used to resample particles proportionally to their distance from the known last point with probability $P = dnorm(0,precision.sd)$

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behav.mask.low.value

Probability value that will be used instead of 0 in the behavioural mask. If set to

1 behavioural mask will not be active anymore

k Kappa parameter from vonMises distribution. Default is NA, otherwise will

generate particles in a direction of a previous transitions with kappa = k

plot Should function plot preliminary map in the end of the run?

cluster.type see help to package parallel for details

a minimum distance that is used in the movement model - left boundary for trun-

cated normal distribution of distances moved between twilights. Default is 45

for as default grid has a minimum distance of 50 km.

b Maximum distance allowed to fly between two consecutive twilights

L how many consecutive particles to resample

adaptive.resampling

Above what level of ESS resampling should be skipped

check.outliers switches ON the online outlier routine

sink2file will write run details in a file instead of showing on the screen add.jitter will add spatial jitter inside a grid cell for the median estimates

Value

FLightR object, containing output and extracted results. It is a list with the following elements

Indices List with prior information and indices

Spatial Spatial data - Grid, Mask, spatial likelihood

Calibration all calibration parameters

Data original data

Results The main results object. Main components of it are

Quantiles dataframe containing results on locations. Each line corresponds to

a twilight

Movement.results dataframe containing all the movement results, Note - time

at line n means time of the end of transition between n and n-1

outliers id of twilights excluded by online outlier detection tool

LL -Log likelihood

Points.rle run length encoding object with posterior distribution for every twilight. Note that numbers of points correspond to line numbers in \$Spatial\$Grid

Transitions.rle run length encoding object with all the transitions

Author(s)

Examples

```
File<-system.file("extdata", "Godwit_TAGS_format.csv", package = "FLightR")
# to run example fast we will cut the real data file by 2013 Aug 20
Proc.data<-get.tags.data(File, end.date=as.POSIXct('2013-07-02', tz='GMT'))
Calibration.periods<-data.frame(
       calibration.start=NA,
       calibration.stop=as.POSIXct("2013-08-20"),
       lon=5.43, lat=52.93)
    #use c() also for the geographic coordinates, if you have more than one calibration location
       # (e. g., lon=c(5.43, 6.00), lat=c(52.93,52.94))
print(Calibration.periods)
# NB Below likelihood.correction is set to FALSE for fast run!
# Leave it as default TRUE for real examples
Calibration<-make.calibration(Proc.data, Calibration.periods, likelihood.correction=FALSE)
Grid<-make.grid(left=0, bottom=50, right=10, top=56,
  distance.from.land.allowed.to.use=c(-Inf, Inf),
  distance.from.land.allowed.to.stay=c(-Inf, Inf))
all.in<-make.prerun.object(Proc.data, Grid, start=c(5.43, 52.93),
                             Calibration=Calibration, threads=2)
# here we will run only 1e4 partilces for a very short track.
# One should use 1e6 particles for the full run.
Result<-run.particle.filter(all.in, threads=1,
           nParticles=1e3, known.last=TRUE,
           precision.sd=25, check.outliers=FALSE)
```

stationary.migration.summary

find potential stationary periods and estimates their location and movement schedule

Description

This function will find any sites where birds stayed longer than min.stay. Potential movement is detected by the minimum probability of movement prob.cutoff.

Usage

```
stationary.migration.summary(Result, prob.cutoff = 0.1, min.stay = 3)
```

Arguments

Result FLightR result object obtained from run.particle.filter

prob.cutoff Minimum probability that defines movement

min. stay Minimum duration of stationary period (in twilights)

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Value

list with stationary and movement statistics

Author(s)

Eldar Rakhimberdiev

Examples

```
File<-system.file("extdata", "Godwit_TAGS_format.csv", package = "FLightR")</pre>
# to run example fast we will cut the real data file by 2013 Aug 20
Proc.data<-get.tags.data(File, end.date=as.POSIXct('2013-06-25', tz='GMT'))
Calibration.periods<-data.frame(</pre>
       calibration.start=as.POSIXct(c(NA, "2014-05-05")),
       calibration.stop=as.POSIXct(c("2013-08-20", NA)),
       lon=5.43, lat=52.93)
     #use c() also for the geographic coordinates, if you have more than one calibration location
       # (e. g., lon=c(5.43, 6.00), lat=c(52.93,52.94))
# NB Below likelihood.correction is set to FALSE for fast run!
# Leave it as default TRUE for real examples
Calibration<-make.calibration(Proc.data, Calibration.periods, likelihood.correction=FALSE)
Grid<-make.grid(left=0, bottom=50, right=10, top=56,
  distance.from.land.allowed.to.use=c(-Inf, Inf),
  distance.from.land.allowed.to.stay=c(-Inf, Inf))
all.in<-make.prerun.object(Proc.data, Grid, start=c(5.43, 52.93),
                             Calibration=Calibration, threads=1)
# here we will run only 1e4 partilces for a very short track.
# One should use 1e6 particles for the full run.
Result<-run.particle.filter(all.in, threads=1,
           nParticles=1e3, known.last=TRUE,
           precision.sd=25, check.outliers=FALSE)
Summary<-stationary.migration.summary(Result, prob.cutoff=1)</pre>
# Use lower cut offs for real runs!
```

twGeos2TAGS

Function to write down twilights annotated in twGeos package data in so-called TAGS format

Description

this function converts combines twilights detected in twGeos with raw data and writes them down in TAGS format that can be easily read by get.tags.data

Usage

```
twGeos2TAGS(raw, twl, threshold, filename = NULL)
```

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Arguments

raw original data - dataframe with two columns first column must contain time and

second measured light levels

twl twilights object from preprocess.light function

threshold threshold value used for twilight definition in preprocess.light

filename if NULL data.frame in TAGS format will be returned otherwise .csv file in TAGS

format will be written

Details

TAGS format returned or written as .csv by this function is a dataframe with columns

datetime date and time in ISO 8601 format e.g. 2013-06-16T00:00:11.000Z

• light light value measured by tag

• twilight assigned by the software numeric indication of whether the record belongs to sunrise (1), sunset (2) or none of those (0)

• excluded indication of whether a twilight was excluded during manual inspection (logical, TRUE | FALSE)

• interp indication of whether the light value at twilight was interpolated (logical, TRUE | FALSE)

The fields excluded and interp may have values of TRUE only for twilight > 0.

Value

NULL if filename is provided or TAGS formatted dataframe.

Author(s)

Eldar Rakhimberdiev & Simeon Lisovski

See Also

BAStag2TAGS and GeoLight2TAGS

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